

Nonhydrostatic modeling on the sphere

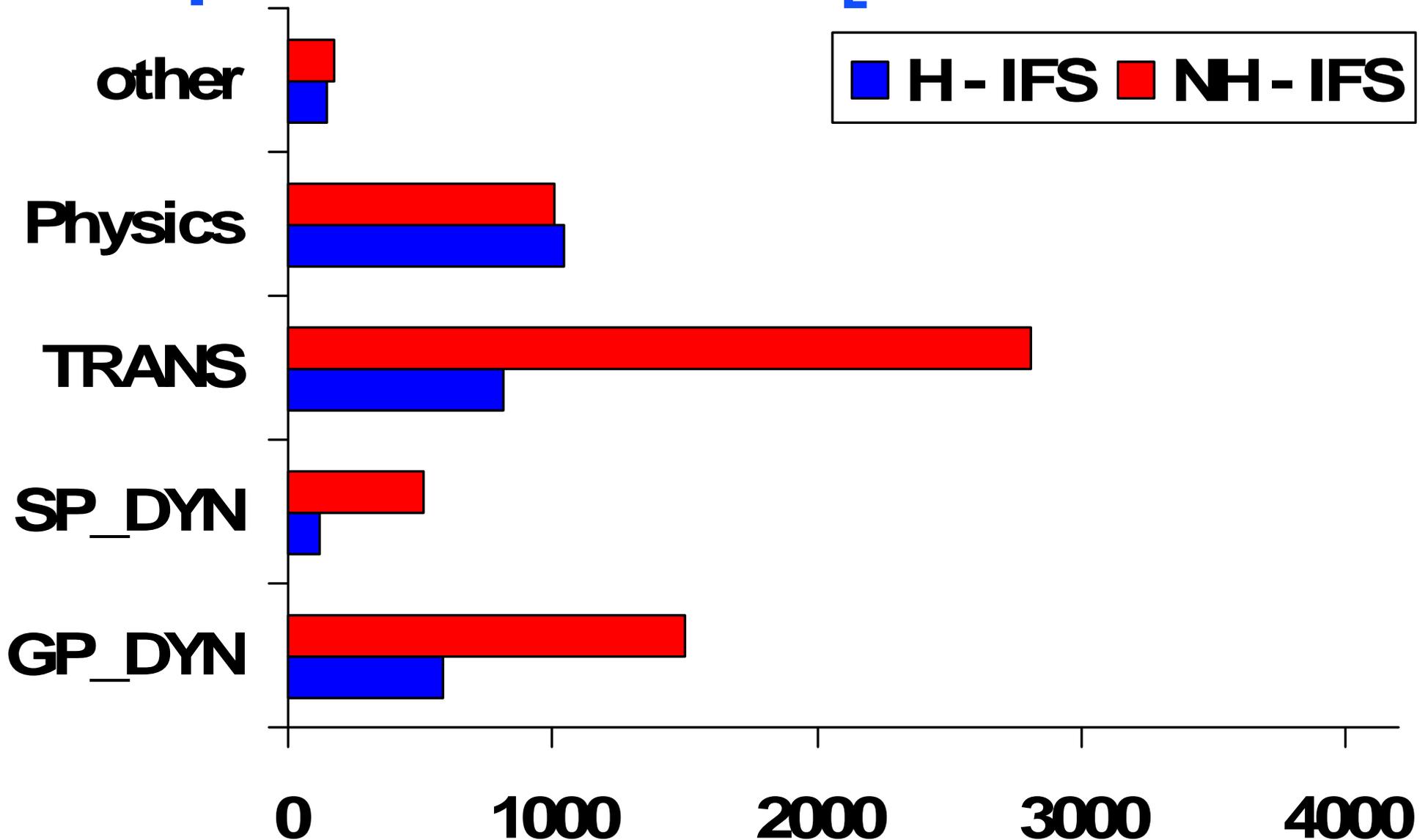
Nils Wedi

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Hamrud, George Mozdzyński

Outline

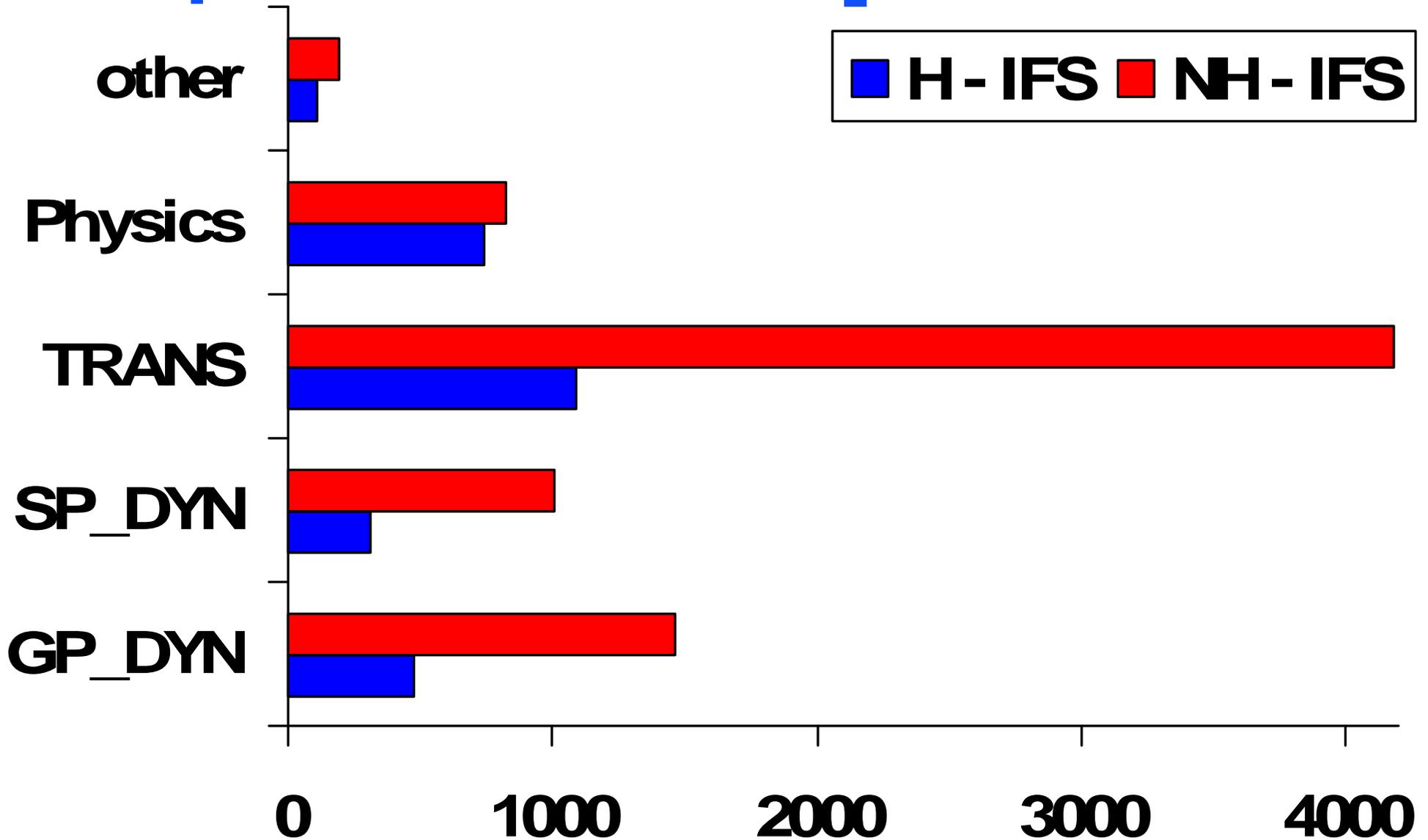
- ◆ (Ultra-)high resolution T3999 simulations highlight some areas of concern:
 - ◆ The spectral transform method
 - ◆ Cost of the NH dynamics
 - ◆ NH dynamics coupling to the physics

Computational Cost at T_L2047



Total cost increase NH – H 106 %

Computational Cost at T_L3999



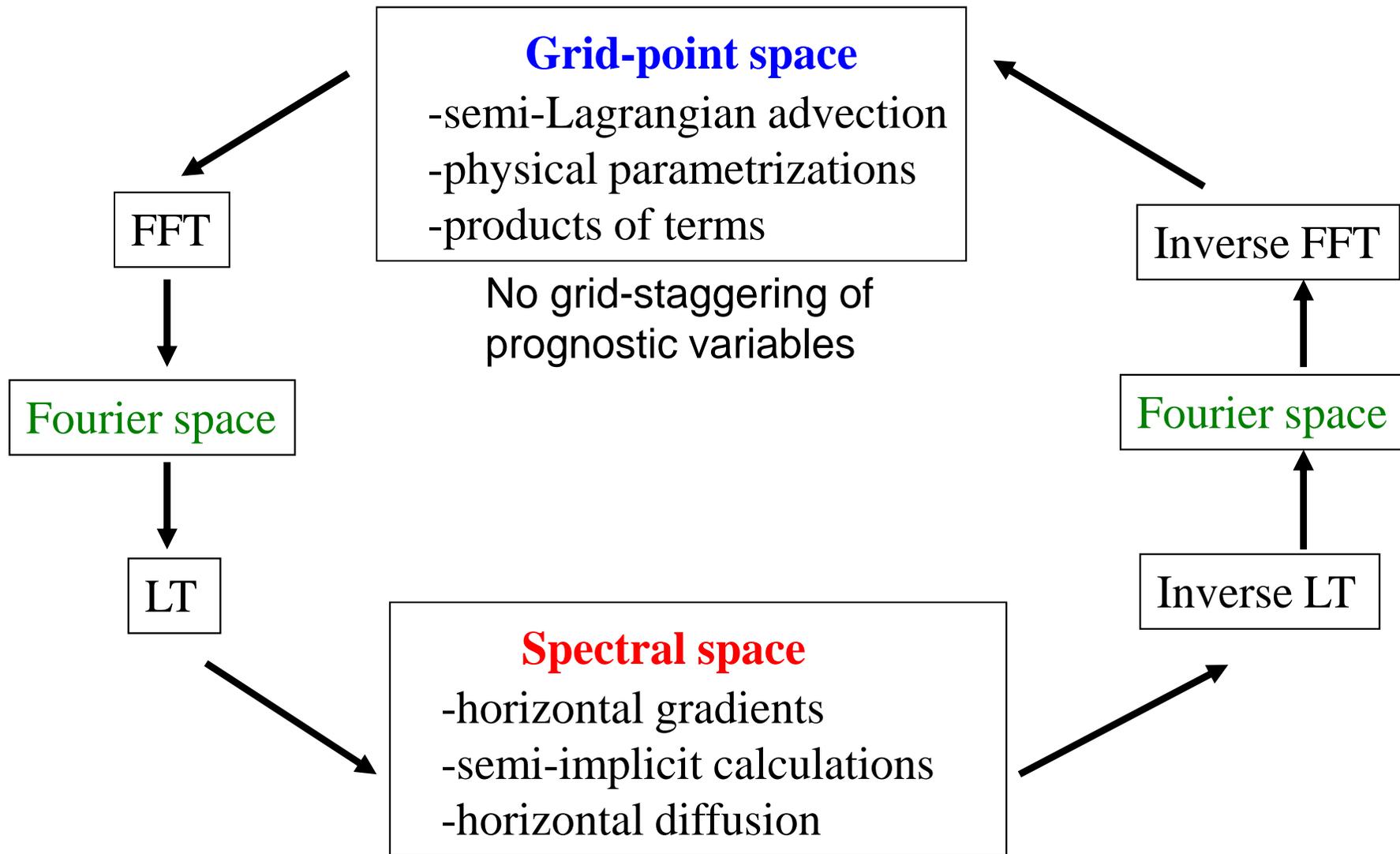
Total cost increase for 24h forecast: H 50min vs. NH 150min

Cost of spectral transform method

- ◆ The Fourier transform can be computed at a cost of $C*N*\log(N)$ where C is a small positive number and N is the cut-off wave number in the triangular truncation with the Fast Fourier Transform (FFT).
- ◆ Ordinary Legendre transform is $O(N^2)$ but can be combined with the fields/levels such that the arising matrix-matrix multiplies make use of the highly optimized BLAS routine DGEMM.
- ◆ But overall cost of transforms is $O(N^3)$ for both memory and CPU time requirements.
- ◆ On top of the computational cost there is also the cost of message passing associated with the “transpositions” but likely $O(N^2)$

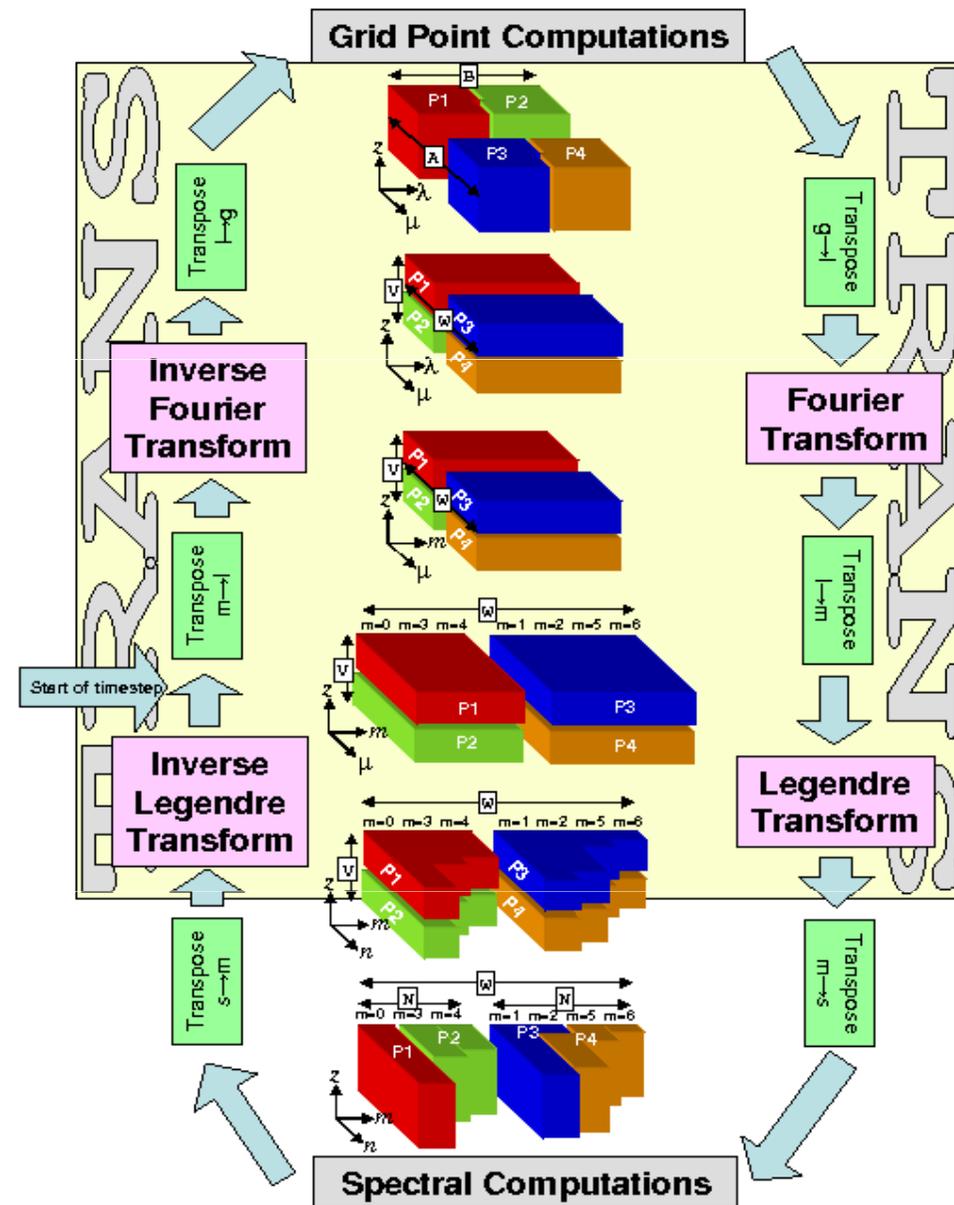
➔ **Desire for a fast Legendre transform where the cost is proportional to $C*N*\log(N)$
and thus overall cost proportional to $N^2*\log(N)$**

Schematic description of the **spectral transform method** in the **ECMWF IFS model**



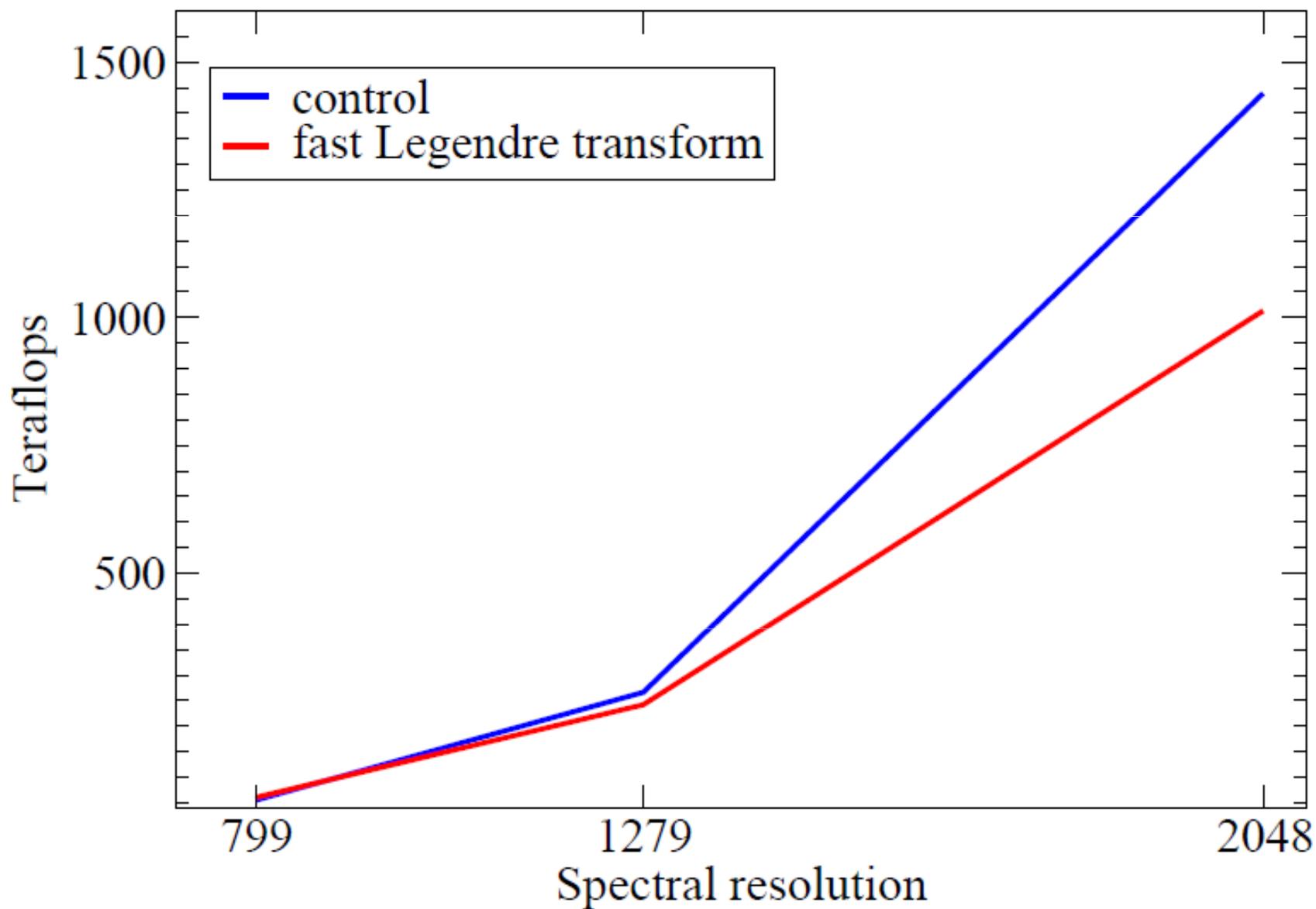
FFT: Fast Fourier Transform, LT: Legendre Transform

Transpositions within the spectral transforms

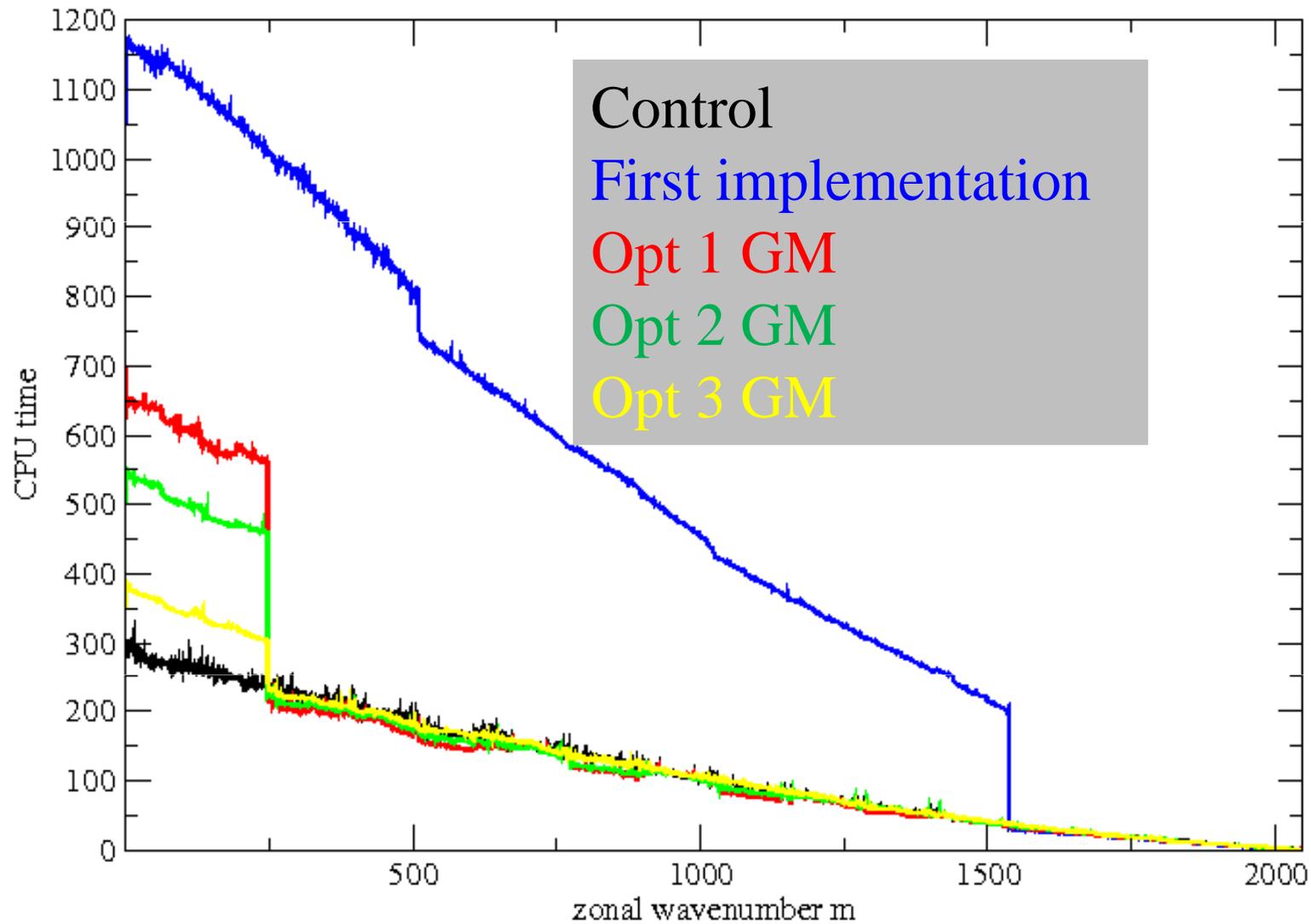


Total number of operations (24h forecast)

Inverse Legendre transform



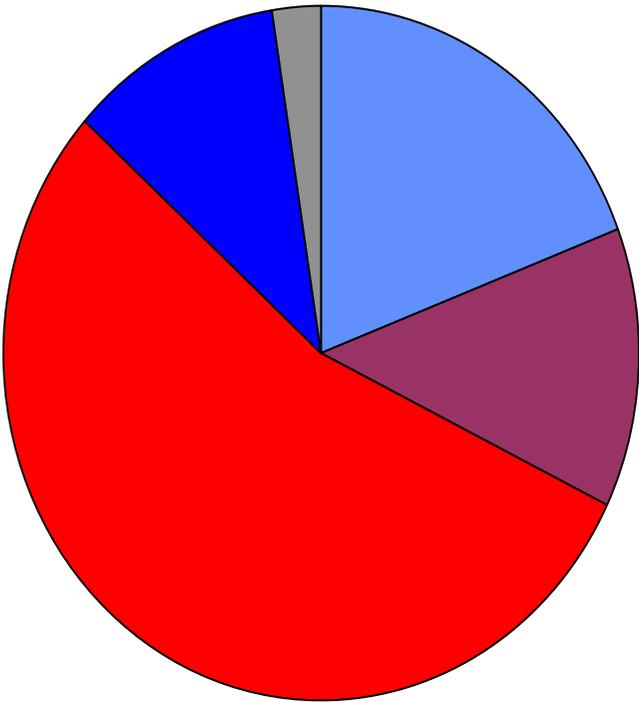
Timings for new Legendre transform



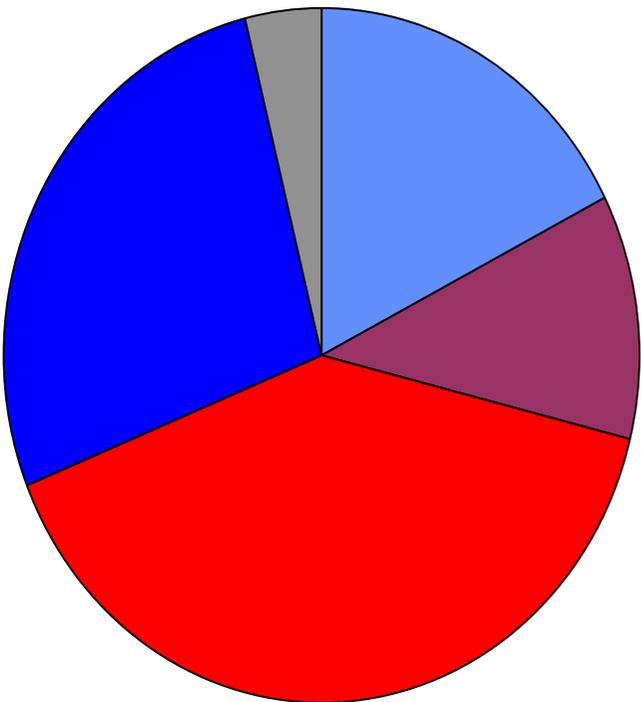
Accuracy of computation of the associated Legendre polynomials

- ◆ Increase of error due to recurrence formulae (Belousov, 1962)
- ◆ Recent changes to transform package went into cycle 35r3 that allow the computation of Legendre functions and Gaussian latitudes in double precision following ([Schwarztrauber, 2002](#)) and increased accuracy 10^{-13} instead of 10^{-12} .
- ◆ **Note:** the increased accuracy leads in the “*Courtier and Naughton* (1994) procedure for the reduced Gaussian grid” to slightly more points near the poles for all resolutions.
- ◆ **Note:** At resolutions $> T3999$ above procedure needs review!

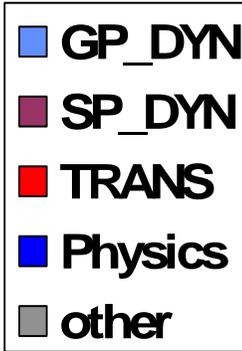
Computational Cost at T_L3999 hydrostatic vs. non-hydrostatic IFS



NH T_L3999



H T_L3999



The IFS NH equations

Two new prognostic variables in the nonhydrostatic formulation

$$Q \equiv \log(p/\pi)$$

‘Nonhydrostatic
pressure departure’

$$d \equiv -g(p/mRT)\partial w/\partial \eta \quad \text{‘vertical divergence’}$$

Define also: $\mathcal{D} \equiv d + \mathcal{X}$

With residual residual

$$\mathcal{X} \equiv (p/RTm)\nabla_{\eta}\Phi \cdot \partial \mathbf{v}_h/\partial \eta$$

Three-dimensional divergence writes

$$D_3 = \nabla_{\eta} \cdot \mathbf{v}_h + \mathcal{X} + d.$$

NH-IFS prognostic equations

$$\frac{d\mathbf{v}_h}{dt} = -\frac{RT}{p}\nabla_\eta p - \frac{1}{m}\frac{\partial p}{\partial\eta}\nabla_\eta\Phi - 2\Omega \times \mathbf{v}_h + P_v,$$

$$\frac{dD}{dt} = \frac{dd}{dt} + \frac{d\mathcal{X}}{dt} = -\frac{gp}{mRT}\frac{\partial P_w}{\partial\eta},$$

$$\frac{dT}{dt} = -\frac{RT}{c_v}D_3 + \frac{c_p}{c_v}P_T,$$

$$\frac{dQ}{dt} = -\frac{c_p}{c_v}D_3 - \frac{1}{\pi}\frac{d\pi}{dt} + \frac{c_p}{c_v\Gamma}P_T.$$

$$\frac{\partial\pi_s}{\partial t} = -\int_0^1 \nabla_\eta \cdot (m\mathbf{v}_h)d\eta,$$

‘Physics’

— “anelastic physics coupling”

Dynamics – Physics coupling

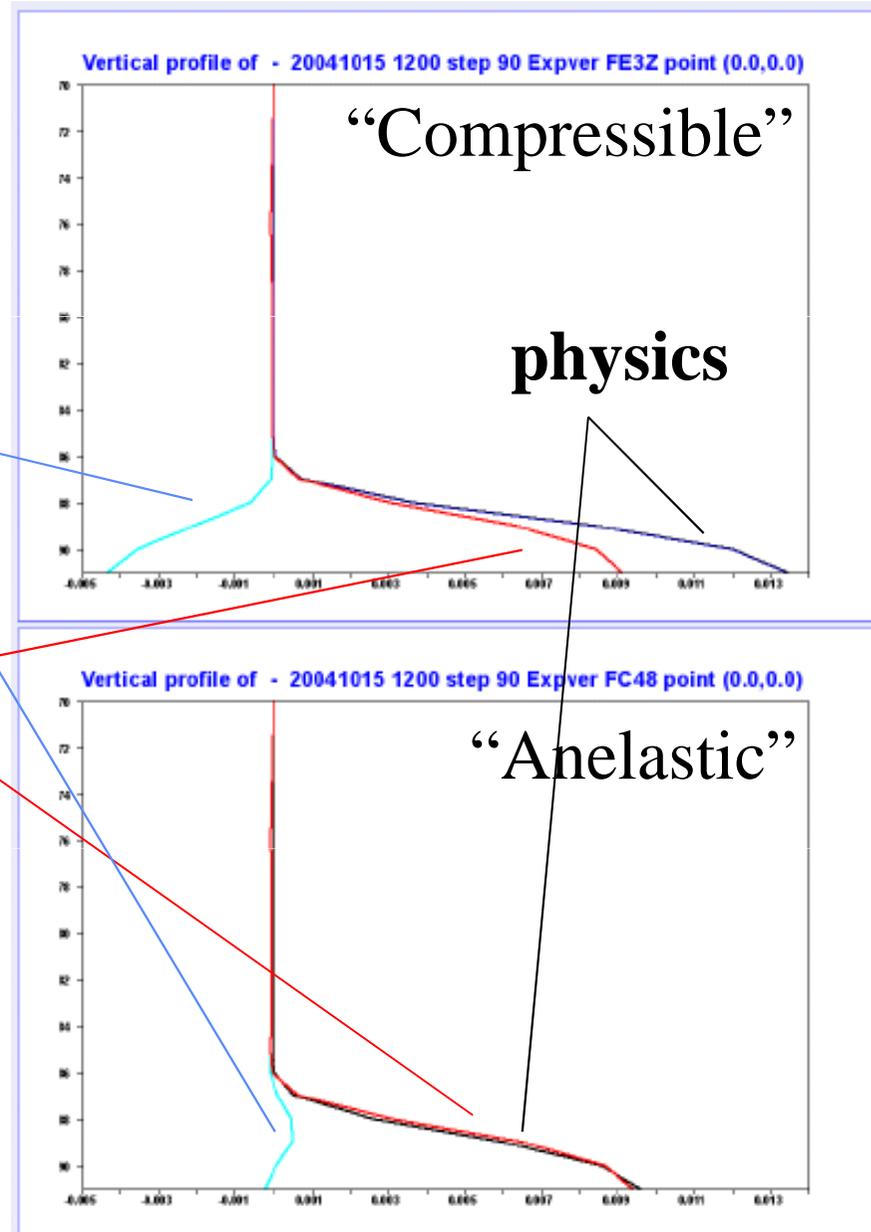
Sylvie Malardel

The case of constant heating near the surface with $dt=10s$

dynamics

total

Total temperature tendency after 15min is nearly identical !



Dynamics – Physics coupling

- ◆ (A) In the “anelastic coupling case” the nonhydrostatic pressure departure is instantaneously converted into volume change (D3) without the (“resolved”) computations of the dynamics.
 - ◆ (B) In the “compressible coupling case” the physics is allowed to change the non-hydrostatic pressure departure, but cannot change the mass distribution. The mass rearrangement can be done only in the dynamics (via advection).
- Preliminary results suggest that (A) is more stable with large time-steps and the need to retain fully compressible dynamics for cloud-resolving simulations is questionable !

Towards a unified hydrostatic-anelastic system

- ◆ Scientifically, the benefit of having a prognostic equation for non-hydrostatic pressure departure is unclear.
- ◆ The existence of two reference states with different requirements undesirable.
- ◆ The coupling to the physics is ambiguous.
- ◆ For stability reasons, the NH system requires at least one iteration, which essentially doubles the number of spectral transforms.
- ◆ Given the cost of the spectral transforms, any reduction in the number of prognostic variables will save costs.
- ◆ Split-explicit (vertically implicit) schemes essentially damp the pressure perturbation towards the anelastic solution.

Towards a unified hydrostatic-anelastic system

- ◆ There is a recent enhancement of the validity of anelastic models (based on scale analysis) to temperature perturbations of 30-50K which substantially extends the original work by Ogura and Philipps (*Klein et al, 2010*)

Unified system

(Arakawa and Konor, 2009)

here in the context of IFS

$$\rho_{qs} \equiv \frac{\pi}{R\tilde{T}}$$

$$\frac{\partial \pi}{\partial z} \equiv -\rho_{qs}g$$

$$\frac{1}{\rho_{qs}} \frac{d\rho_{qs}}{dt} = -\nabla \cdot \mathbf{v} + \cancel{\epsilon},$$

$$\epsilon = \frac{(\kappa - 1)}{1 + q^x} \frac{dq^x}{dt},$$

$$\tilde{T} \equiv T(1 + q^x)^{-R/c_p},$$

$$q^x = (p - \pi)/\pi$$

The linear system

$$\frac{\partial D'}{\partial t} = -\Delta \left[\gamma \tilde{T}' + RT^* q' + \frac{RT^*}{\pi_S^*} \pi'_S \right],$$

$$\frac{\partial w'}{\partial t} = g(\kappa + \partial^*) q',$$

$$\frac{\partial \tilde{T}'}{\partial t} = -\tau D',$$

$$\frac{\partial \phi'}{\partial t} = gw' - c_p \tau D' + RT^* B(\eta) \left(\frac{\pi_S^*}{\pi^*} \right) \nu D',$$

$$\frac{\partial \pi'_S}{\partial t} = -\pi_S^* \nu D',$$

Describes the small deviation from a hydrostatically balanced, isothermal, and resting reference state.

Unified system – the linear system

$$\frac{1}{H_*} \partial^* \left\{ \left[\Delta + \frac{1}{H_*^2} \partial^* (\partial^* + 1) \right] \frac{\partial^2}{\partial t^2} + N_*^2 \Delta \right\} w' = 0,$$

The structure equation is identical to the Lipps and Hemler system, or in other words, small perturbations from a hydrostatically balanced reference state show the *same behaviour in EULAG and the unified system* ! (and with Coriolis only small difference for baroclinic modes.)

At large scales the unified system collapses to the existing hydrostatic system.

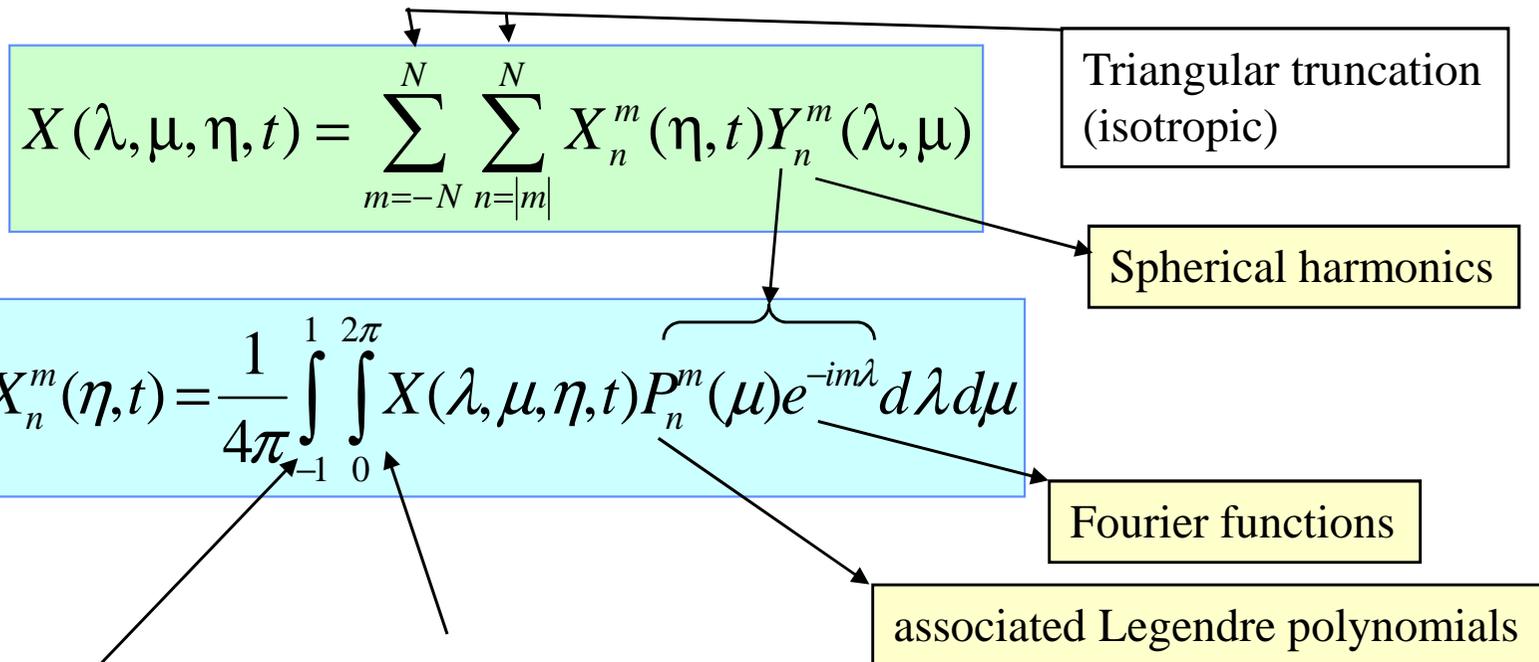
There may be a remaining concern for high altitude wave-breaking in the stratosphere (*U. Achatz + Klein et al, 2010*)

Executive Summary

- ◆ For the hydrostatic model not too many worries until 2015 !
- ◆ Nonhydrostatic IFS: Computational cost (almost 3 x at T_L3999) is a serious issue !
- ◆ Progress in the application of Fast Legendre Transforms.
- ◆ “anelastic” Dynamics-Physics coupling more stable with large time-steps and leading to the same result.
- ◆ Exploring possibilities towards a unified IFS hydrostatic-anelastic system (*Arakawa and Konor, 2009*).

Additional slides

Horizontal discretisation of variable X (e.g. temperature)



Legendre transform
 by Gaussian quadrature
 using $N_L \geq (2N+1)/2$
 “Gaussian” latitudes (linear grid)
 $((3N+1)/2$ if quadratic grid)
 “fast” algorithm desirable ...

FFT (fast Fourier transform)
 using
 $N_F \geq 2N+1$
 points (linear grid)
 $(3N+1$ if quadratic grid)
 “fast” algorithm available ...

