

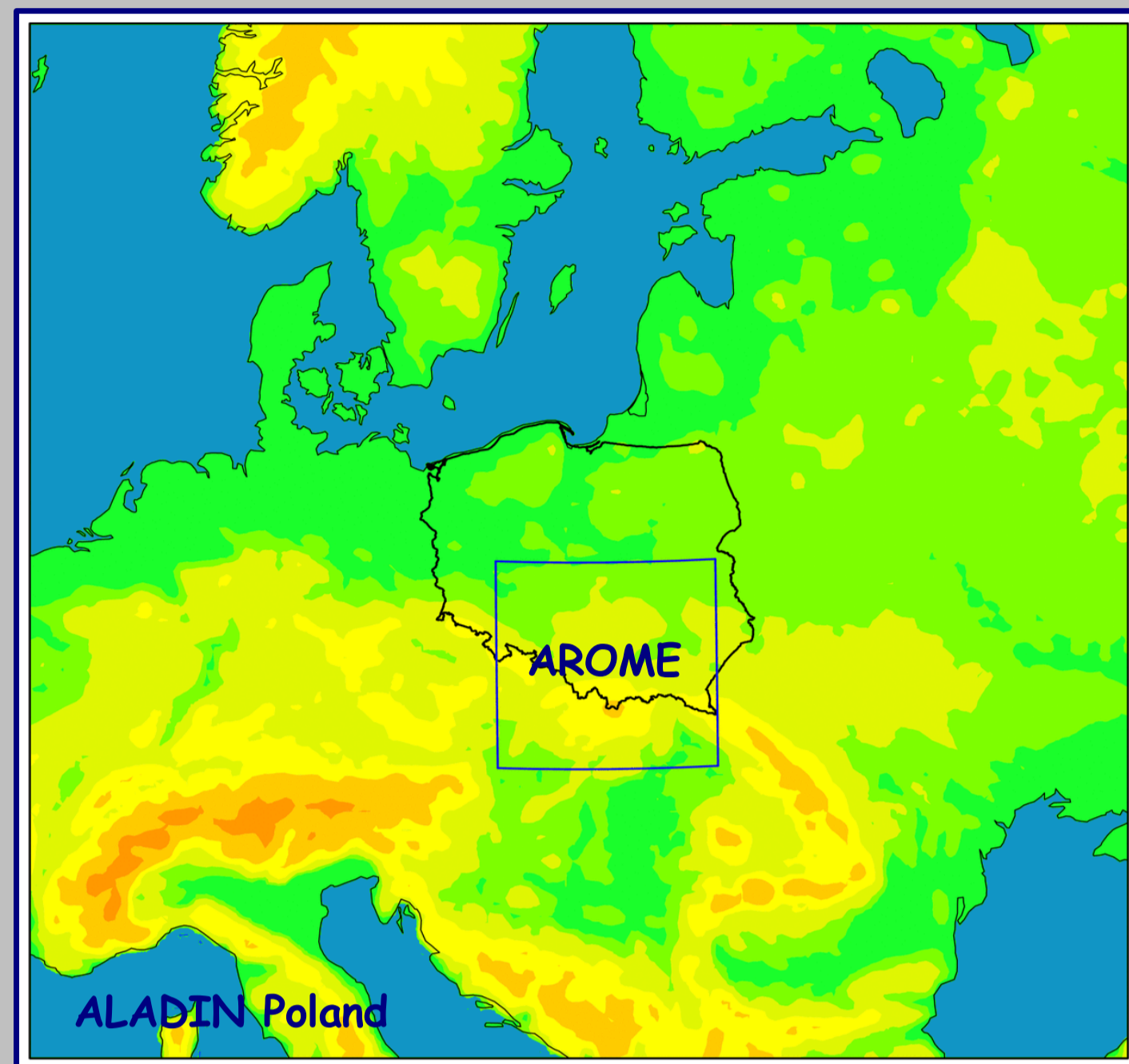
Małgorzata Szczęch-Gajewska, Marek Jerczyński, Jadwiga Woyciechowska, Marcin Kolonko  
Institute of Meteorology and Water Management Cracow Branch, Poland

## Computer characteristics

## Operational status

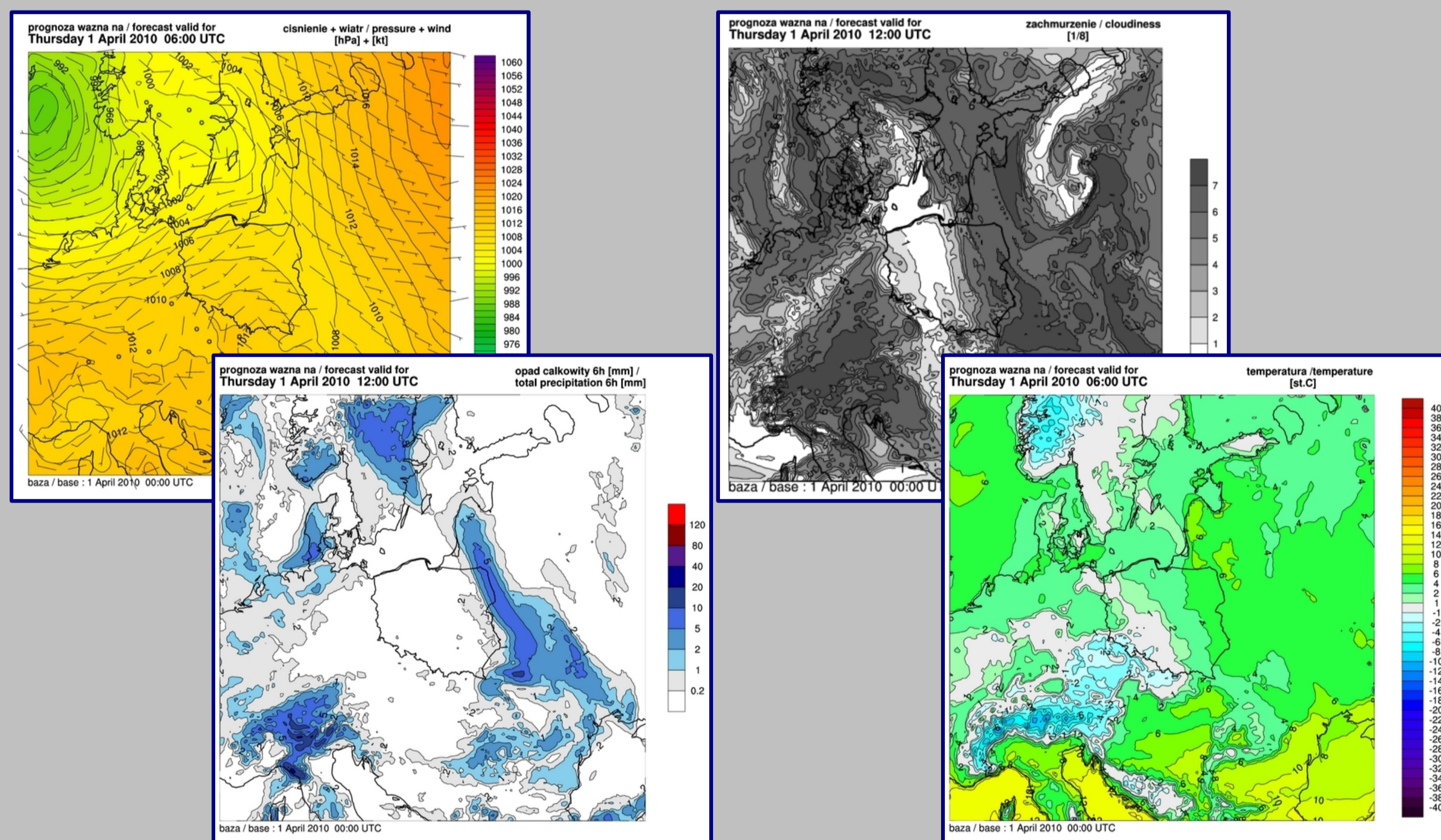
- 13.5km horizontal resolution
- 169x169 grid points
- 31 vertical model levels
- Lambert projection

- 2 runs per day (00 and 12UTC) with 54 hours forecast range
- LBC from ARPEGE (3h coupling frequency)
- on-line Fpos on model grid, every 3h – for operational database
- off-line Fpos on geographical regular grid, every 3h – for LEADS system



## Products

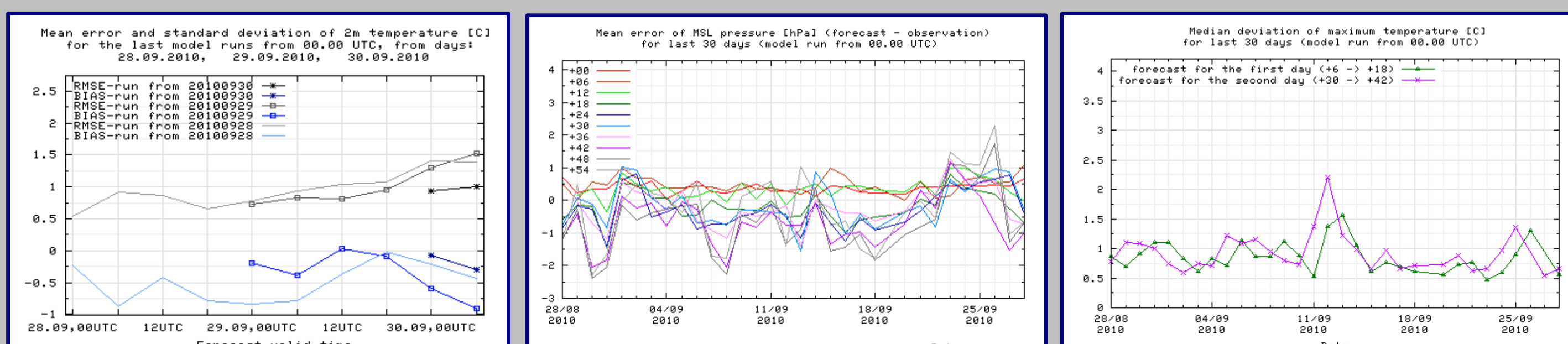
Lately we ran in test mode new system for graphical presentation of results based on NCAR Graphics/NCL tools. Examples of them you can see below.



## Verification

Observational values from each station are compared with model values at the grid point which is nearest to the given station. Verification is carried out for both runs of model (initial time 00.00 and 12.00 UTC respectively). The forecasts of following meteorological elements are evaluated:

- MSL pressure,
- air temperature at 2 m AGL,
- wind speed at 10 m AGL,
- wind direction at 10 m AGL,
- relative humidity at 2 m AGL,
- air maximum temperature at 2 m AGL,
- air minimum temperature at 2 m AGL,
- accumulated precipitation,
- cloud cover.

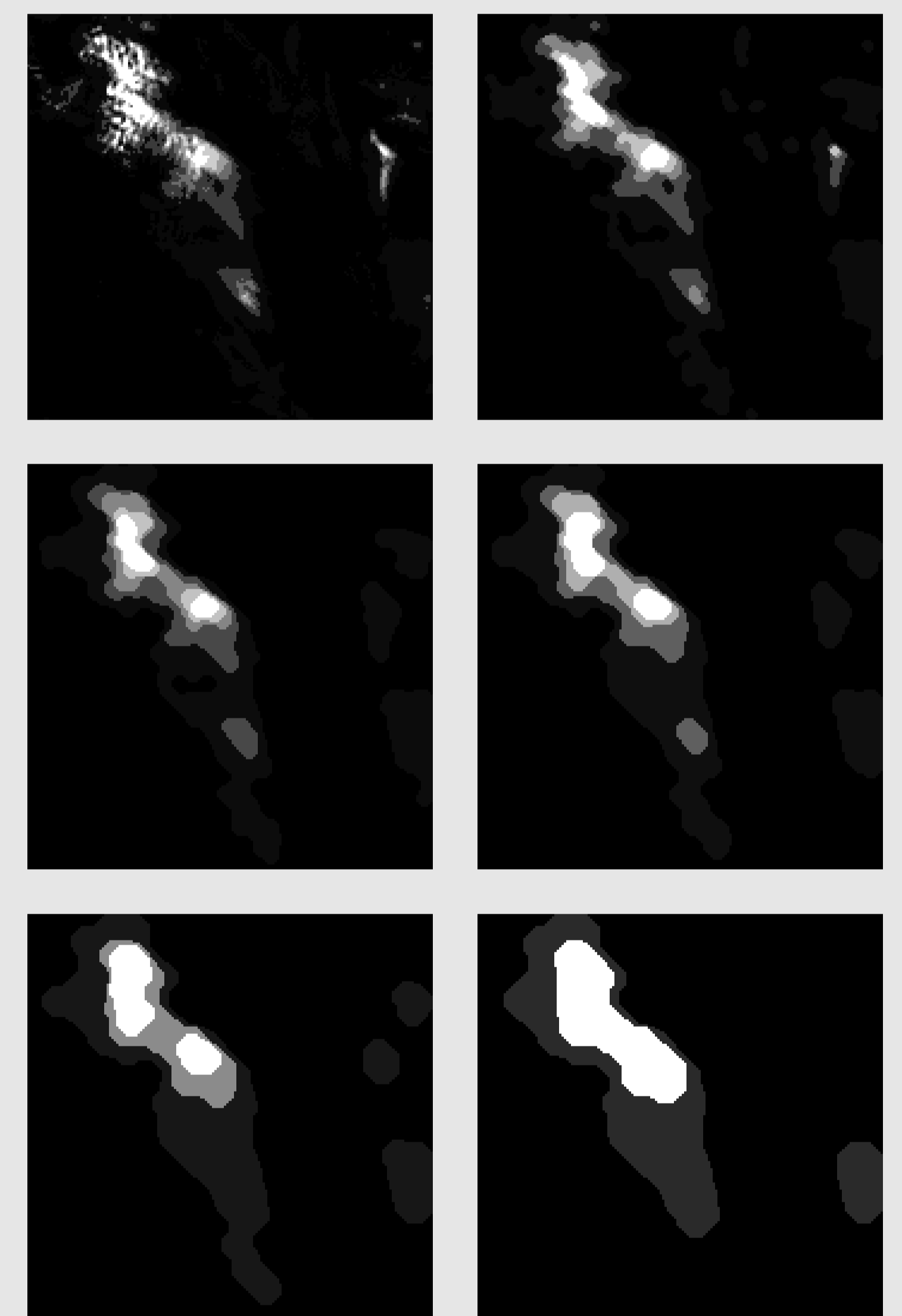
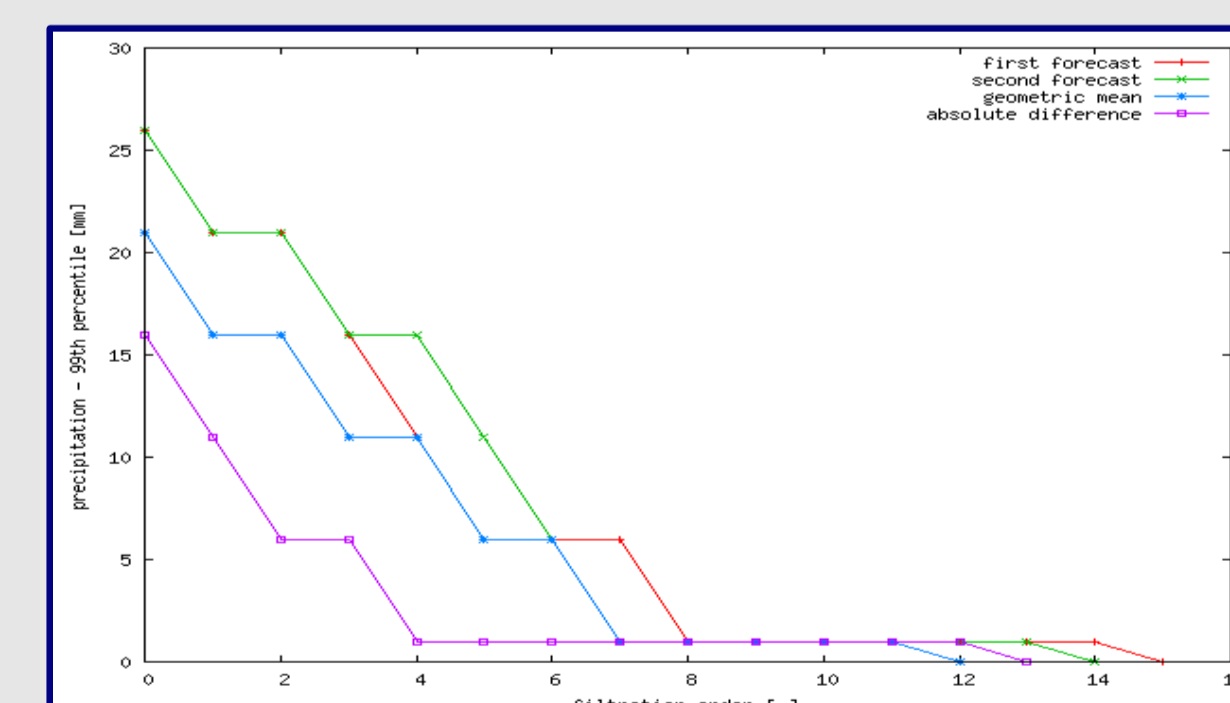
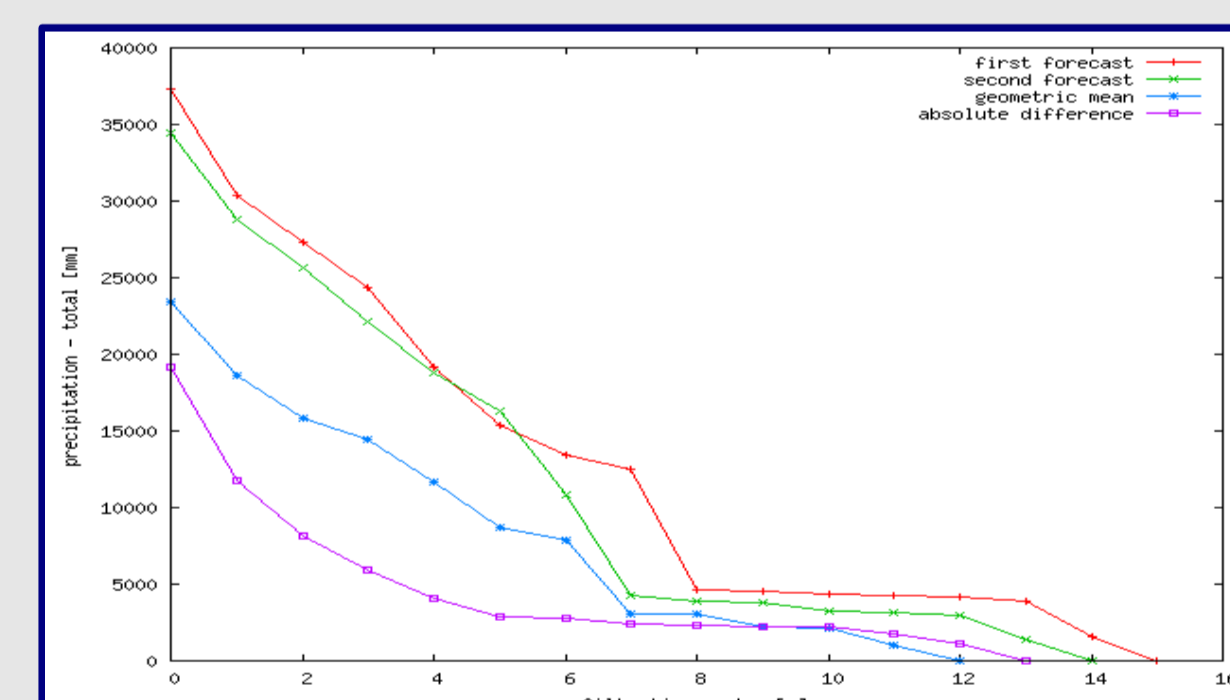
[illegible]

## Research activities

## AROME - preliminary tests

## 2-D ICWM Filters

At right there are examples of precipitation field filtration - 2 - D ICWM filter with two-parameter field quantization is applied. Attached images are normalized. It can be noticed that precipitation area preserves its boundaries really well.



At left there are examples of scale-by-scale comparison of two precipitation forecasts. Simple statistics are applied to filtered fields and some their derivatives.

## Fuzzy Methods

**Upscaling** matches neighborhood of observations and the neighborhood of forecast. Useful forecast in this case resembles the observations when averaged to coarser scales.

**Minimum coverage** method matches also both neighborhoods (of observation and of forecast) and the forecast is useful when predicts the event over a minimum fraction of the region of interest.

**Multi-event contingency table** compares single observation with the neighborhood of forecast. Useful forecast predicts at least one event close to an observed event.

**Fuzzy logic** method matches also both neighborhoods (of observation and of forecast) and the forecast is useful when is more correct than incorrect over the region of interest.

FAR fuzzy logic									cum 24h									
165km	0.28	0.33	0.42	0.52	0.64	0.84	0.96	0.98	NaN									
85km	0.33	0.38	0.46	0.55	0.65	0.83	0.94	0.98	0.99									
45km	0.43	0.47	0.53	0.58	0.66	0.81	0.92	0.97	0.99									
25km	0.43	0.46	0.53	0.58	0.67	0.82	0.92	0.97	0.99									
10km	0.43	0.46	0.53	0.58	0.66	0.81	0.91	0.97	0.99									
	0.1	0.2	0.5	1.0	2.0	5.0	10.0	20.0	50.0									

FAR fuzzy logic									cum 24h									
165km	0.26	0.3	0.41	0.51	0.64	0.83	0.96	0.98	NaN									
85km	0.32	0.37	0.45	0.54	0.65	0.82	0.94	0.98	NaN									
45km	0.41	0.45	0.52	0.57	0.66	0.81	0.92	0.97	0.99									
25km	0.41	0.45	0.52	0.57	0.66	0.81	0.92	0.97	0.99									
10km	0.41	0.44	0.52	0.57	0.65	0.81	0.91	0.97	0.99									
	0.1	0.2	0.5	1.0	2.0	5.0	10.0	20.0	50.0									

ALADIN  
AROME  
The example of results for the precipitation thresholds [in the units of mm / 24 hours]