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... and many colleagues from CH, D, I, ROM, RU ...
... in particular Hendrik Reich (DWD)

- **Km-scale ENsemble-based Data Assimilation** : COSMO priority project
- Local Ensemble Transform Kalman Filter (LETKF) system being developed

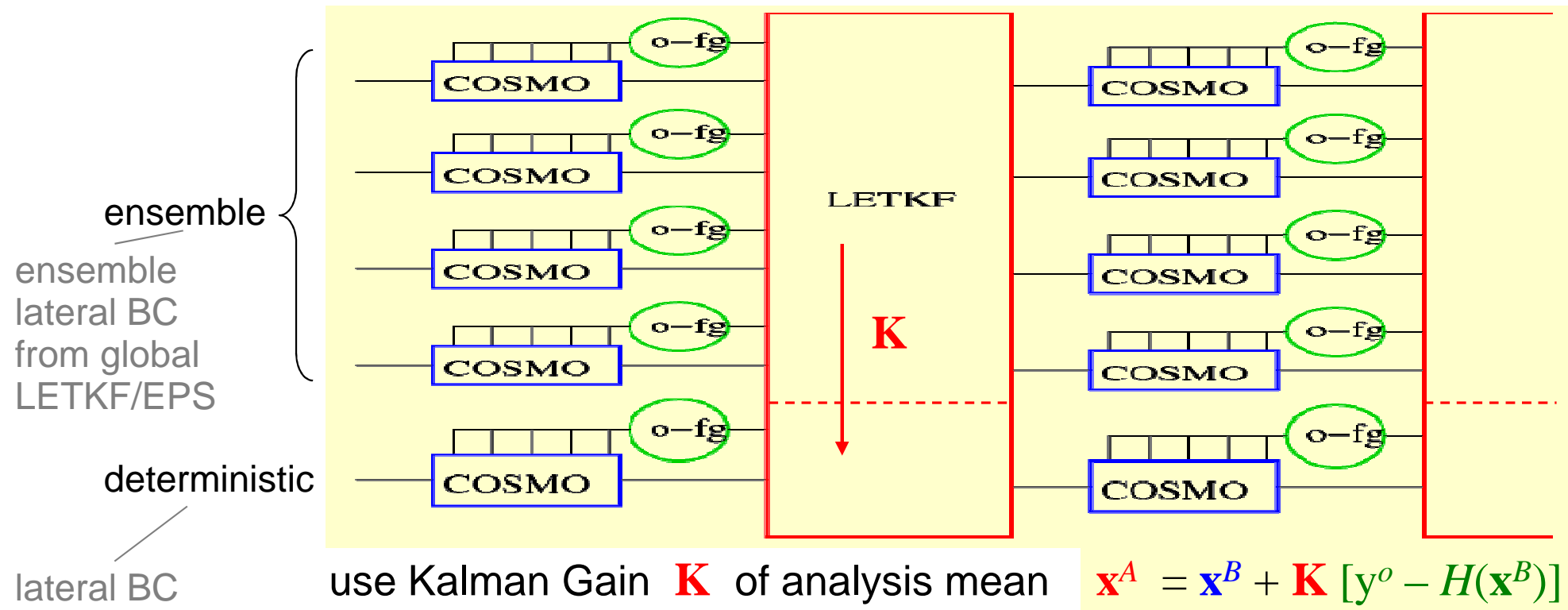
first goal: replace nudging (+ latent heat nudging) with deterministic LETKF analysis
→ focus on quality of deterministic analysis/forecast

This talk:

- LETKF experiments using conventional obs, comparison to nudging (+ LHN)
- brief overview on use of high-res obs and plans

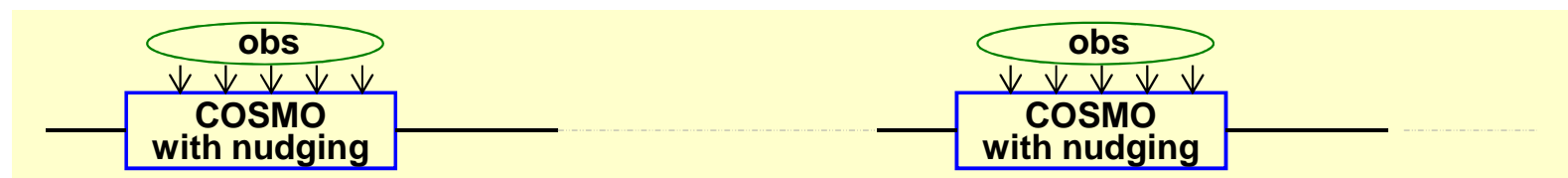
LETKF (km-scale COSMO) : implementation

→ ensemble of COSMO runs, collecting obs – f.g. → 4D-LETKF

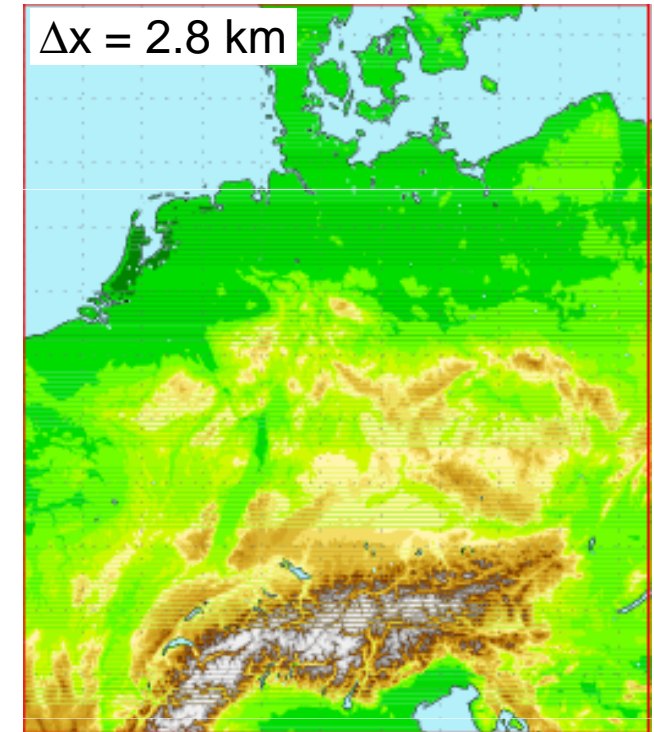


- deterministic run must use same set of obs as ensemble system !
- deterministic run may have higher resolution

benchmark:
Nudging
(+ LHN)



- **DWD:** BACY experimentation environment
 - 1.5 days of **1-hrly** LETKF cycle ($N_{ens}=40$)
with COSMO-DE computed in 1 day real-time
 - adaptive multiplicative covariance inflation
(based on innovation statistics)
applied to analysis ensemble
 - relaxation to prior spread (RTPP)
 - adaptive horizontal localisation length scale
(idea: adapt scale to data density)
- **MeteoSwiss:** similar experiments (→ Poster !),
 $\Delta x = 2.2$ km, smaller domain
lateral BC from IFS EPS



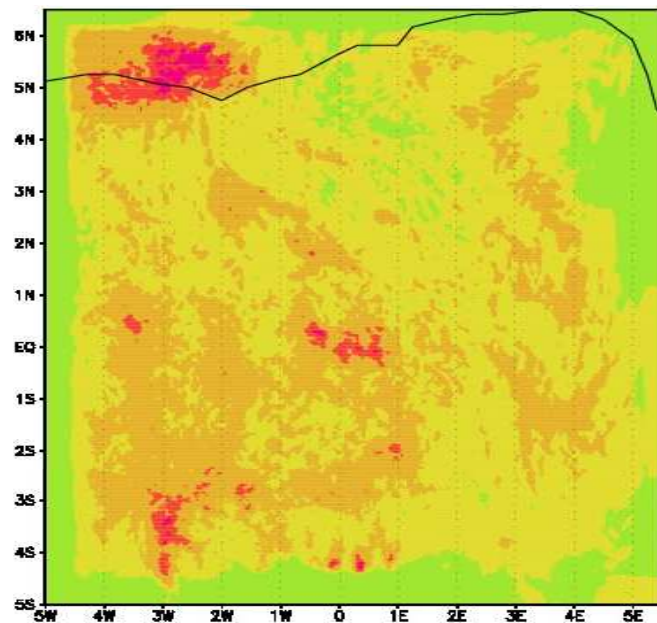
KENDA, new series of experiments: influence of **lateral BC (spread)**

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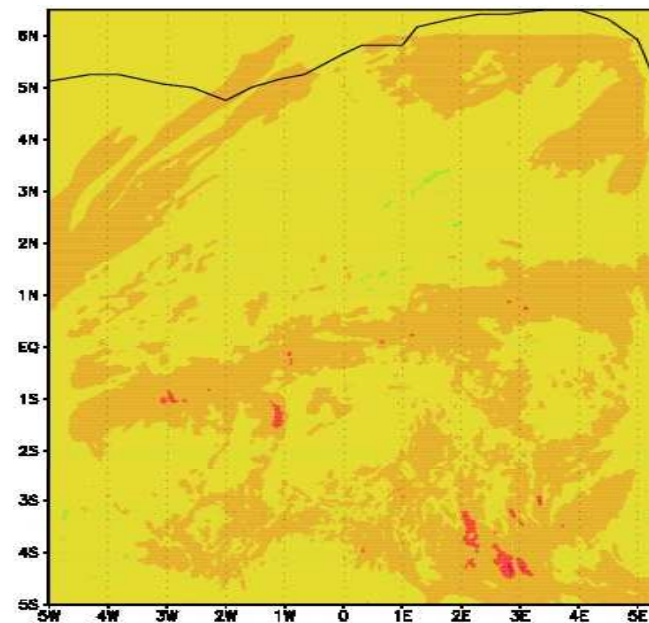


- new period: 19 – 25 July 2012, deterministic 24-h forecasts every 6 hrs
- lateral BC from ICON-LETKF (better spread than GME-LETKF over Europe !)

2011060600
lateral BC from **GME-LETKF**



2012072400
lateral BC from **ICON-LETKF**



f.g. spread
zonal wind
at ~ 500 hPa

→ spread from
ICON-LETKF
~ ok

- compare deterministic LETKF forecast with free fc & nudging :
same obs (except QC), lateral BC, initial state at 19 July (atm. + soil)

→ better spread in lat. BC → LETKF compares more favourably to nudging



introduction of soil moisture (SM) perturbations (+ SST pert.)

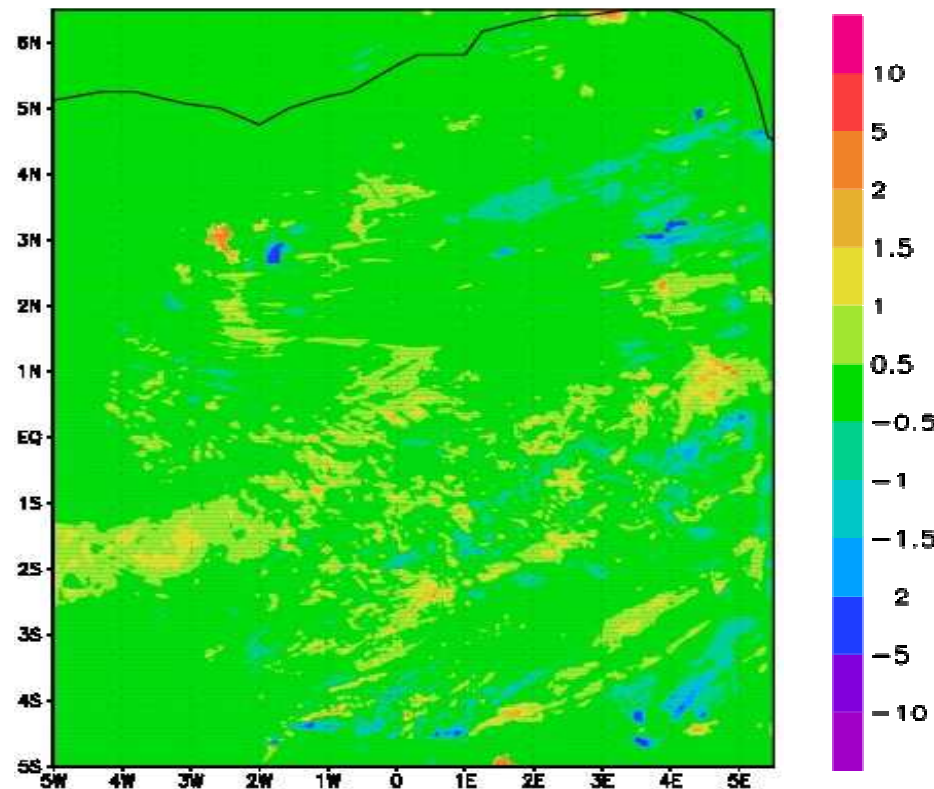
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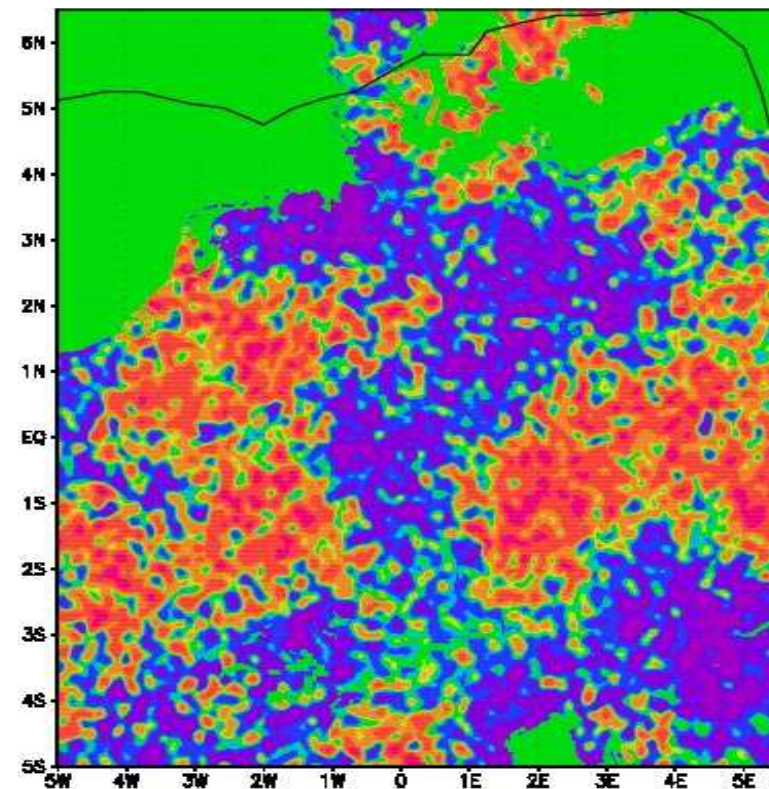
- ✓ simple superposition of Gaspari-Cohn (~ Gaussian) functions at each analysis g.p., with random amplitude and pre-specified horiz. / temporal correlation scale(s)
- ✓ scales : 100 km + 10 km ; 1 day ; std dev of amplitude: 0.1 soil moisture index

spread of soil moisture (WSO), layer 3 (3 – 9 cm), after 5 days

cycling without perturbations



cycling with SM perturbations

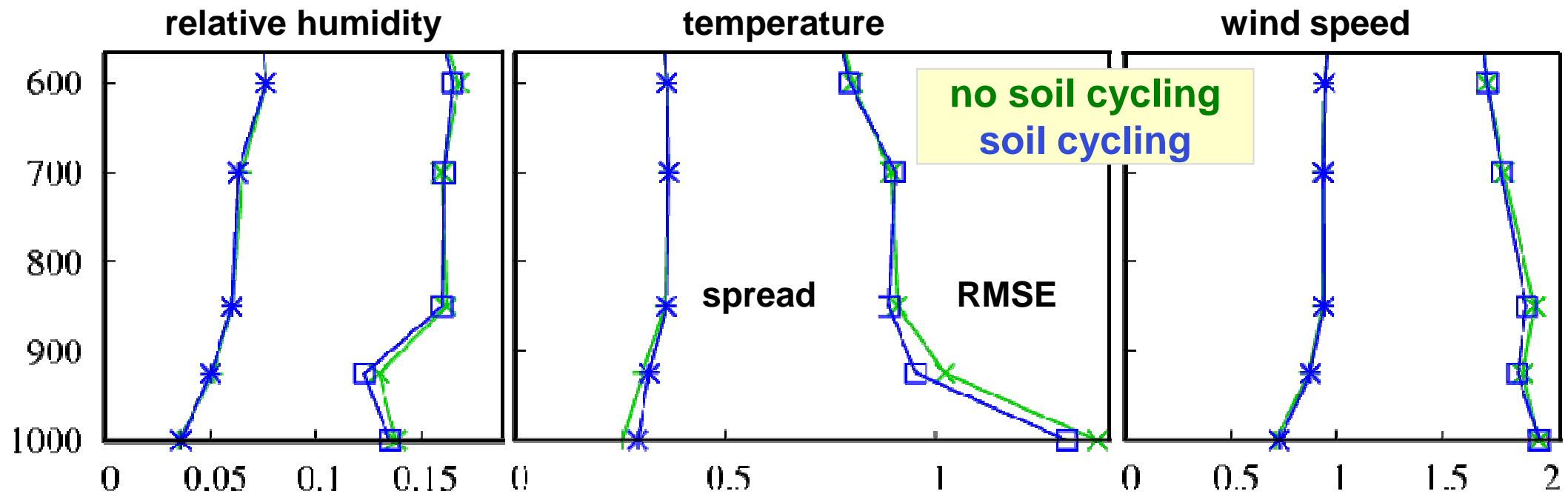


impact of including in LETKF (SST +) **soil moisture perturbations**

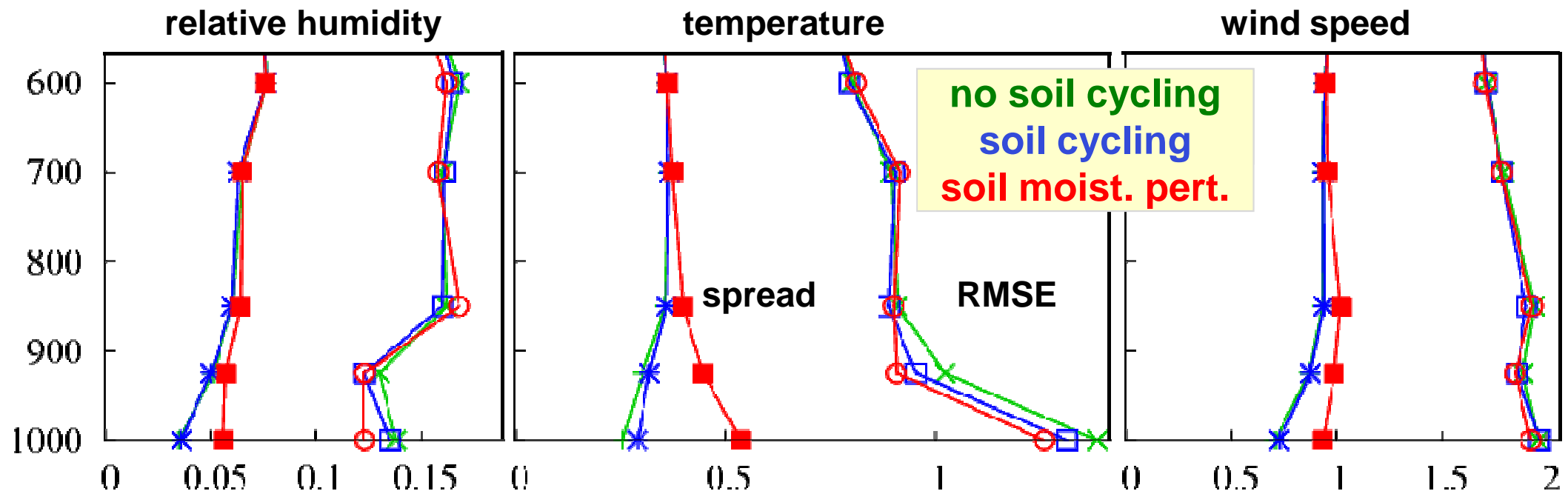
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upper-air verification (spread / RMSE) of first guess (1-h forecast)

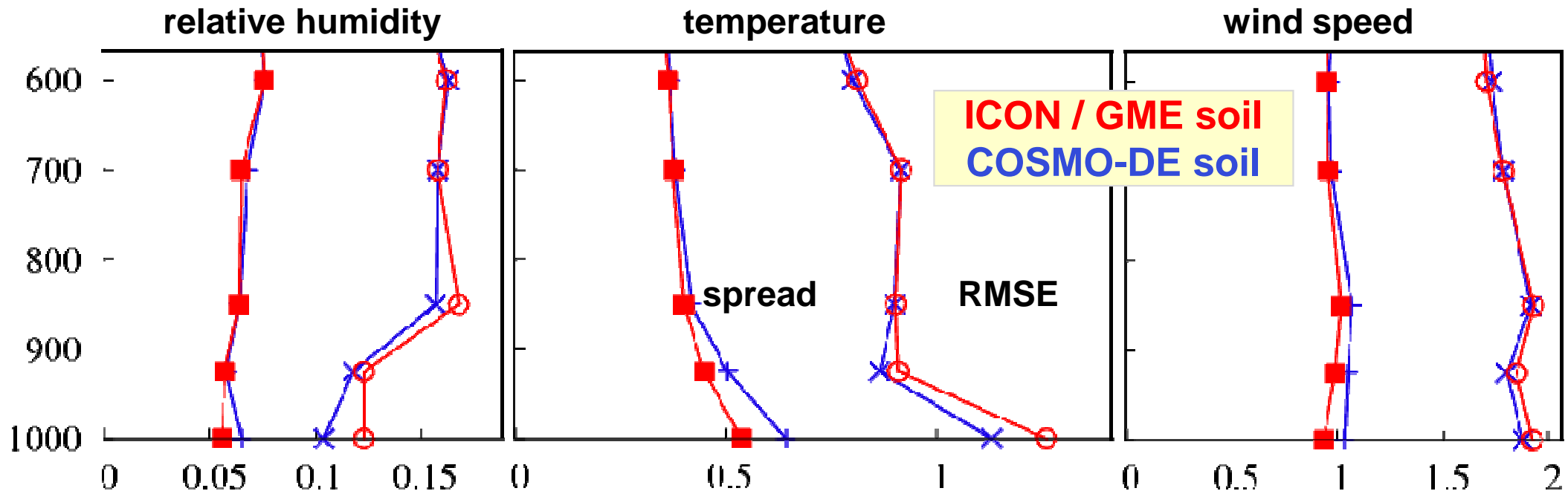


upper-air verification (spread / RMSE) of first guess (1-h forecast)



- RH, T, wind, near surface:
larger spread, smaller errors in f.g. (+ 6 h)
- slightly smaller errors in ps(!), T2m, Td2m, CLCM forecasts
- use soil moisture perturbations in following exp.

upper-air verification (spread / RMSE) of first guess (1-h forecast)



→ RH, T, wind, near surface: smaller errors,
larger spread, despite soil moisture perturbations of same size !

Why ?

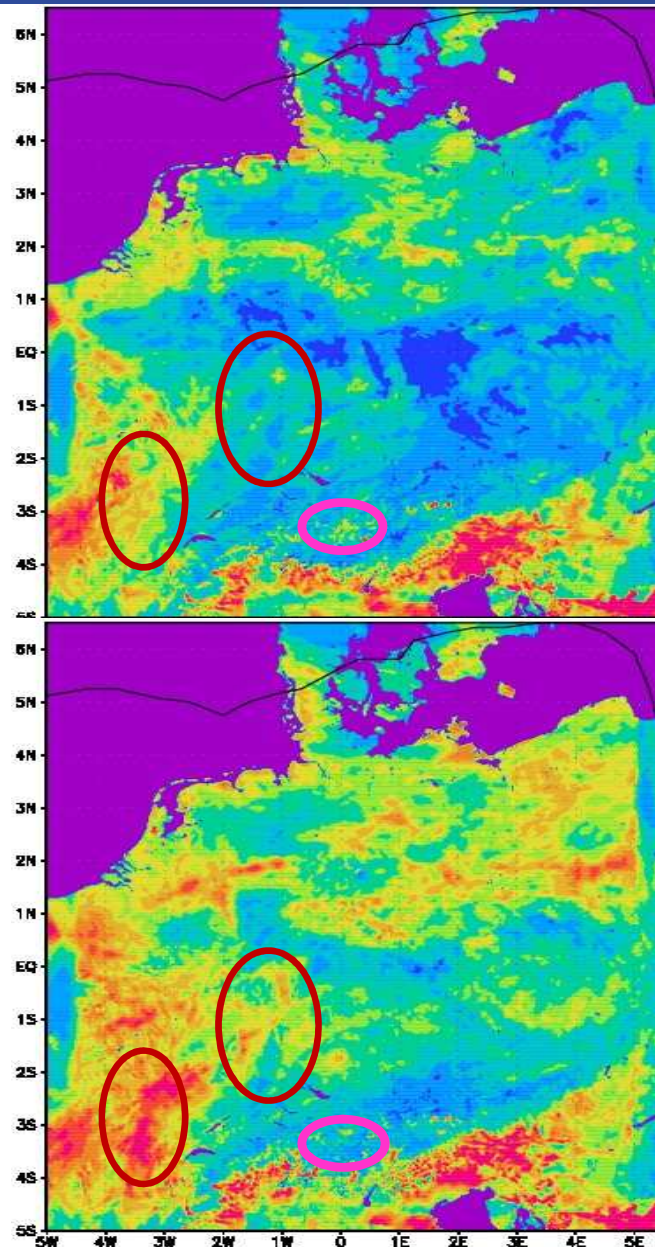
LETKF with COSMO-DE soil (LHN, no SMA)
vs. ICON / GME soil (→ SMA)

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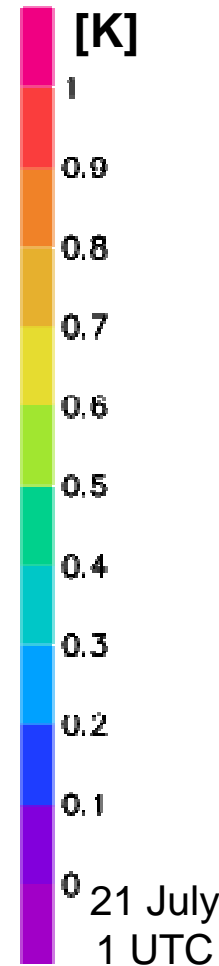


ICON
soil

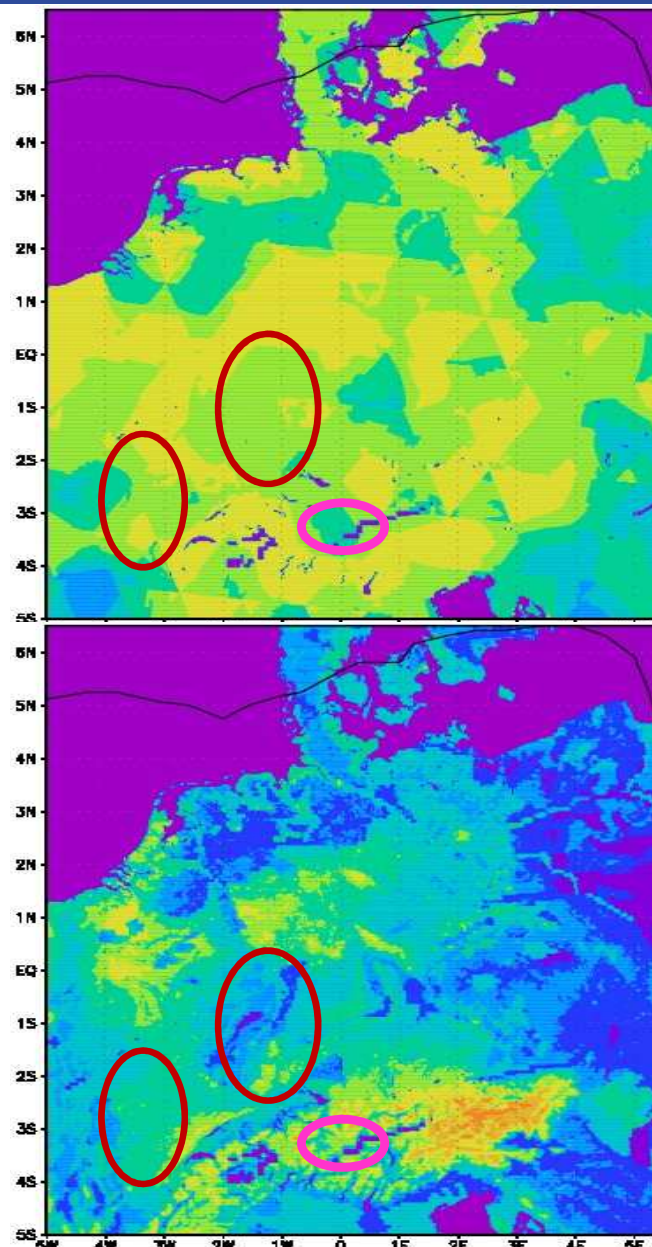
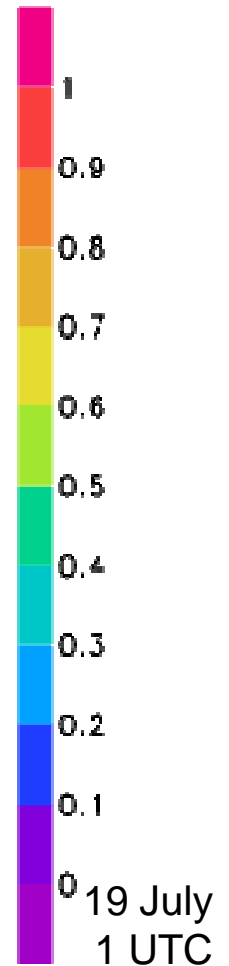
C-DE
soil

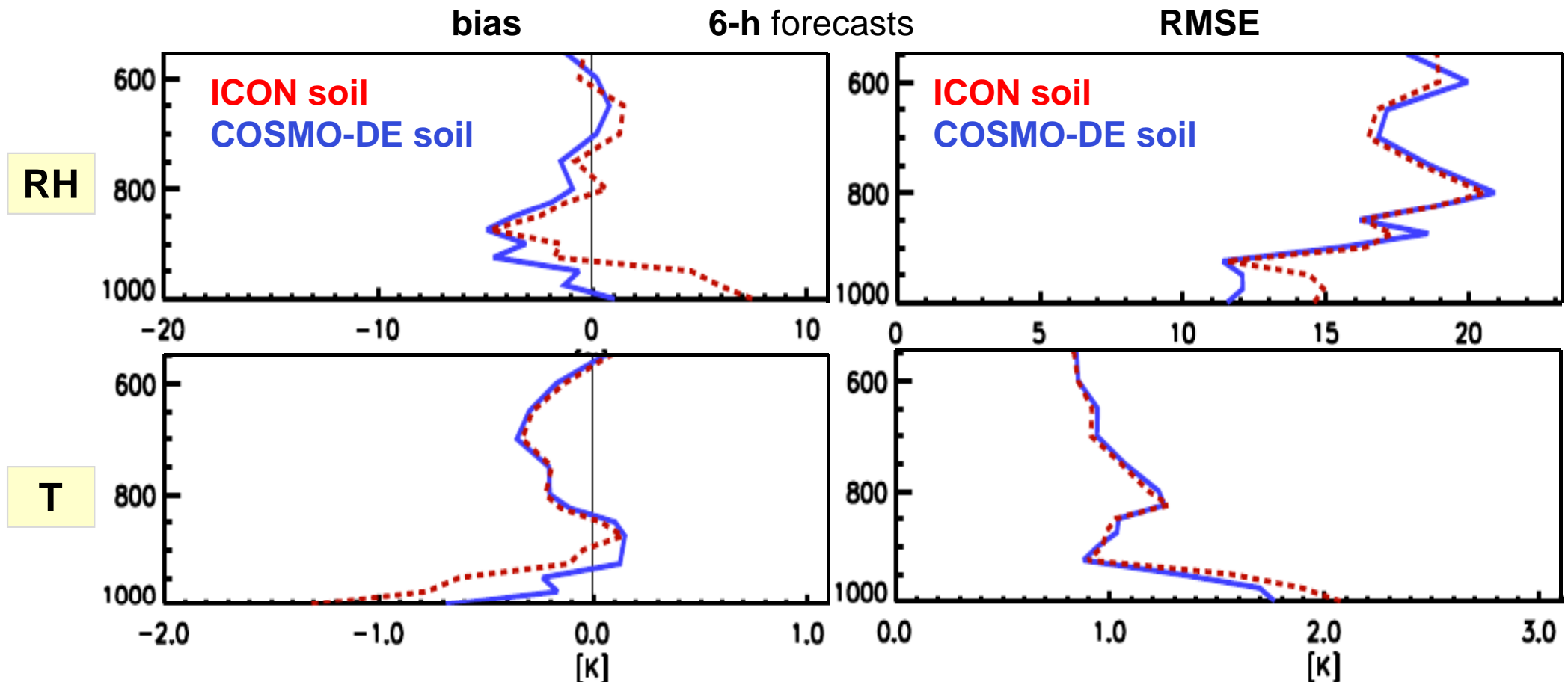


soil
temperature
spread,
layer 1
0 – 1 cm
[K]

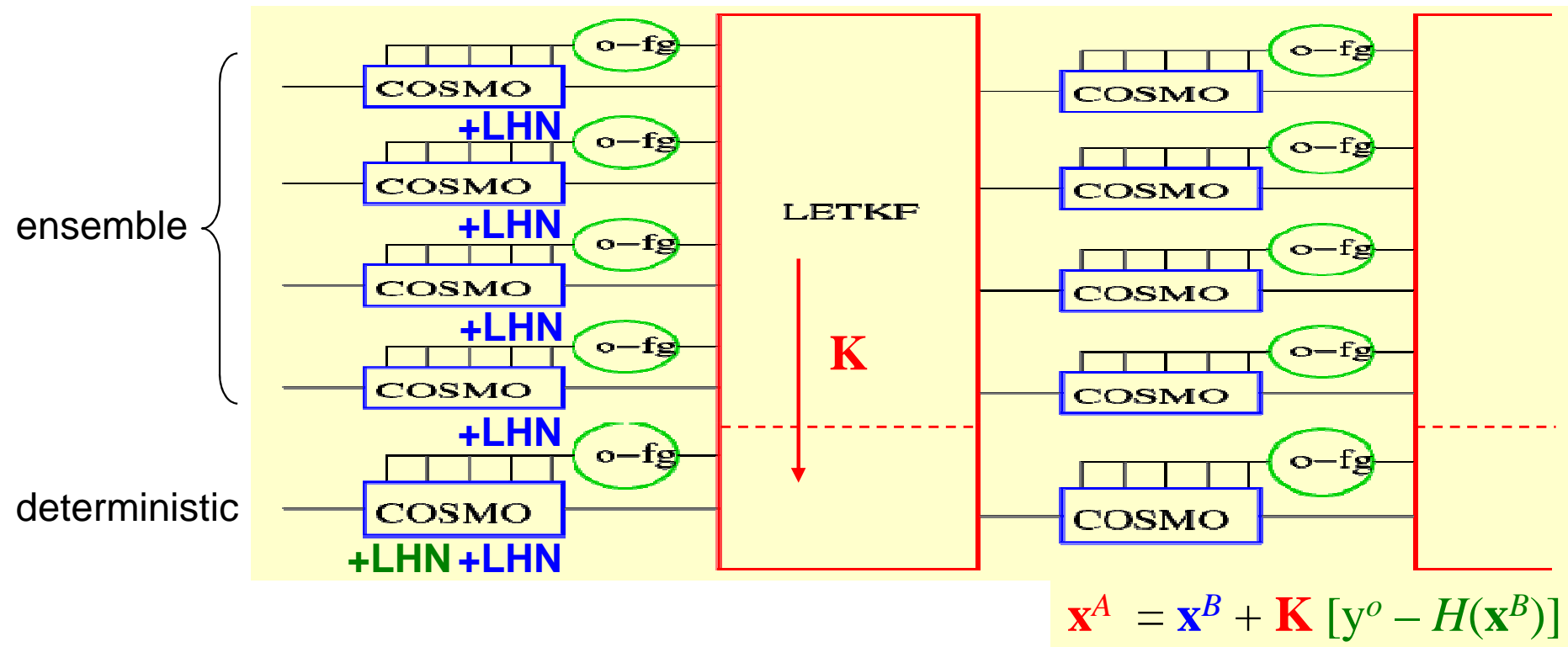


Soil
Moisture
Index,
layer 5
27–71 cm





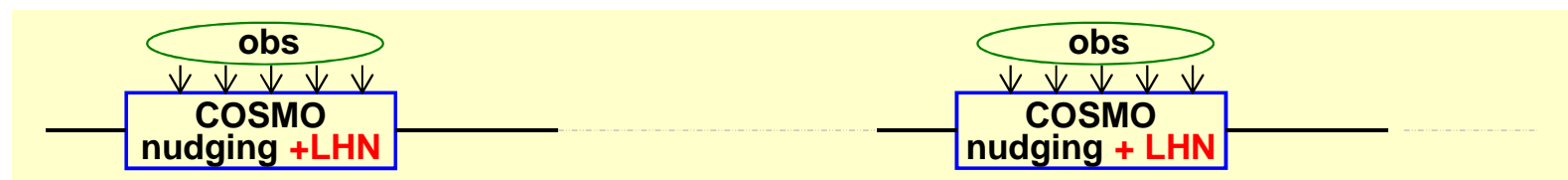
- plant evapotranspiration more sensitive to SM changes/perturb., if SM low
- C-DE soil: higher spread in soil temperature & in f.g. T, RH at low levels
- reduced bias & RMSE of T, RH at low levels
- reduced bias of T2m, Td2m, improved T2m, low cloud



LETKF + LHN-det : LETKF unaffected; but Kalman Gain \mathbf{K} not optimal ?

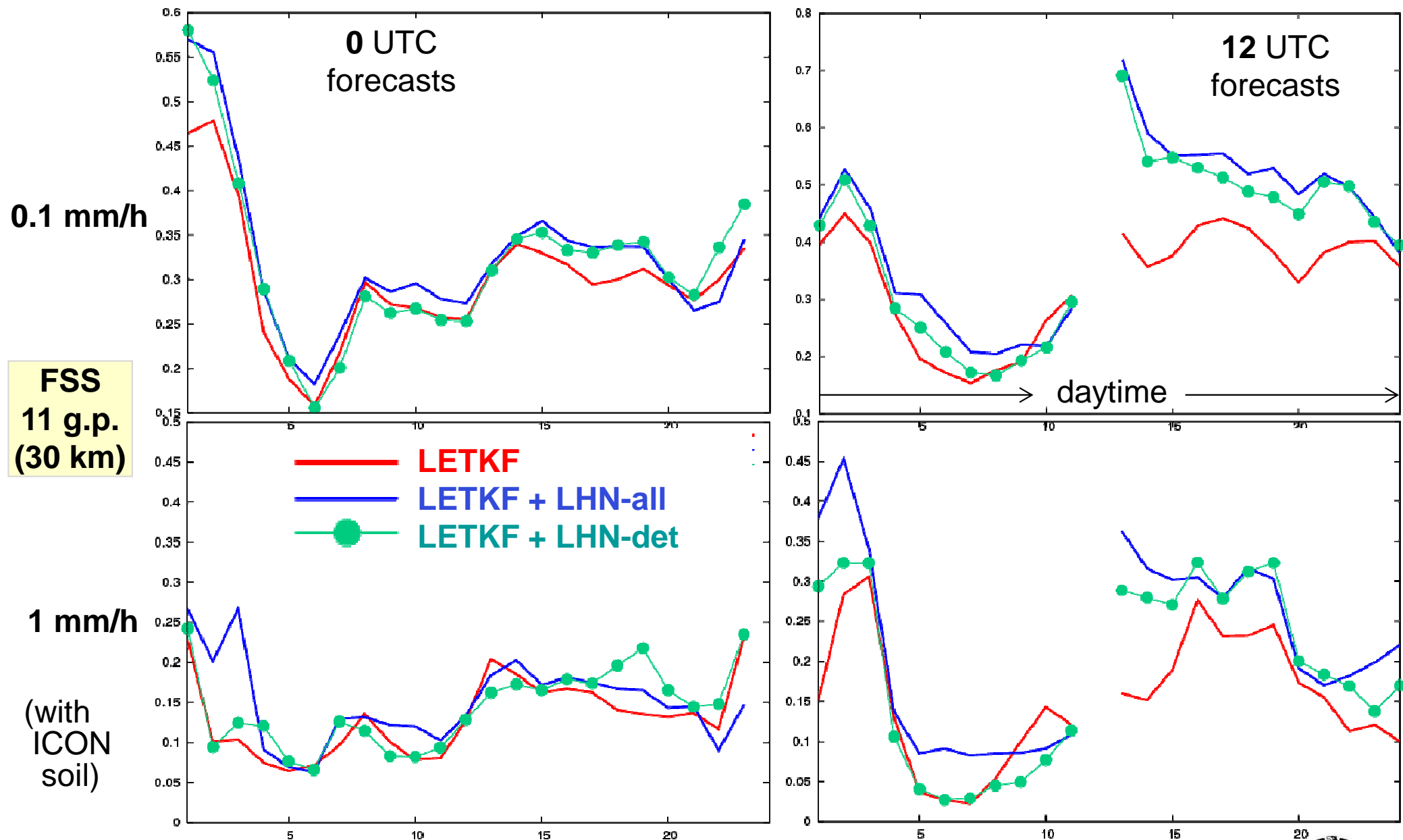
LETKF + LHN-all : f.g. ens. deviations (B-matrix !) 'destroyed' by LHN ?

benchmark:
Nudging
+ LHN



including LHN in LETKF DA cycle:
verification against 1-hrly radar precipitation

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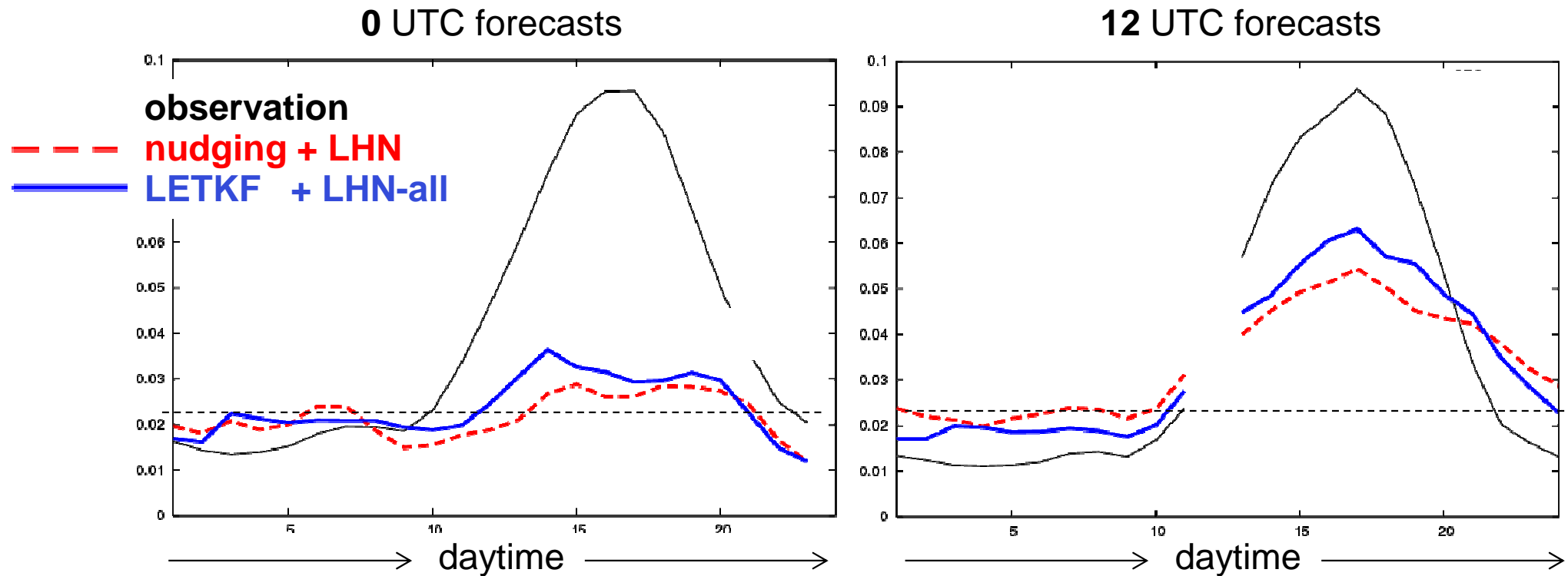


LETKF + LHN-all vs. Nudging + LHN (with C-DE soil) : verification against radar precipitation

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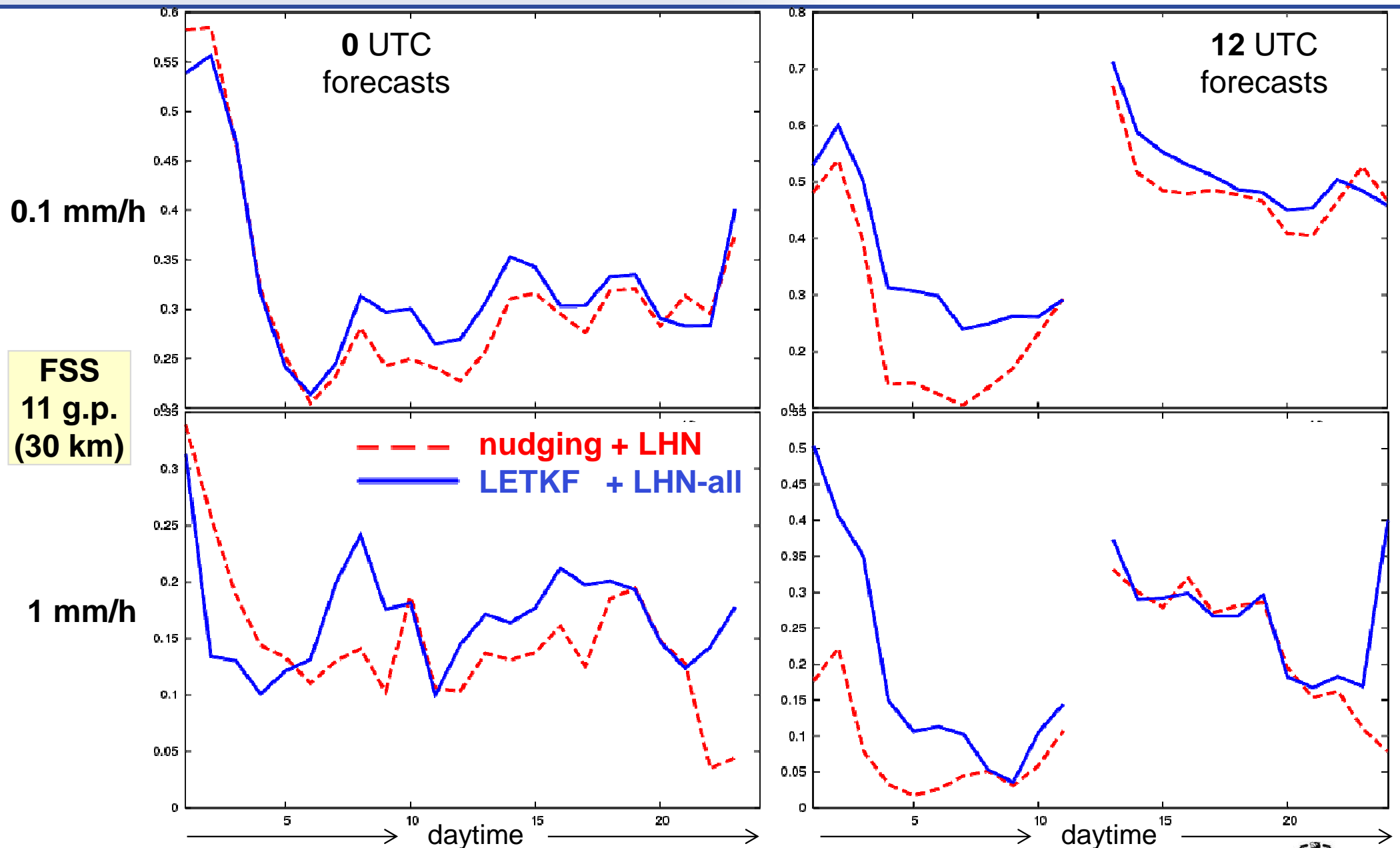


daily cycle of domain average precip → info on bias



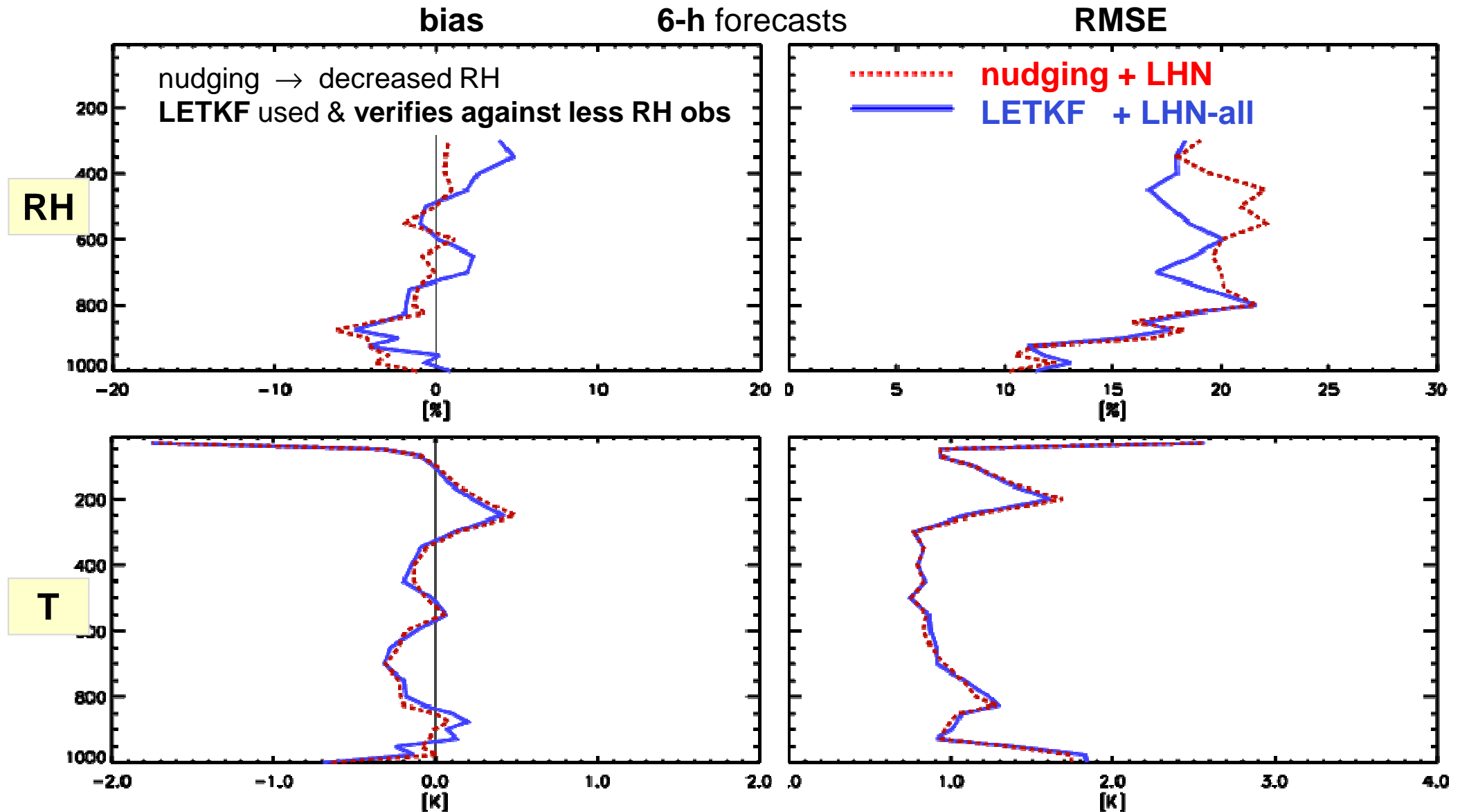
LETKF + LHN-all vs. Nudging + LHN : verification against radar precipitation

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LETKF + LHN-all vs. Nudging + LHN : upper-air verification

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LETKF + LHN-all vs. Nudging + LHN : surface verification

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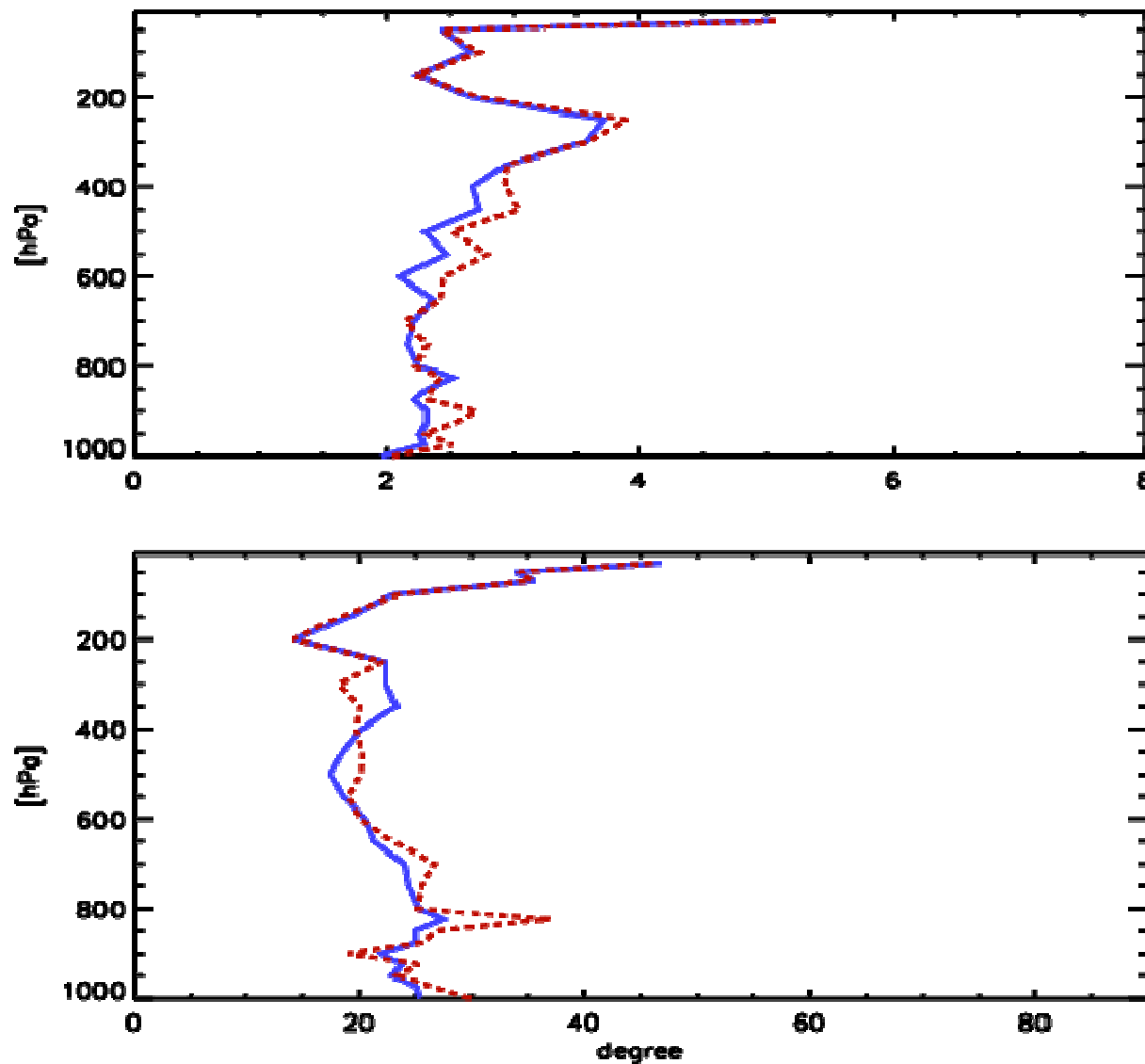
wind speed

..... nudging + LHN
—— LETKF + LHN-all

wind direction

6-h forecasts

RMSE



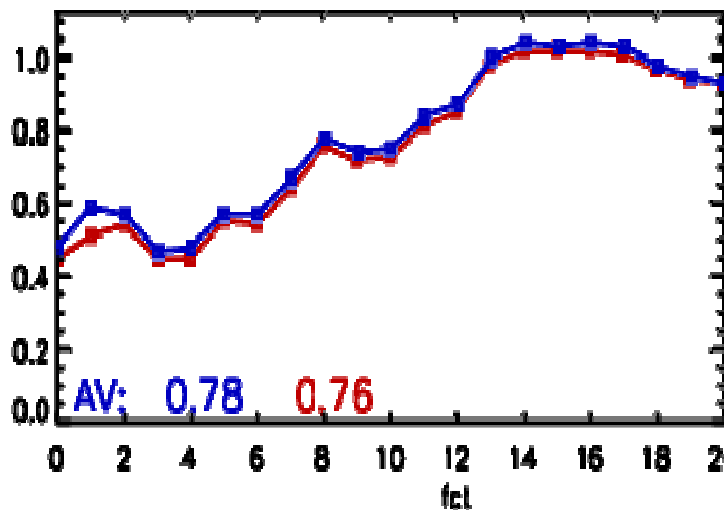
LETKF + LHN-all vs. Nudging + LHN : upper-air verification

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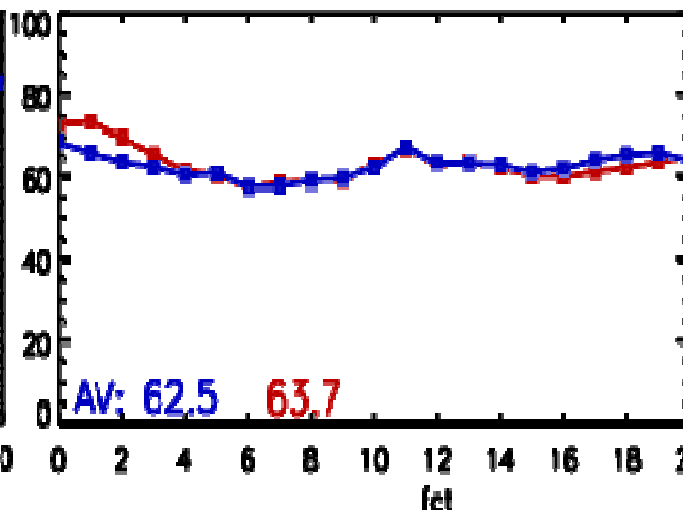
— nudging + LHN
— LETKF + LHN-all

RMSE
surface pressure



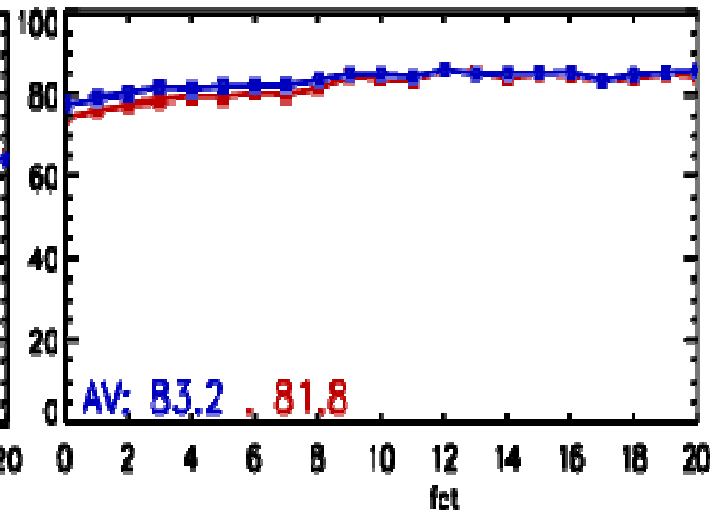
LETKF worse

hit rate
high cloud



LETKF worse in first 3 hours
(too little high cloud)

hit rate
mid-level cloud



LETKF better



| (C-DE soil) | <u>LETKF + LHN-all</u> vs. <u>Nudging + LHN</u> | | |
|----------------|-------------------------------------------------|-------|------|
| | variable | RMSE | bias |
| upper air | geopotential | = | = |
| | temperature | (-/=) | = |
| | (relative humidity) | + | (-) |
| | wind speed | + | = |
| | wind direction | (+) | = |
| surface | 2-m temperature | = | = |
| | 2-m dew point temp. | = | = |
| | 10-m wind | = | = |
| | surface pressure | - | = |
| | total cloud | = | = |
| | low cloud | (+) | (+) |
| | mid-level cloud | (+) | (+) |
| | high cloud | (-) | (-) |
| radar | precip 0 UTC | (+/-) | (+) |
| | precip 12 UTC | + | + |

LETKF:

- overall comparable / better results
- problem with surface pressure

- ✓ lateral BC spread (+ quality) important (also seen in MeteoSwiss experiments)
- ✓ soil moisture perturbations beneficial near surface;
- ✓ large sensitivity of results to level of soil moisture
- ✓ no very obvious problems with combining LETKF & LHN
- ✓ deterministic forecasts: **LETKF comparable / better than nudging**
negative: surface pressure (→ need more spread of ps in lateral BC)
needs attention: precip (exp. 0-UTC runs) ; high cloud

BUT, **results are preliminary !!**

- only 6 days → need longer periods, different weather situations
- quality control of RH too restrictive in LETKF (assim. + verif.)

- **GPS slant path delay:** pure obs operator implemented
(Bender) some technical work before DA exp.
- **Radar : 3-D radial velocity V_r & reflectivity Z**
(Zeng, Bick) – thinning, superobbing strategies implemented, monitoring set up
– first DA cycles run
- **SEVIRI cloudy radiances:** first cycled DA experiments,
(Perianez) different (cloud-type dep.) bias correction
→ positive impact on simulated radiances in first guess
- **SEVIRI cloud top height :** tuning experiments on thinning, localisation...
(Schomburg) → positive impact on cloud cover, negative on upper-air T, RH
- Microwave radiometer + Raman lidar (Haefele, MCH)

A lot of work yet to be done, everywhere !

SMC meeting Feb 2014: **extend PP KENDA** (by ~ 1 y, Sep. 2015)

reason: clear project **aim: operability**

- Background: KENDA pre-operational at MeteoSwiss in mid 2015
KENDA pre-operational at DWD in Oct. 2015 (for det. forecasts)

Aim: **operationability of KENDA by ~ Aug. 2015**

- **quality:** match quality of current operational nudging + LHN
 - recommended setup: update frequency, (ensemble size), specified obs errors, adaptive methods (inflation, localisation,..), multi-scale analysis with variable localisation, (possibly noise control by incremental analysis update)...
 - LBC with realistic spread, e.g. add ECMWF EPS forecast perturbations with larger forecast lead time to IFS det. (MCH); optimize ICON-LETKF (DWD)
 - additive covariance inflation: SPPT (stochastic perturbation of physics tendencies), stochastic physics, (perturbed physics parameter ?)
incremental random perturbations with prescribed spatial-temporal correlation scales;
self-evolved perturbations ?)
- complete DA cycle: soil: add SST and snow depth analysis
- technical issues

main strategy: develop EnDA (EnKF) for IC for det.+ EPS forecast at convective scale

- ✓ further optimize / refine LETKF
- ✓ use of dense obs:
radar, satellite, related to humidity / weather parameters, also for surface
- ✓ towards nowcasting
→ need for high quality and efficiency
- + porting COSMO to ICON-regional

Thank you for your attention !