

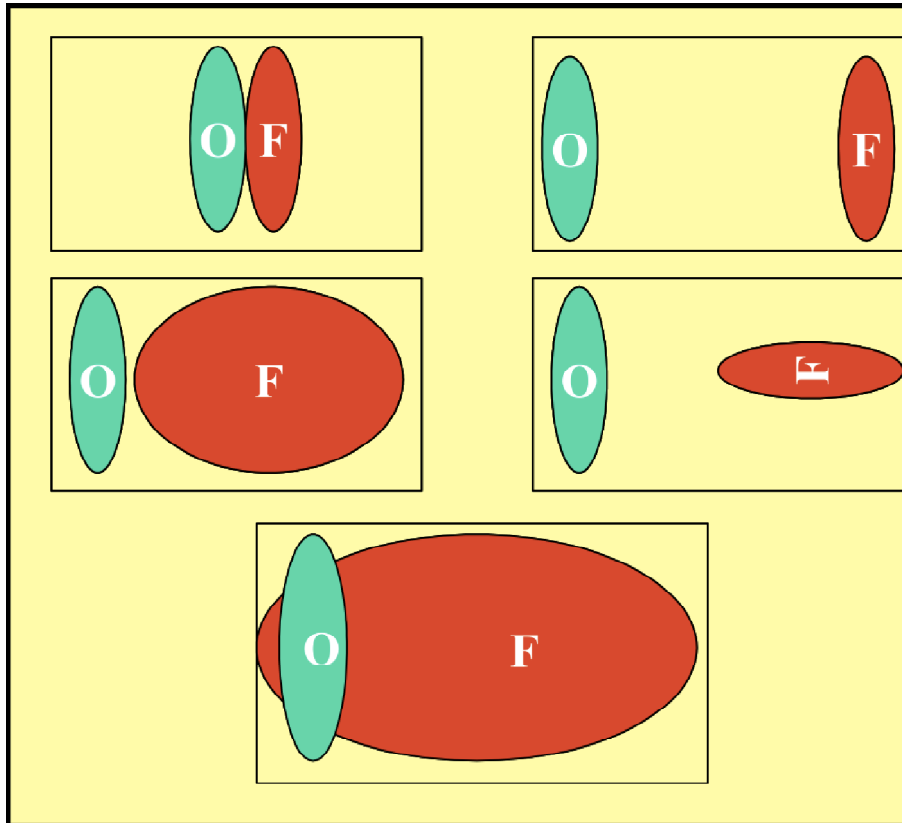
# Demonstrating a strategy for verifying km-scale NWP forecasts at observing sites

Marion Mittermaier

# Background

- **Traditional metrics can be misleading** → trust in objective results undermined, especially for testing model changes.
- **Representativeness** of observations and model grid values → implications for highly localised events.
- **Lack of predictability and rapid error growth** at km-scale → impact on perceived skill.
- **Difference between grid scale ( $\Delta x$ ) and model resolution ( $y * \Delta x$ , typically  $y \geq 4$ )** → now even more reason that km-scale model forecasts must be treated differently (probabilistically) for product generation and verification.

# The double penalty



Closeness not rewarded

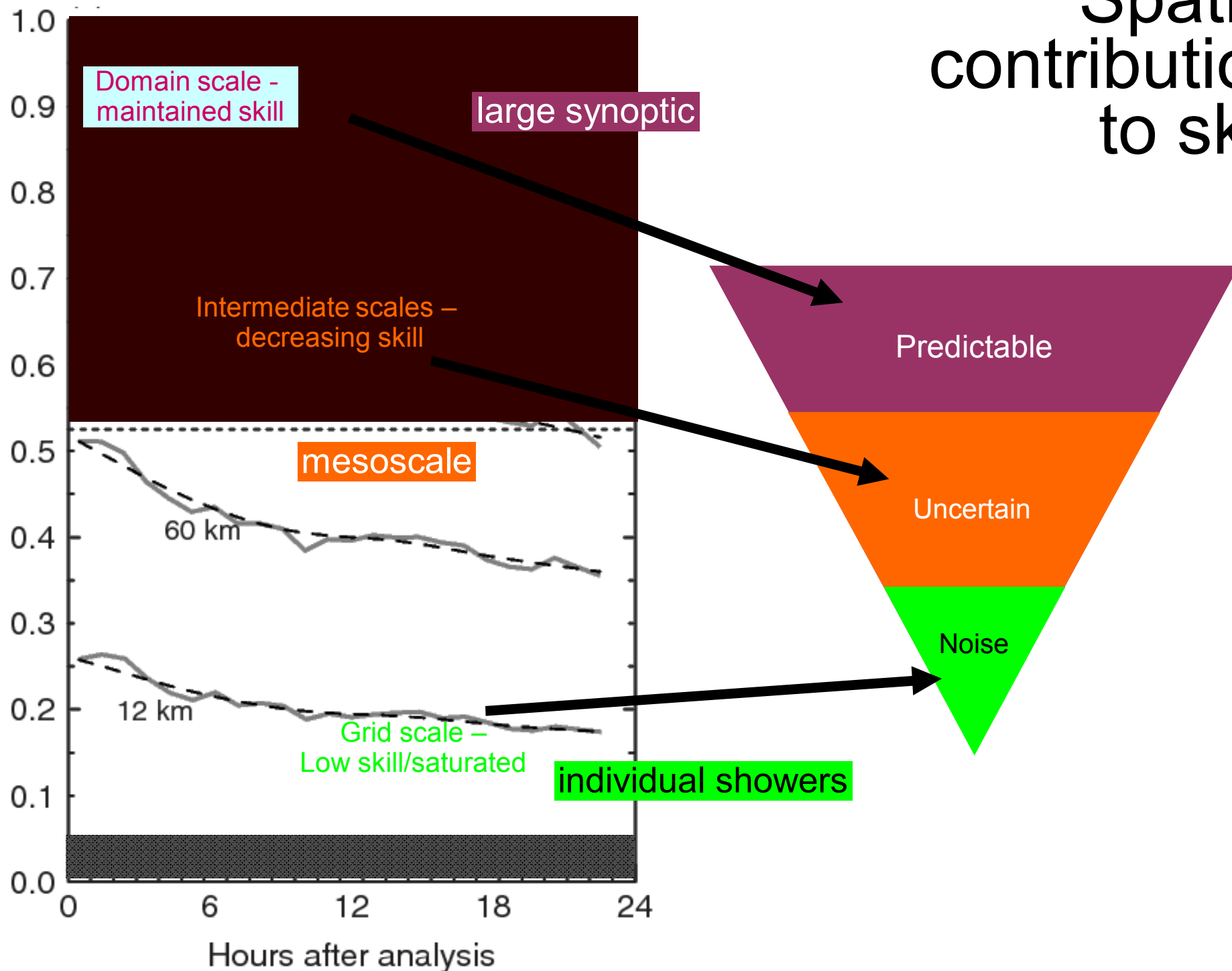
Detail is penalised  
unless exactly correct

- higher resolution is more  
detailed!

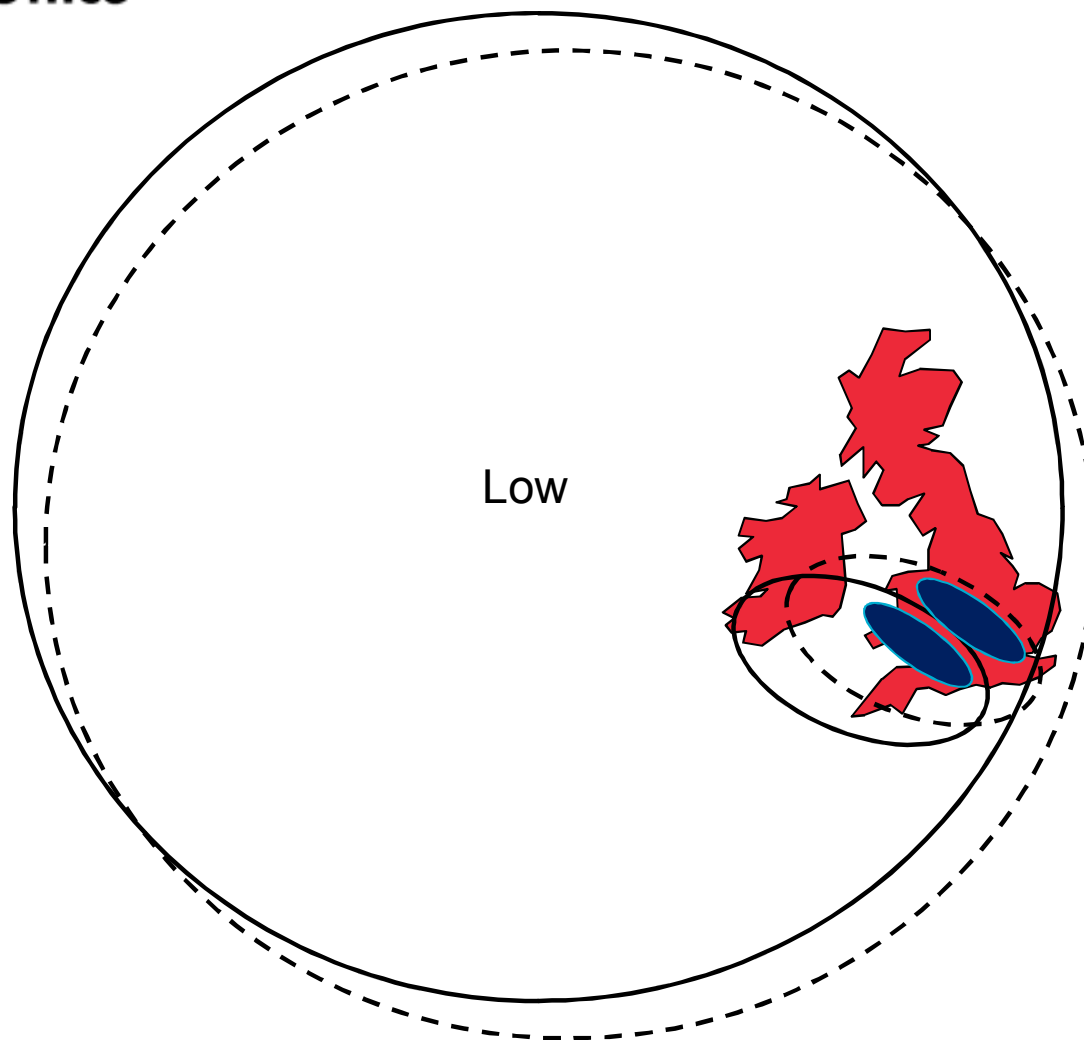
CSI = 0 for first 4;  
CSI > 0 for the 5th

$$CSI = \frac{hits}{hits + false\ alarms + misses}$$

# Spatial contribution to skill



# Small uncertainty at large scales = large uncertainty at small scales



Justifies the use of a  
downscaling ensemble  
(MOGREPS-UK)

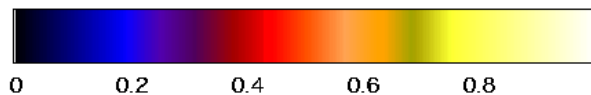
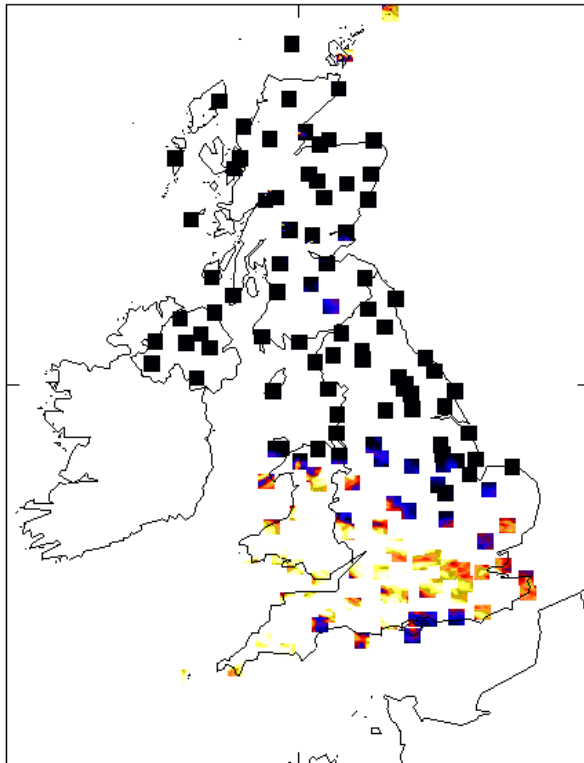
Link to larger scale:  
Russell *et al.* 2008  
Hanley *et al.* 2011, 2012

5% error at 1000 km = 100% error at 50 km

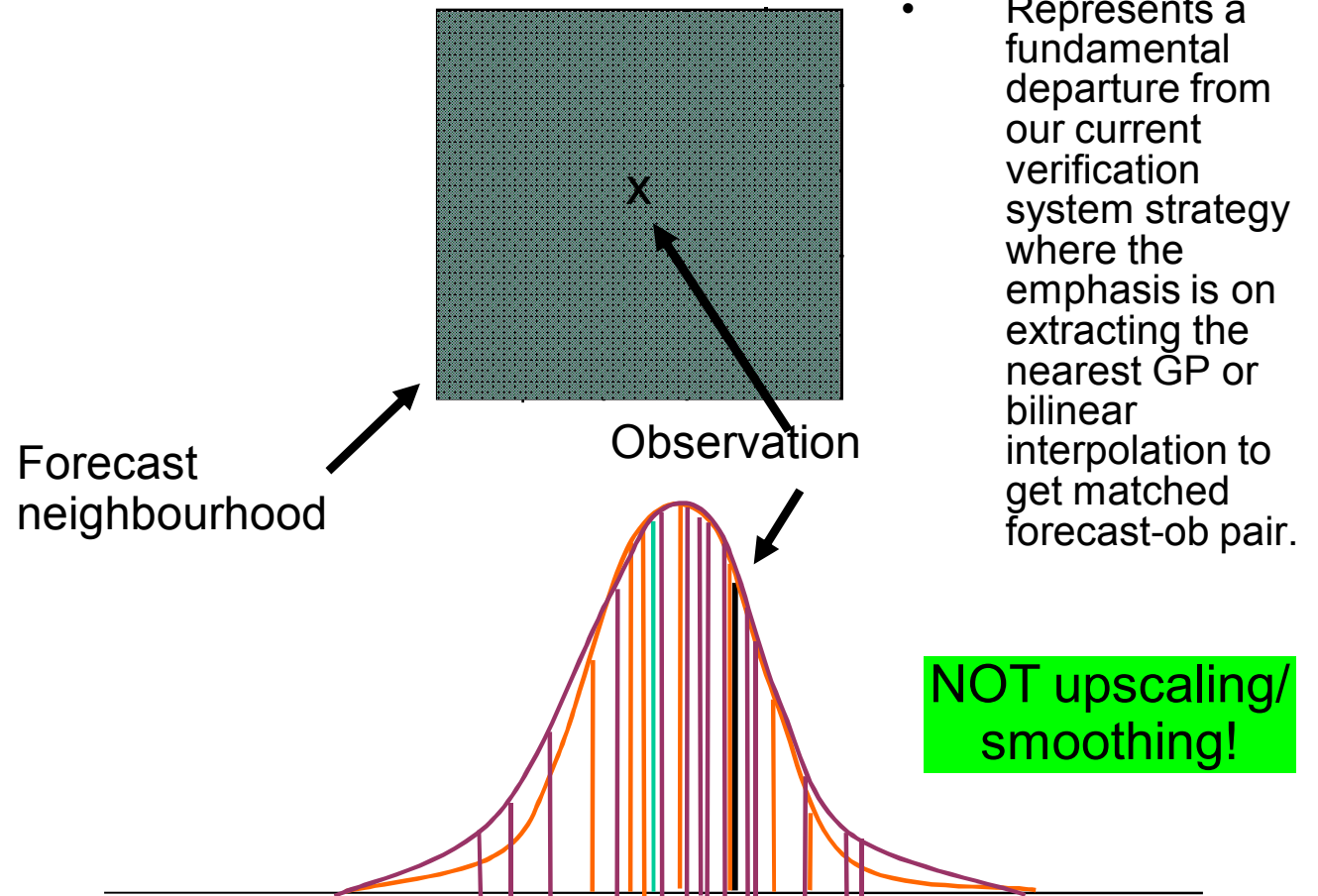
# Spatial sampling

17 x 17

AAABO Atmos total cloud amount max/random overlap  
At 03Z on 1/ 5/2011, from 03Z on 30/ 4/2011



Make use of spatial verification methods which compare single observations to a forecast neighbourhood around the observation location. → SO-NF

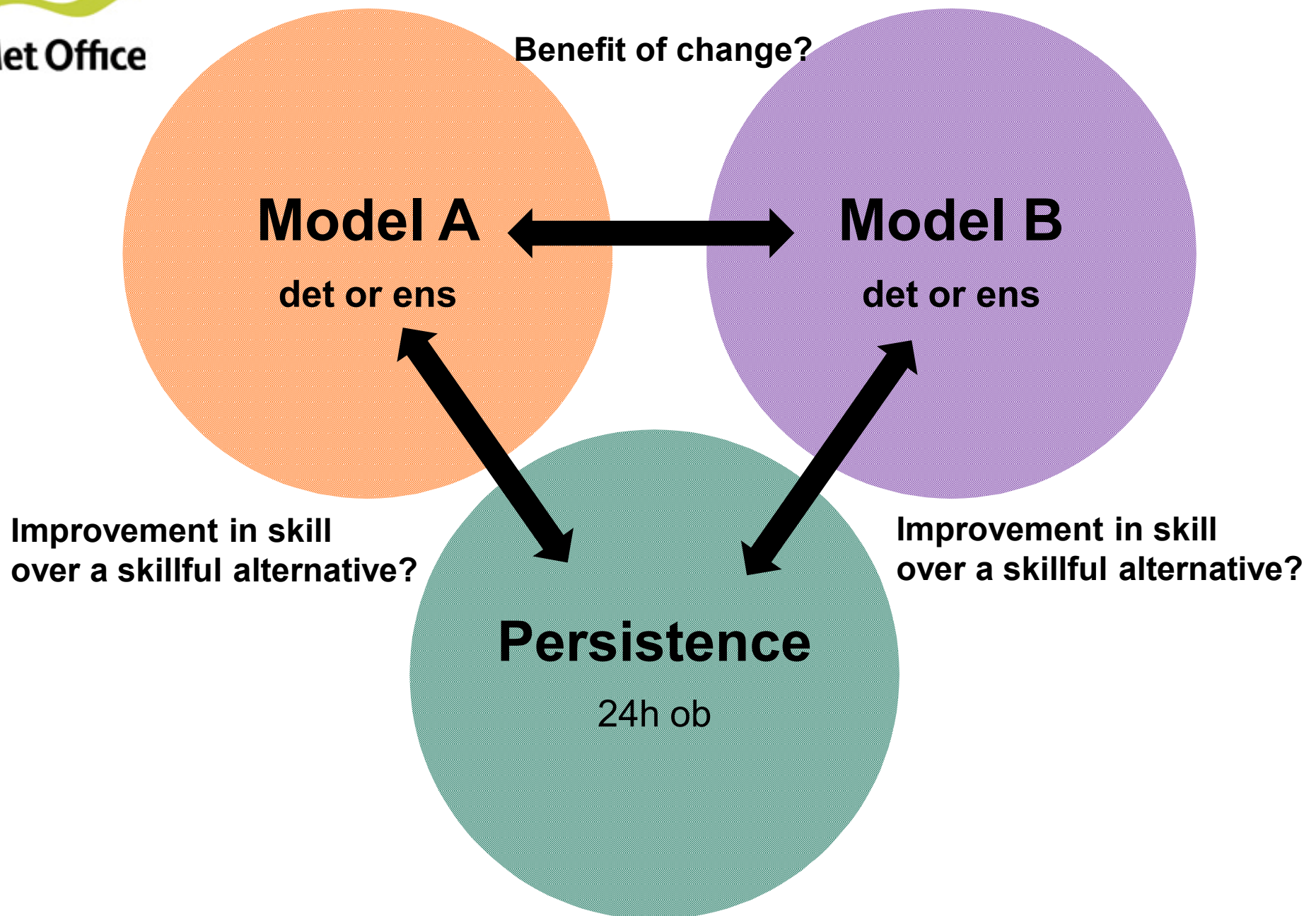


Represents a fundamental departure from our current verification system strategy where the emphasis is on extracting the nearest GP or bilinear interpolation to get matched forecast-ob pair.

Only ~130 1.5 km grid points in >500 000 domain used to assess entire forecast!



# Relative framework



# Framework outline

@ grid scale

- Use **standard synoptic observations** and a **range of neighbourhood sizes**
- Use **24h persisted observations** as reference
- The method needs to be able to compare:
  - Deterministic vs deterministic (different resolutions, and test vs control of the same resolution)
  - Deterministic vs EPS
  - EPS vs EPS
- Test whether differences are **statistically significant** (Wilcoxon) ["s" denotes significant at 5%]
- Grid scale calculated for reference → NOT main focus.

Variable	Old	New
Temp	RMSESS →	MAE
Vector wind (wind speed)	RMSVESS →	MAE
Cloud cover	ETS →	PC
CBH	ETS →	PC
Visibility	ETS →	PC
1h precip	ETS →	PC

RMS(V)ESS = Root Mean Square (Vector) Error Skill Score  
 ETS = Equitable Threat Score  
 BSS = Brier Skill Score  
 RPSS = Ranked Probability Skill Score  
 CRPSS = Continuous Ranked Probability Skill Score  
 MAE = Mean Absolute Error  
 PC = Proportion Correct



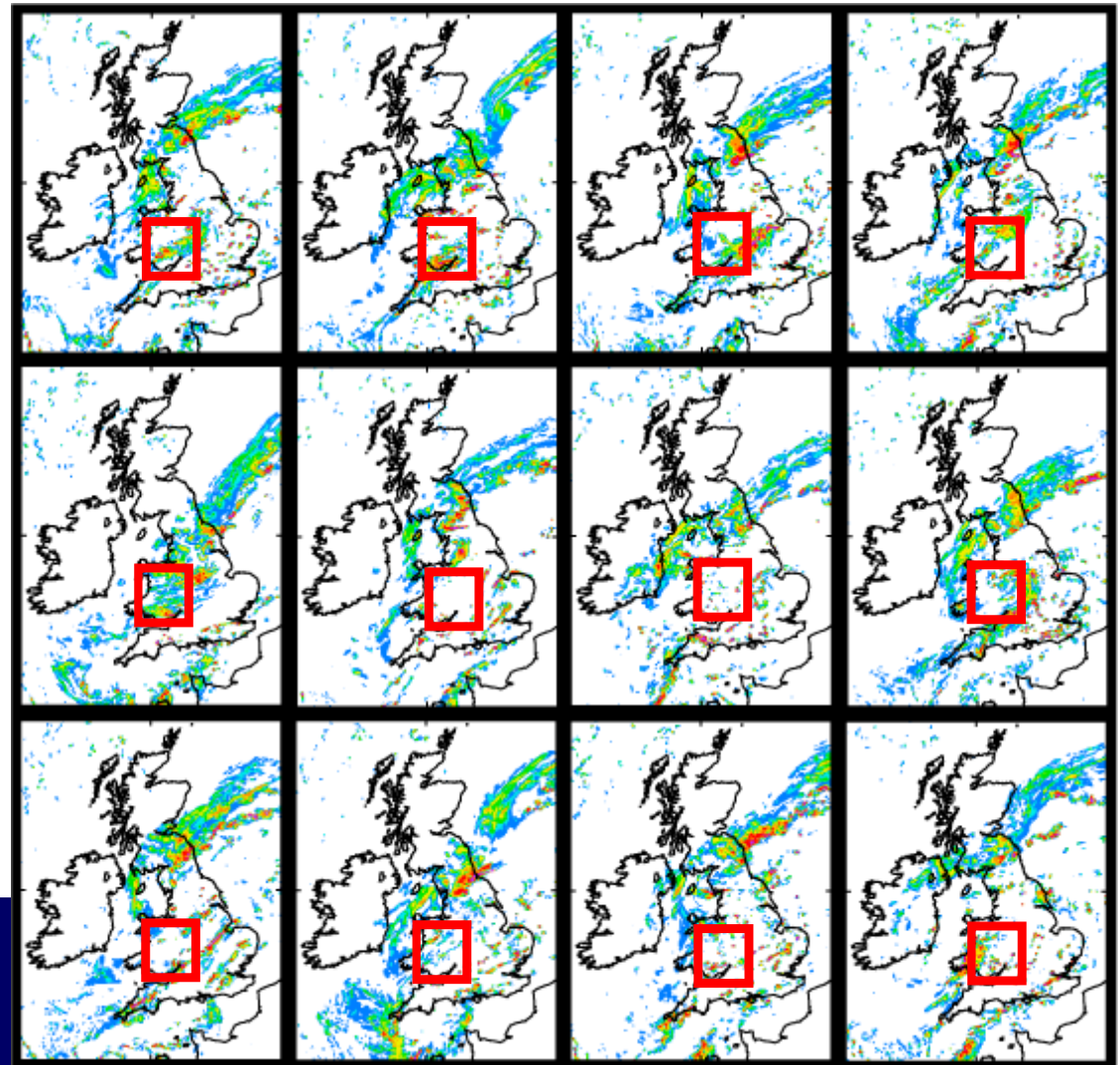


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# Approach

- Deterministic forecast **with/without** neighbourhood
- or
- Ensemble members **with/without** neighbourhoods

2.2 km MOGREPS-UK ensemble



## Comparisons:

1 GP with 12 single ensemble GPs

or

9 GP with  $12 * 9$  ensemble GPs → enhanced sampling



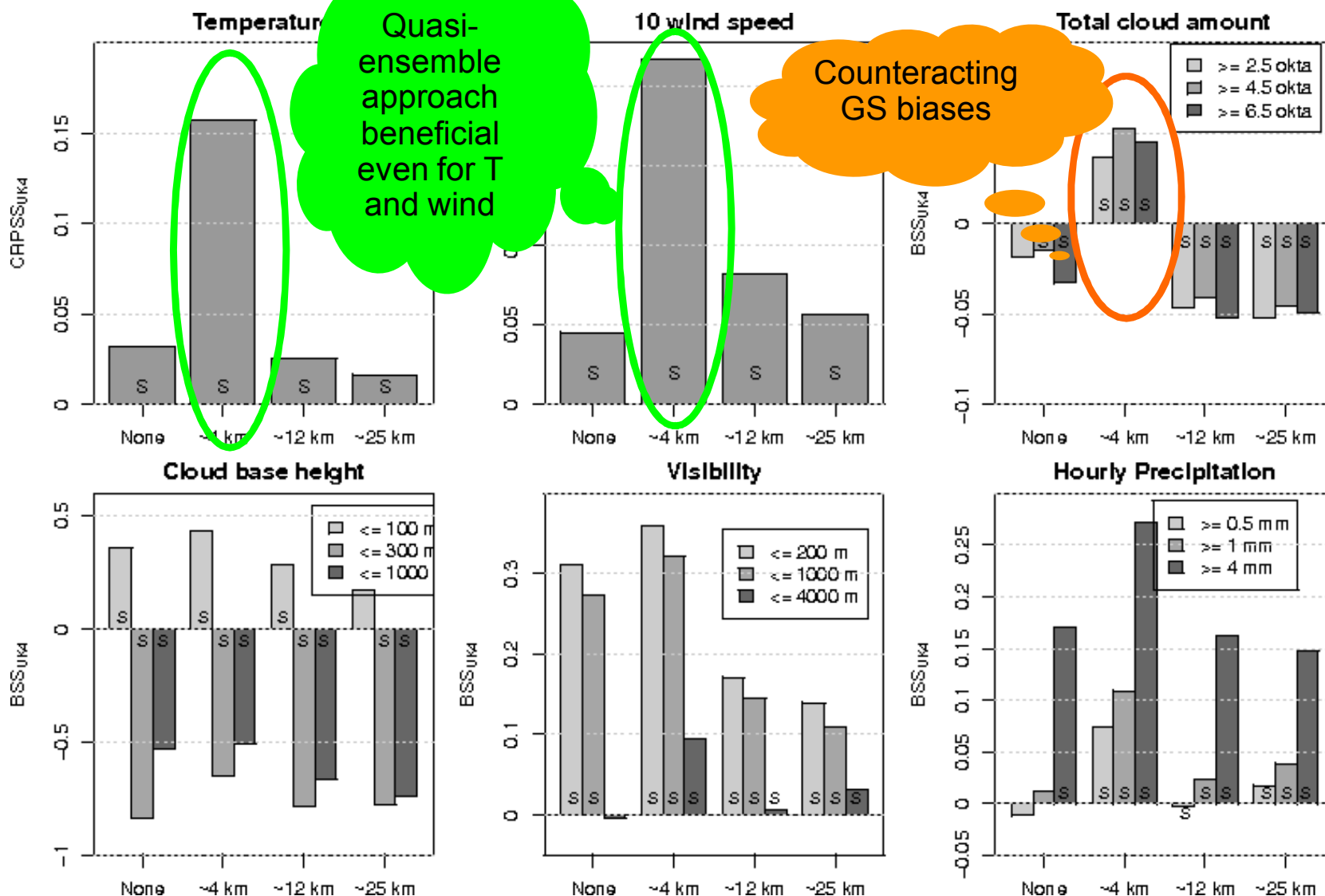
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# Three scenarios ...



# Deterministic vs deterministic (different resolution)

+ve = UKV test better than UK4  
“none” = 1 nearest GP UKV vs 1 nearest GP UK4



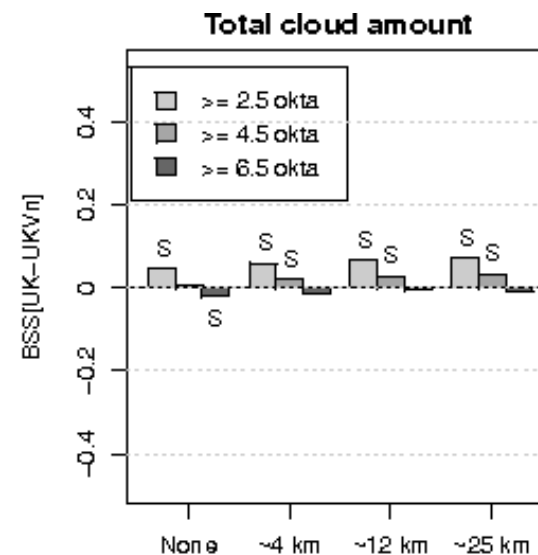
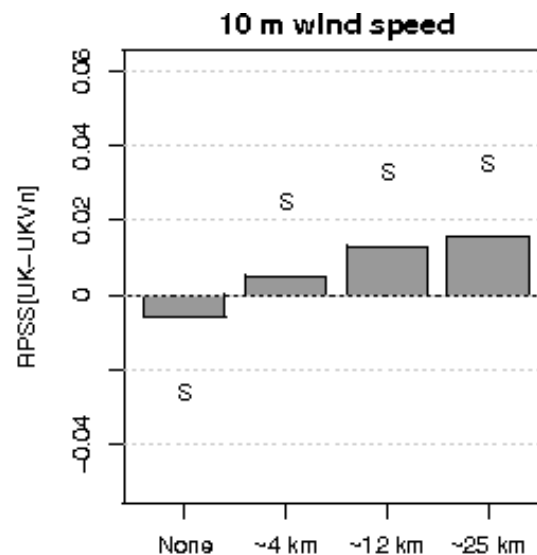
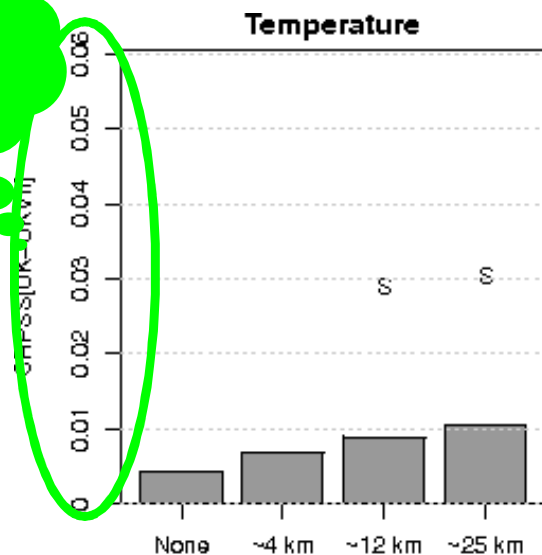


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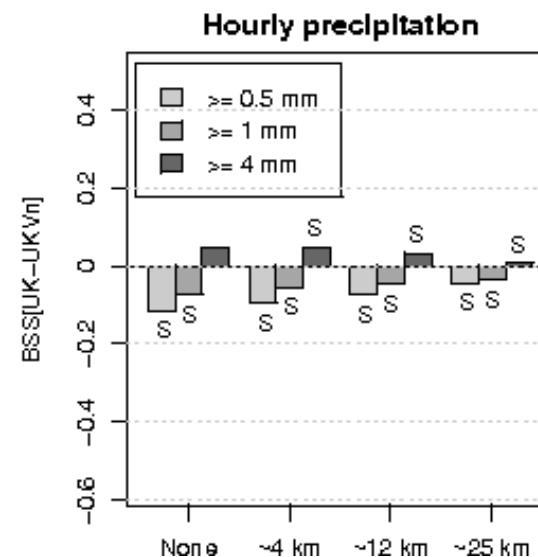
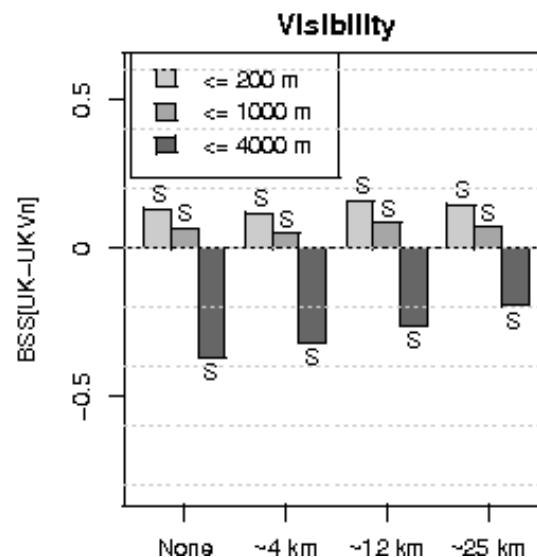
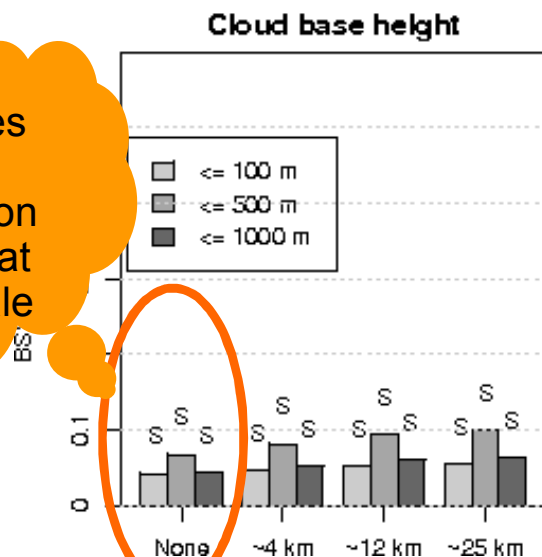
# Deterministic test vs control (model trialling)

+ve = UKV test better than control  
 “none” = 1 nearest GP UKV vs 1 nearest GP UKV

Detect  
small  
changes



Reduces  
to  
proportion  
correct at  
grid-scale

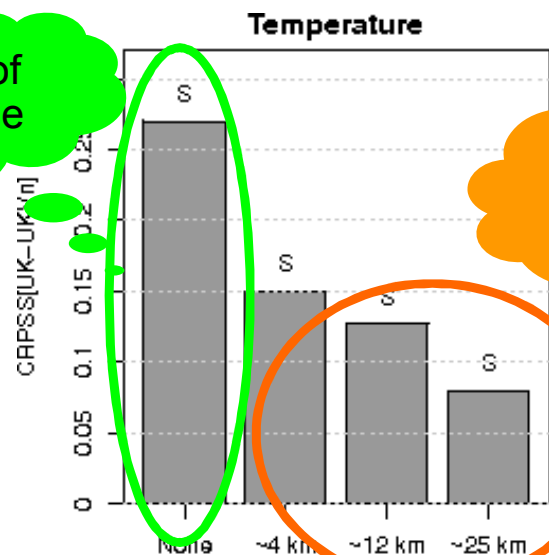




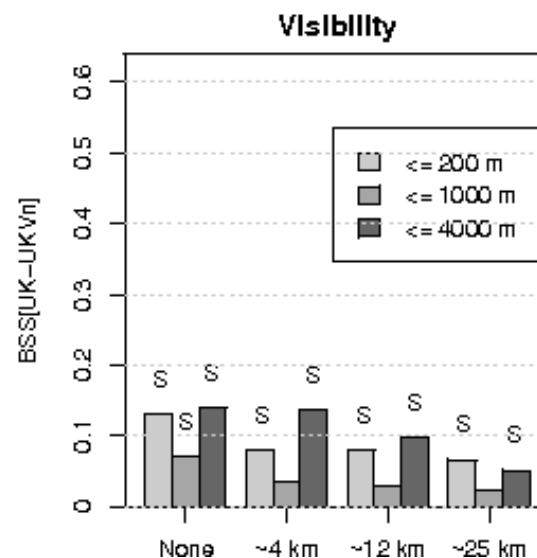
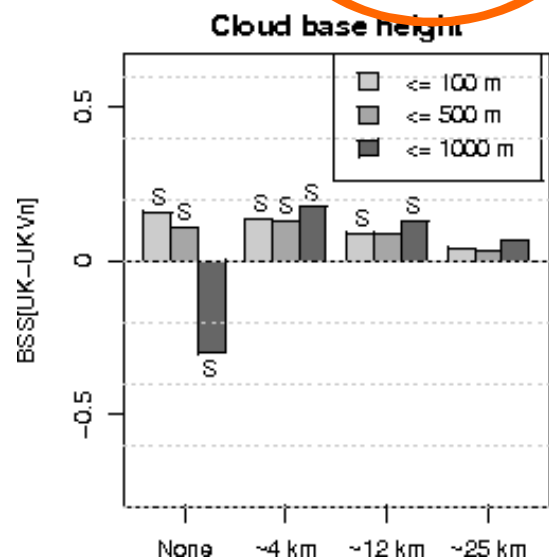
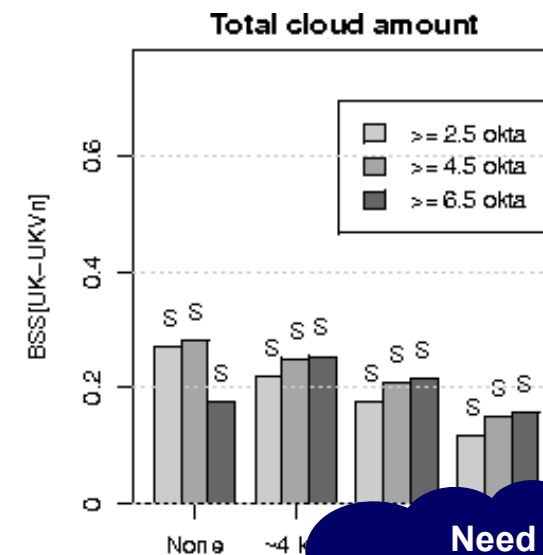
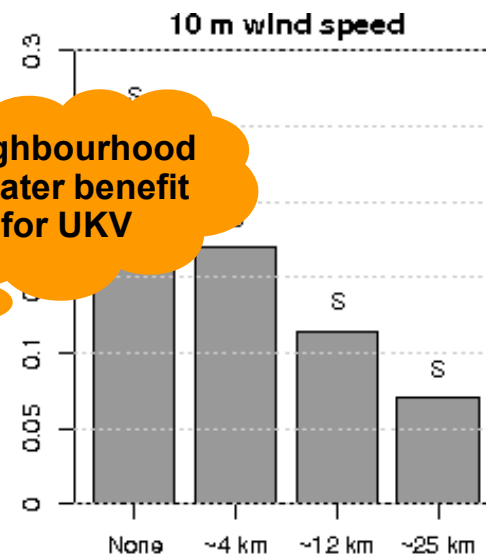
# Deterministic vs EPS

+ve = MOGREPS-UK ensemble better  
"none" = 12 nearest GP values MOGREPS-UK vs 1 nearest GP UKV

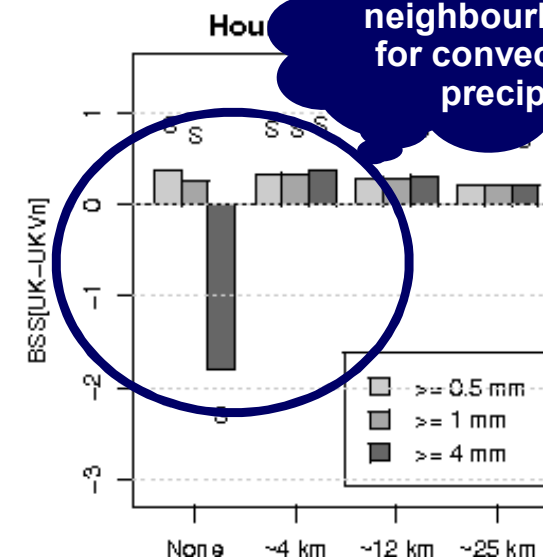
Benefit of ensemble



neighbourhood greater benefit for UKV



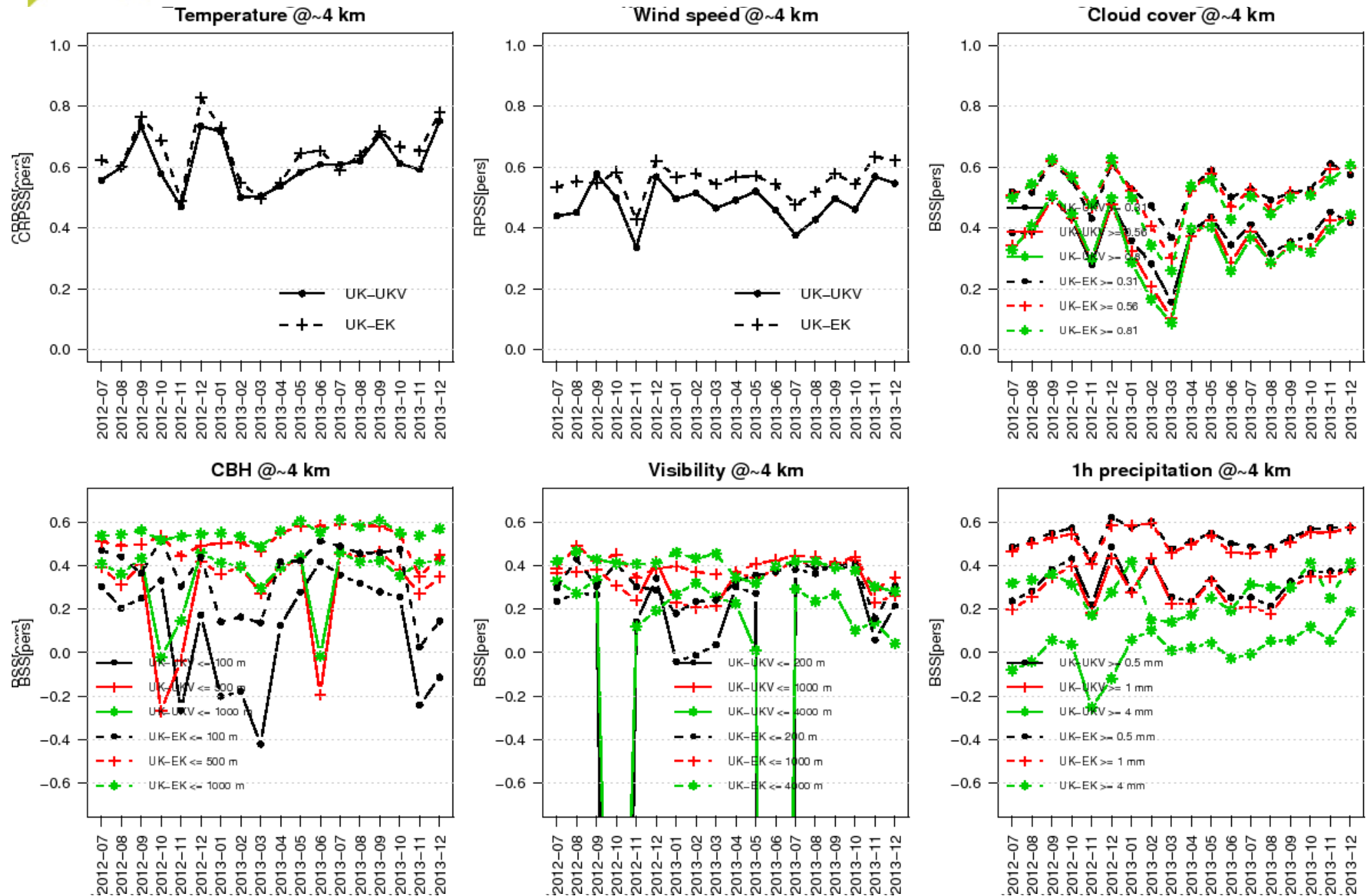
Need neighbourhood for convective precip







# Skill against persistence







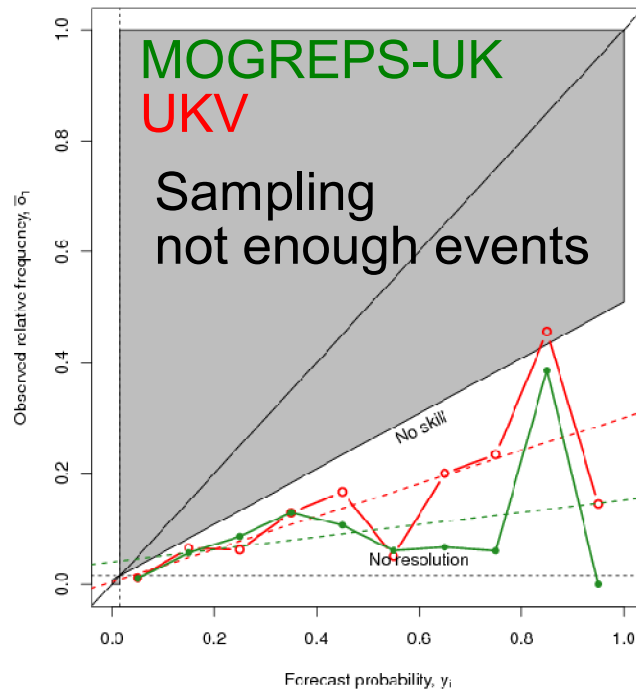
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# A few words on reliability ....

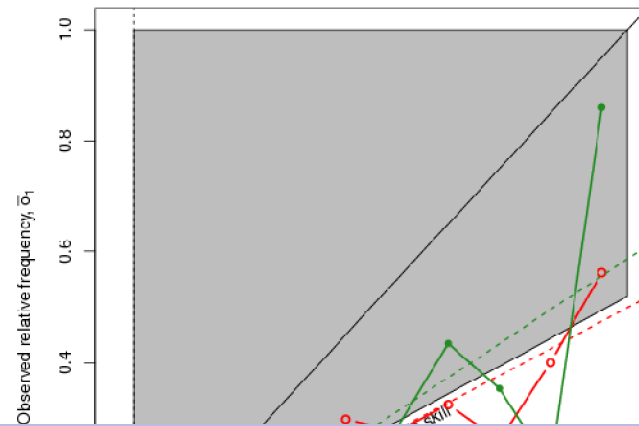
# Visibility and cloud base height (CBH) for 3 months JFM 2013

NB3 ~ 25 km

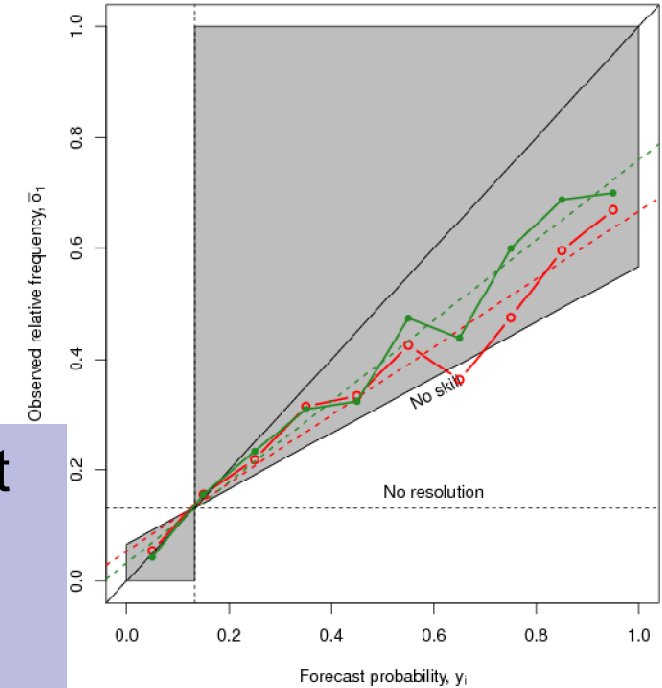
Visibility  $\leq 200\text{m}$  for NB 3 at t+6



Visibility  $\leq 1000\text{m}$  for NB 3 at t+6

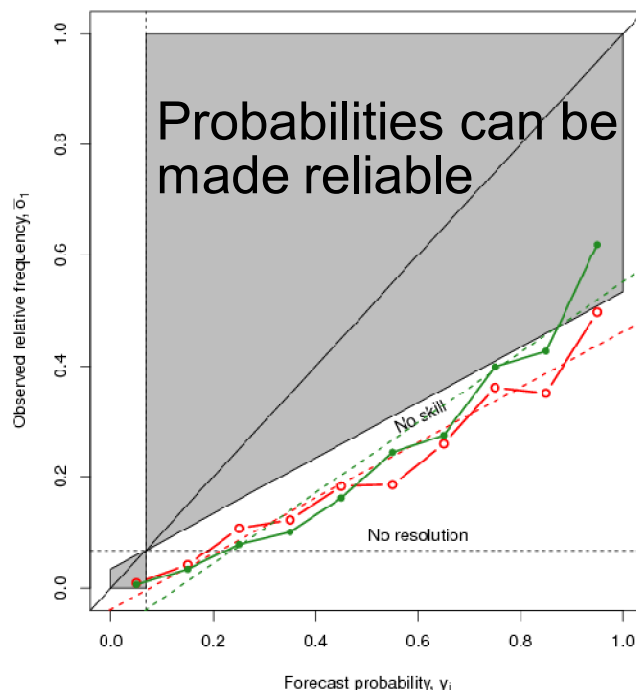


Visibility  $\leq 4000\text{m}$  for NB 3 at t+6

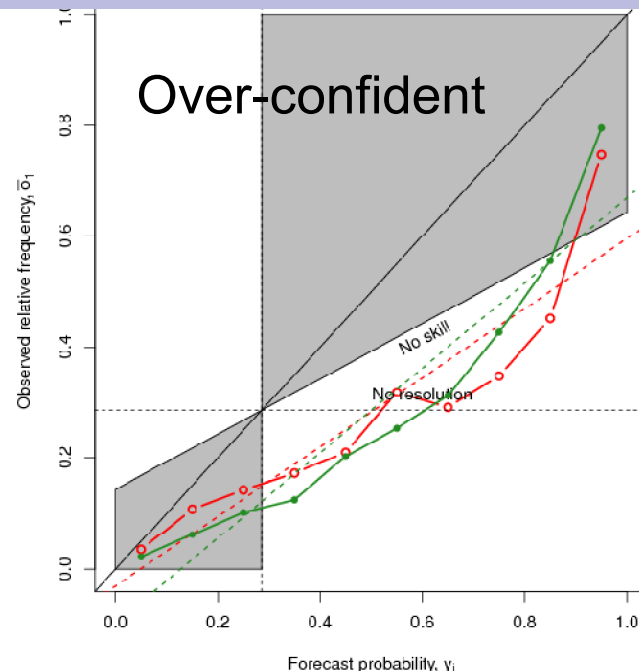


Reliability is not that different between UKV and MOGREPS-UK even though the number of grid-points used is 9x greater

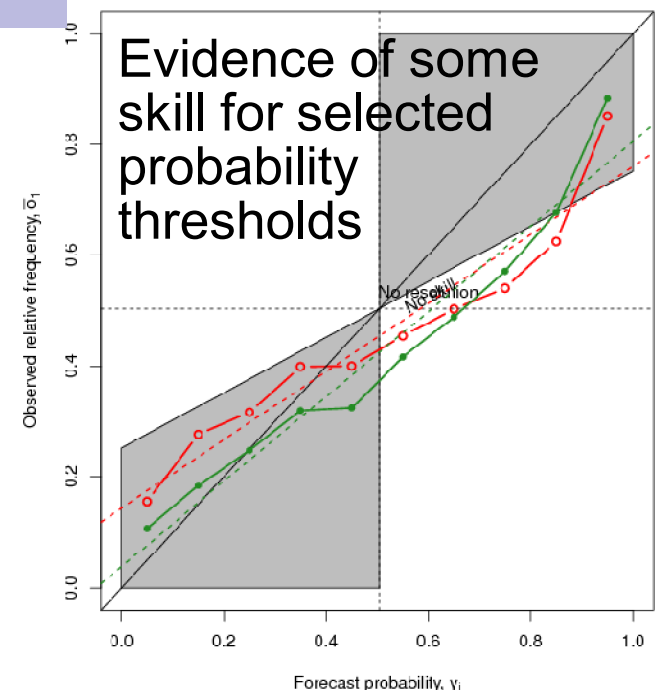
CBH  $\leq 100\text{m}$  for NB 3 at t+3



Over-confident



CBH  $\leq 1000\text{m}$  for NB 3 at t+3



# Conclusions

- Method aims to provide **objective reflection of inherent skill within a forecast neighbourhood** in the vicinity of an observing site in a quasi-probabilistic way.
- Method can not fabricate “skill” where there is none. Model deficiencies are clearly highlighted.
- Method **appears robust** for all three scenarios tested → key requirement for Met Office Unified Model R & D.
- Results point the way for **post-processing km-scale NWP output** to maximise skill of forecast products.



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# Conclusions (cont.)

- New verification framework illustrates **benefit of km-scale ensemble** over deterministic.
- **Bigger neighbourhoods will improve forecast skill** (for the most part) but the UKV needs (and benefits more from) neighbourhood processing, i.e. better “harvesting” of information content.



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# Questions?

Mittermaier MP, 2014: A strategy for verifying near-convection-resolving forecasts at observing sites. *Wea. Forecasting*. **29(2)**, 185-204.