

ALADIN status overview

Piet Termonia



37th EWGLAM and 22th SRNWP Meeting



Members of the ALADIN Consortium

Algeria



Austria



Belgium



Bulgaria



Croatia



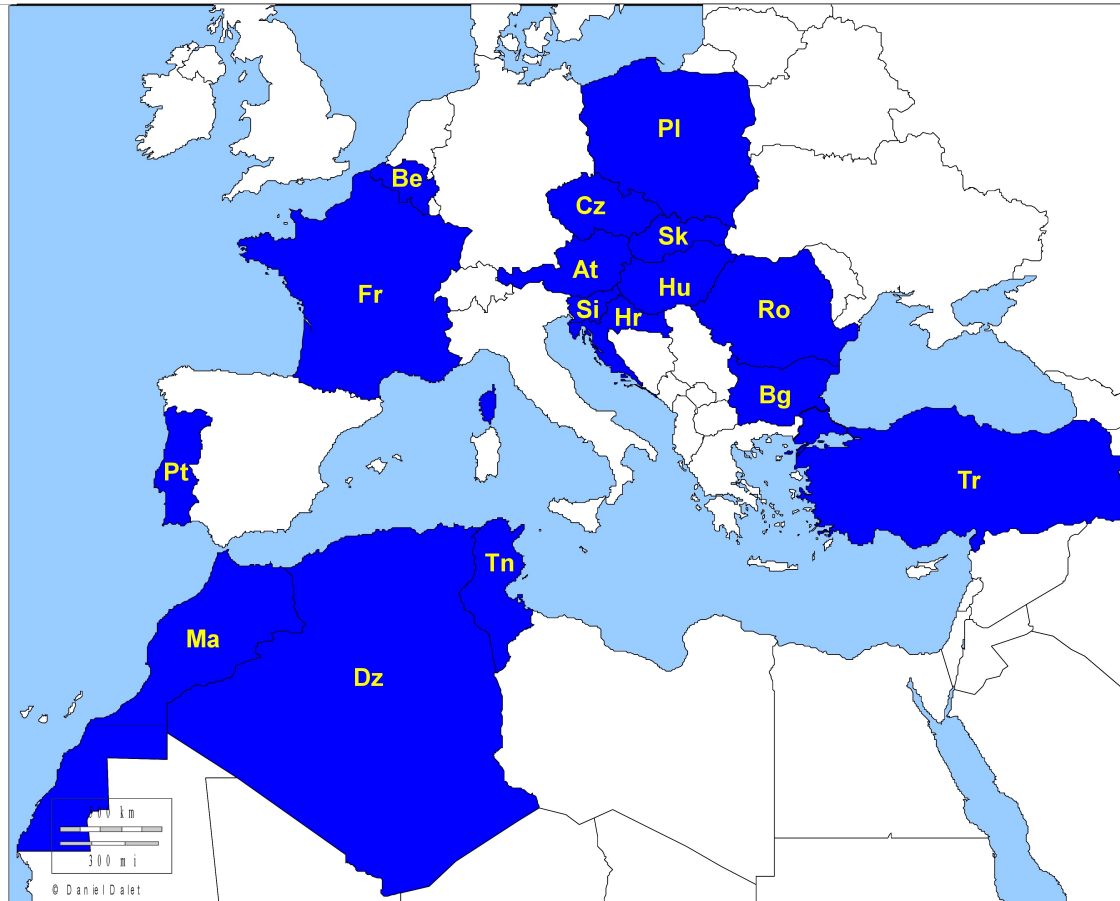
Czech R.



France



Hungary



Morocco



Poland



Portugal



Romania



Slovakia



Slovenia



Tunisia



Turkey

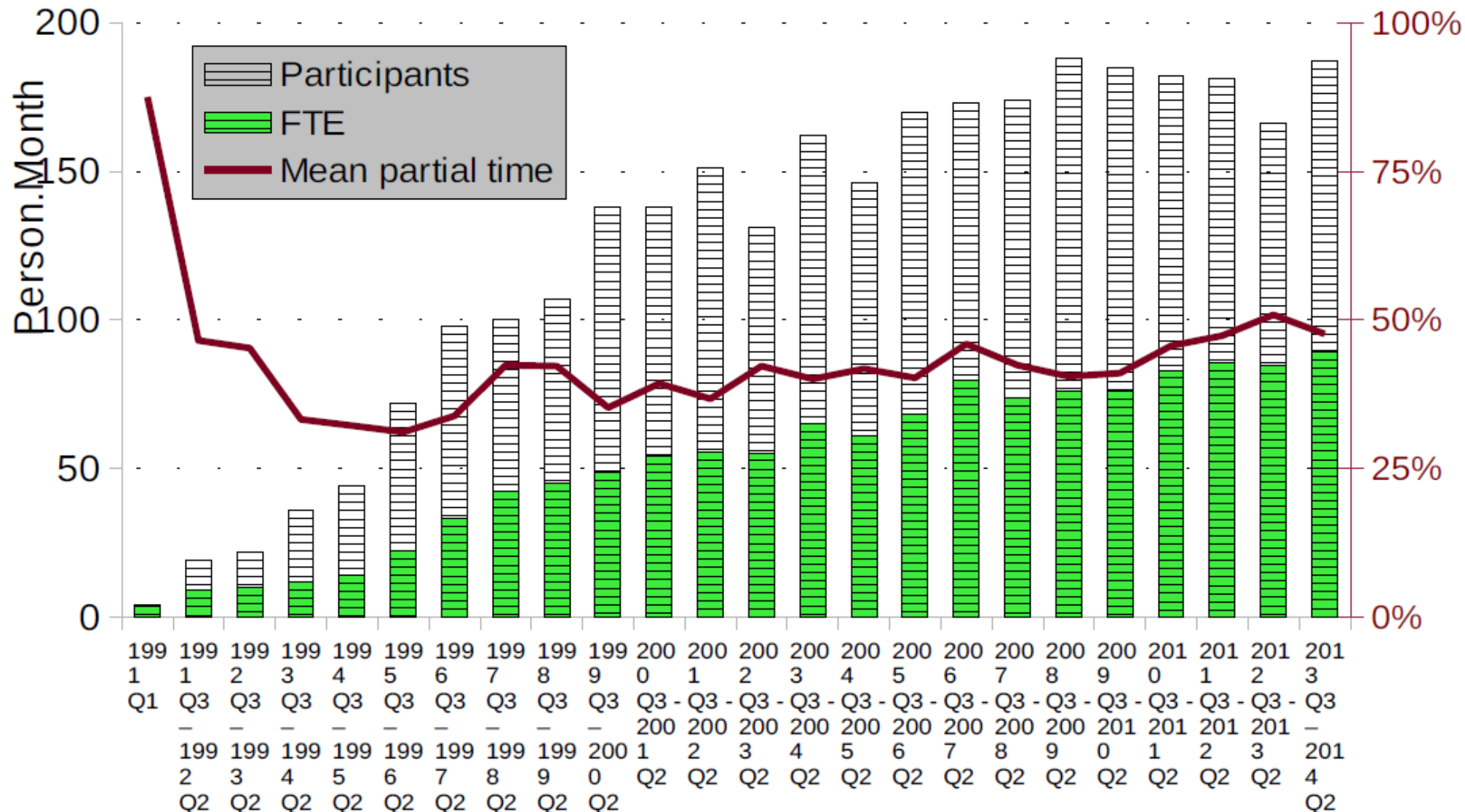
Updated on 07/01/2013



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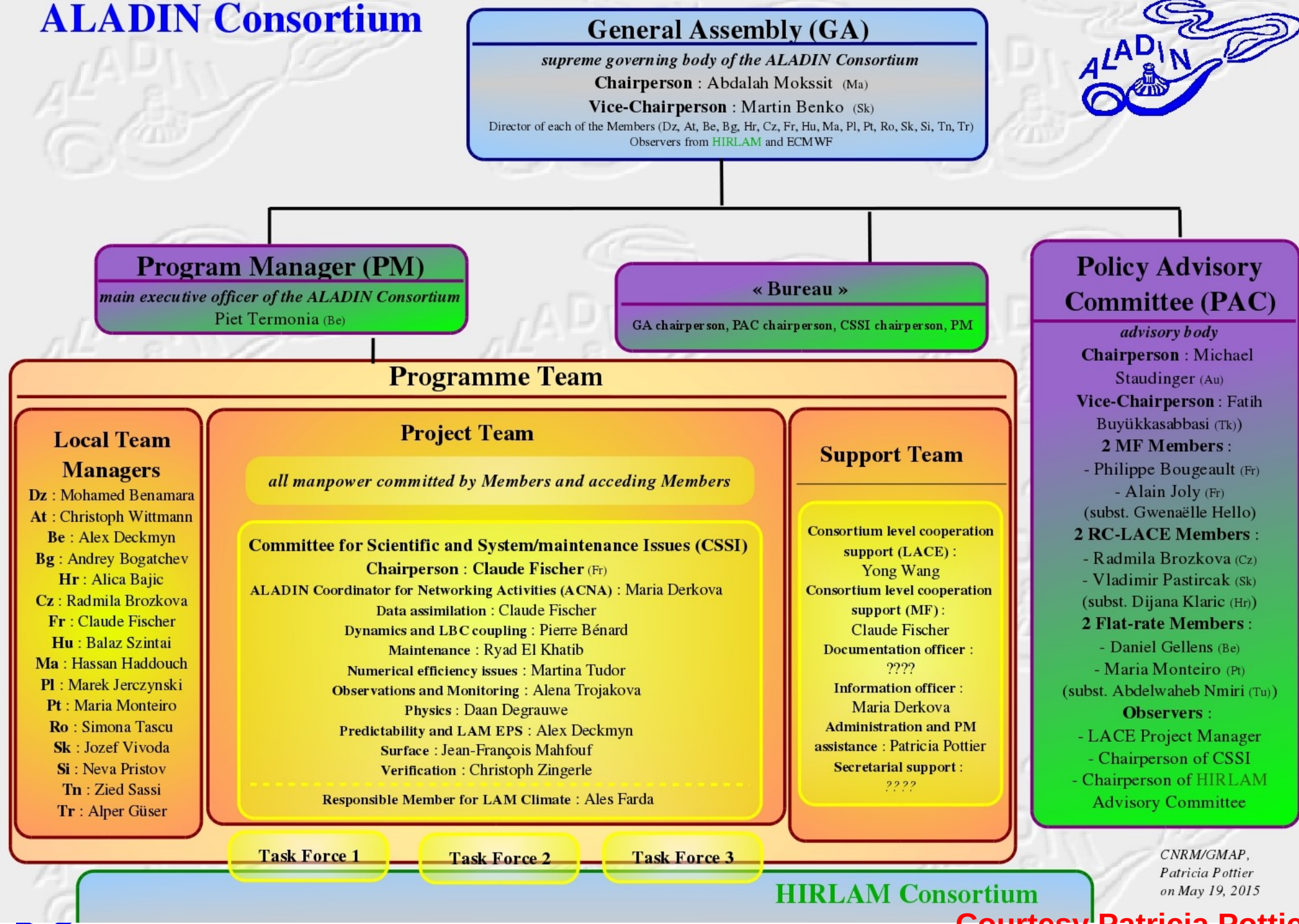
Total participation in the ALADIN project

Evolution of the yearly Full Time Equivalent



Courtesy Patricia Pottier

ALADIN Consortium



CNRM/GMAP,
Patricia Pottier
on May 19, 2015

Courtesy Patricia Pottier

Activities

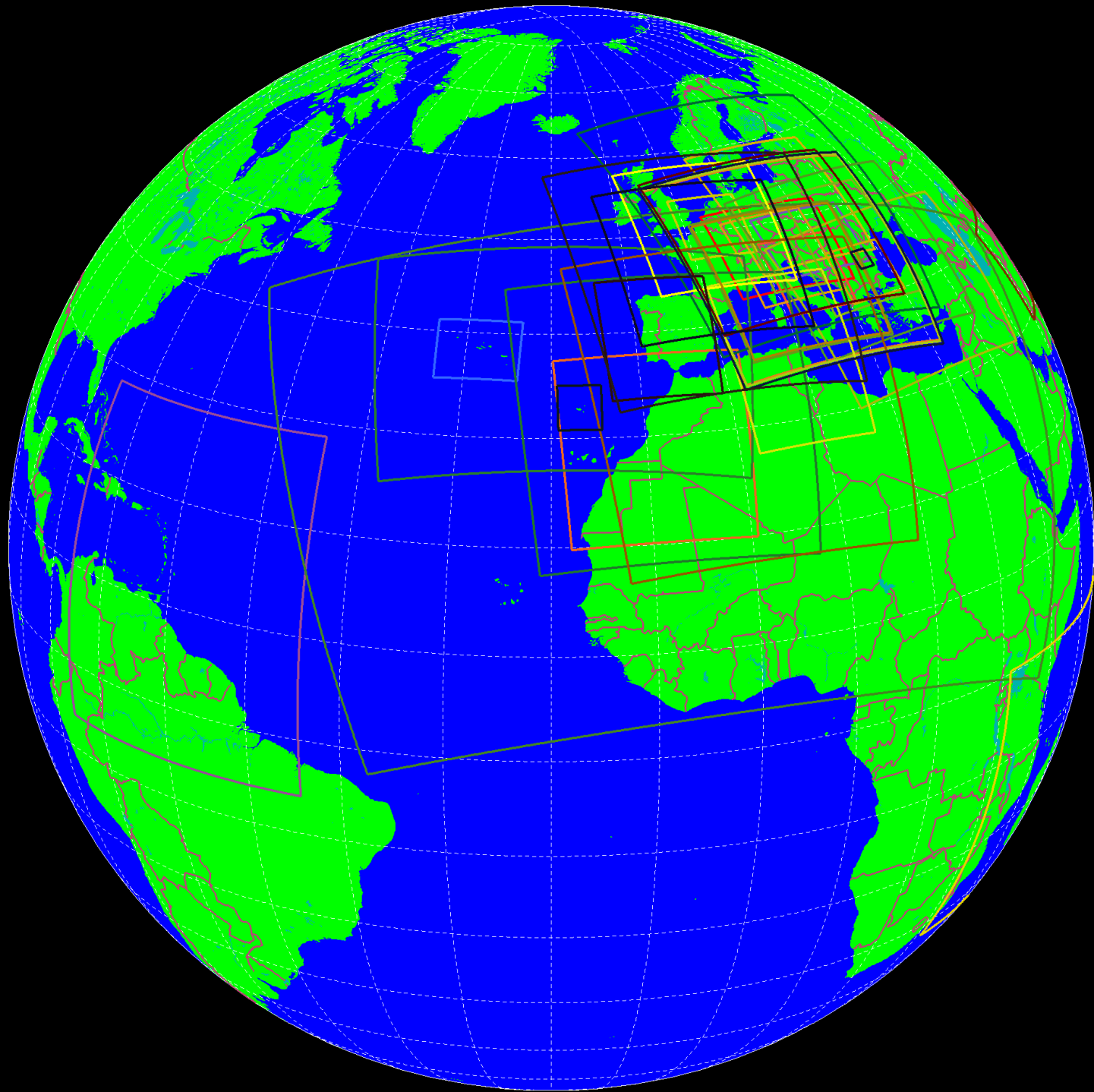
- ALADIN workshop/HIRLAM ASM (2015: Denmark)
- Several working week meetings (some together with HIRLAM)
- Visiting stays including phasings of new cycles in Toulouse
- Operational/technical coordination: ACNA
 - Coordinate the LTMs
 - Coordinate the local implementations of the “export versions”
- Facilitate extra NWP activities (data assimilation, EPS), in particular in the LACE consortium (cfr. talk of Yong)



“Seamless” code universe

	Reanalysis	Numerical Weather Prediction	Climate
<i>Global</i>	ERA-40 ERA-Int, ...	IFS ARPEGE	ARPEGE-clim, CNRM CMIP runs
<i>Meso scale</i>	Downscaling	ALADIN System	ALADIN-climate
		ALADIN	ENSEMBLES, CORDEX, ...
<i>Convection permitting</i>		ALARO AROME	ALARO-climate AROME-climate







Recognizing the capabilities and achievements of the NMHS belonging to Aladin and Hirnam consortia:

1. The NMHS present at the joint Aladin-Hirnam meeting (dec 2, 2014) share the same objective to jointly develop and maintain the best possible skilled limited area weather forecasting system, building on the developments of the IFS/Arpege global forecast system and on the Aladin and Hirnam limited area systems. This limited area system is defined as a set of data pre-processing, data assimilation, atmospheric model and postprocessing tools for producing the best possible operational mesoscale weather forecasts.

2. Aladin and Hirnam consortia will work together with the aim of forming one single consortium by the end of the 2016-2020 MoUs. To this aim, the following issues have to be resolved:

- code ownership (software IPR) : current situation and suitable evolutions. In particular advantages vs drawbacks of open source solutions should be assessed;
- data policy (access to model outputs) ; to this aim a map of the various current operational configurations of the limited area system should be produced and scenarios for data dissemination should be assessed;
- global picture of annual contribution of countries to the various types of activities (from fundamental research to code implementation);
- identification of common activities and specific activities (possibility of core and optional programs);
- branding (including suitable evolution of the name of the system).

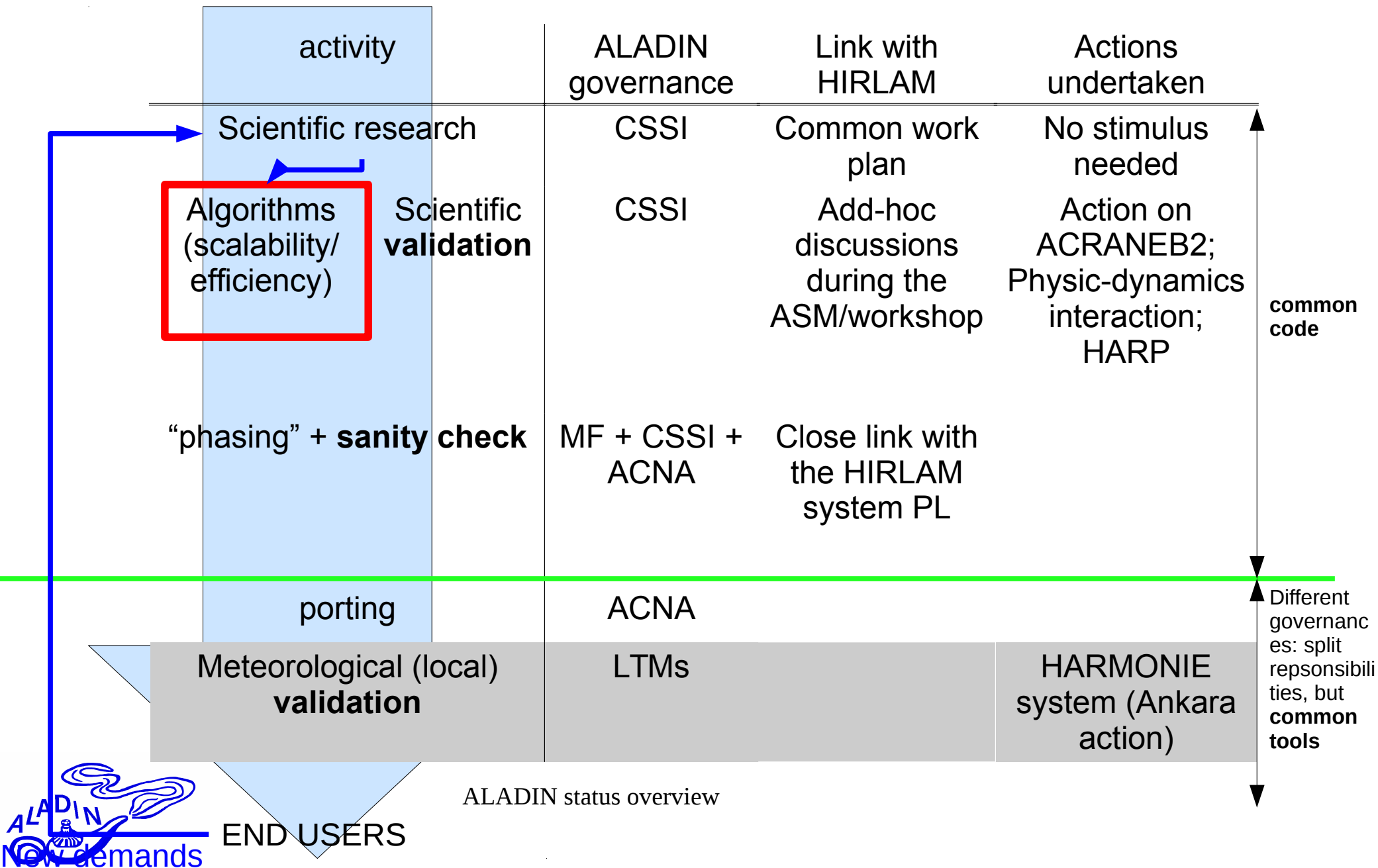
3. Human resources to support the work will be identified.

4. Both PM will report every six months on those issues to the consortia governing bodies.

5. Joint meeting of governing bodies of both consortia will be held at least once a year.



From science to operations summarized on 1 sheet



Novelty:

CMCs, *Canonical* Model Configurations

- v. A Canonical Model Configuration is a configuration of the ALADIN System for which resources are provided by the Members in order to (a) perform regular code updates, which includes the required scientific and technical validation according to the state of the art of the latest research and development, and (b) to provide the coordination and networking activities in order to install and run any canonical configuration at this state-of-the-art level by the ALADIN Consortium Members.



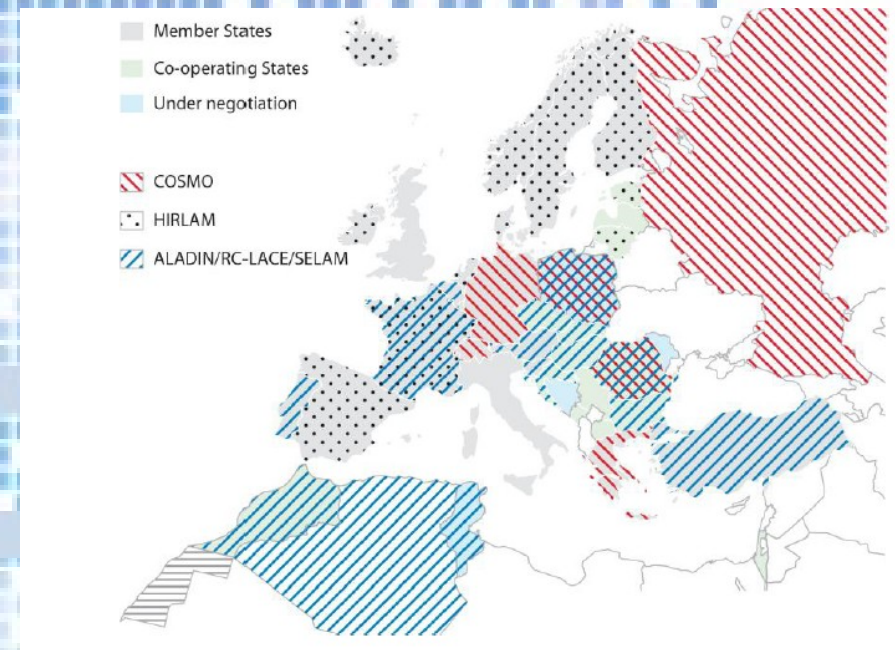
Forecasters meeting Ankara, 2014 conclusions

Forecasters need guidance to interpret high-resolution model output. This was a recurring problem during the discussions and emphasized by several forecasters. This related to the intrinsic stochastic nature of clouds and microphysics processes. It was also concluded that the human eye is not capable of interpreting a weather map in a probabilistic sense; i.e. it is not possible to interpret spatial variation in forecast patterns as probabilities over a wider area.



ESCAPE

- ESCAPE will develop world-class, extreme-scale computing capabilities for European operational numerical weather prediction (NWP) and future climate models.
- Led by ECMWF
- The aim was/is to involve the LAM community.
- Kick off meeting last week (1-2/10)



In memory of Jean-François



A short *tribute* by two papers on the core of “convection-permitting” modeling

- **Pea07**: Piriou, J.-M., Redelsperger, J.-L., Geleyn, J.-F., Lafore, J.-P. Guichard, F., 2007: An Approach for Convective Parameterization with Memory: Separating Microphysics and Transport in Grid-Scale Equations. J. Atmos. Phys, 64, 4127-4139
- **G07**: Gerard, L., 2007: An integrated package for subgrid convection, clouds and precipitation compatible with meso-gamma scales. QRMS, 133, 711-730.
- **Gea09**: Gerard, L., Piriou, J.-M., Brožková, Geleyn, J.-F., Banciu, D., 2009: Cloud and Precipitation Parameterization in a Meso-Gamma-Scale Operational Weather Prediction Model. Mon. Wea. Rev., 137, 3960-3977



3MT

Cloud
System
Resolving
Model
(CSRM)

$$\left\{ \begin{array}{l} \frac{\partial q}{\partial t} = T_q - C + E_C + E_P - (\mathbf{u} \cdot \nabla) q \\ \frac{\partial s}{\partial t} = T_s + R + L(C - E_C - E_P) + H - (\mathbf{u} \cdot \nabla) s \\ \frac{\partial u}{\partial t} = \dot{u}_p - (\mathbf{u} \cdot \nabla) u \\ \frac{\partial v}{\partial t} = \dot{v}_p - (\mathbf{u} \cdot \nabla) v \end{array} \right. ,$$

Arakawa-
Schubert
(QE)

$$\left\{ \begin{array}{l} \frac{\partial \sigma}{\partial t} = -D + E - \frac{\partial \omega^*}{\partial p} \quad (\text{mass}) \\ \frac{\partial \sigma q_c}{\partial t} = -D q_c + E \bar{q} - \frac{\partial \omega^* q_c}{\partial p} - C \quad (\text{water vapor}) \\ \frac{\partial \sigma s_c}{\partial t} = -D s_c + E \bar{s} - \frac{\partial \omega^* s_c}{\partial p} + LC \quad (\text{heat}), \end{array} \right.$$



3MT

Cloud System Resolving Model (CSRM)

$$\left\{ \begin{array}{l} \frac{\partial q}{\partial t} = T_q - C + E_C + E_P - (\mathbf{u} \cdot \nabla)q \\ \frac{\partial s}{\partial t} = T_s + R + L(C - E_C - E_P) + H - (\mathbf{u} \cdot \nabla)s \\ \frac{\partial u}{\partial t} = \dots - (\mathbf{u} \cdot \nabla)u \\ \frac{\partial v}{\partial t} = \dots - (\mathbf{u} \cdot \nabla)v \end{array} \right.$$

Budget formulations

Arakawa-Schubert (QE)

$$\left\{ \begin{array}{l} 0 = -D + E - \frac{\partial \omega^*}{\partial p} \quad (\text{mass}) \\ 0 = -Dq_c + E\bar{q} - \frac{\partial \omega^* q_c}{\partial p} + C \quad (\text{water vapor}) \\ 0 = -Ds_c + E\bar{s} - \frac{\partial \omega^* s_c}{\partial p} + LC \quad (\text{heat}), \end{array} \right.$$

DETRAINMENT TO THE NEIGHBOURING GRIDBOX?



3MT

Cloud System Resolving Model (CSRM)

$$\left\{ \begin{array}{l} \frac{\partial q}{\partial t} = T_q - \boxed{C + E_C + E_P} - (\mathbf{u} \cdot \nabla)q \\ \frac{\partial s}{\partial t} = T_s + R + L \boxed{(C - E_C - E_P) + H} - (\mathbf{u} \cdot \nabla)s \\ \frac{\partial u}{\partial t} = \boxed{\dot{u}_p} - (\mathbf{u} \cdot \nabla)u \\ \frac{\partial v}{\partial t} = \boxed{\dot{v}_p} - (\mathbf{u} \cdot \nabla)v \end{array} \right.,$$

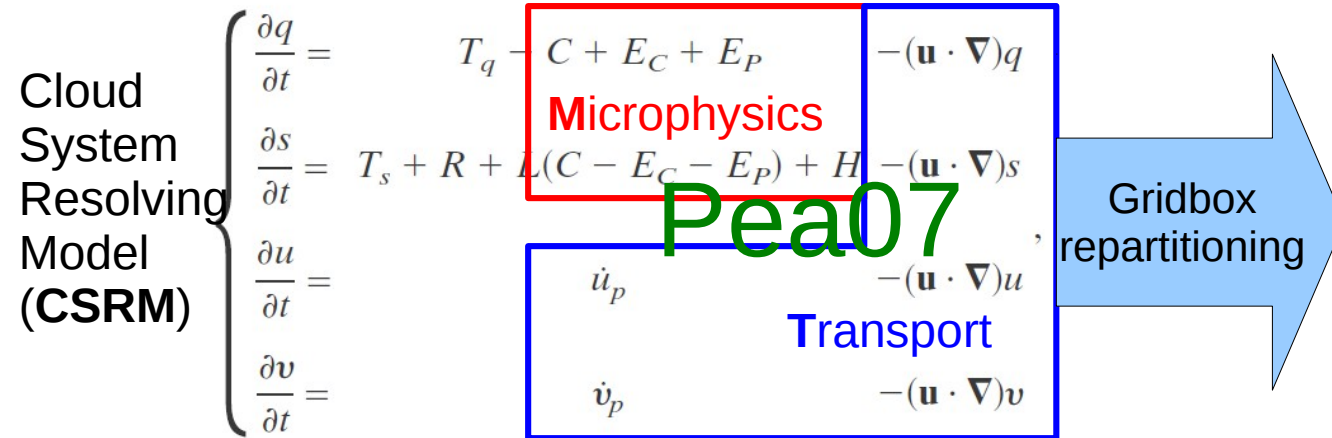
Microphysics
Pea07
Transport

~~$$\left\{ \begin{array}{l} \frac{\partial \sigma}{\partial t} = -D + E - \frac{\partial \omega^*}{\partial p} \quad (\text{mass}) \\ \frac{\partial \sigma q_c}{\partial t} = -D q_c + E \bar{q} - \frac{\partial \omega^* q_c}{\partial p} \quad (\text{water vapor}) \\ \frac{\partial \sigma s_c}{\partial t} = -D s_c + E s - \frac{\partial \omega^* s_c}{\partial p} + LC \quad (\text{heat}), \end{array} \right.$$~~

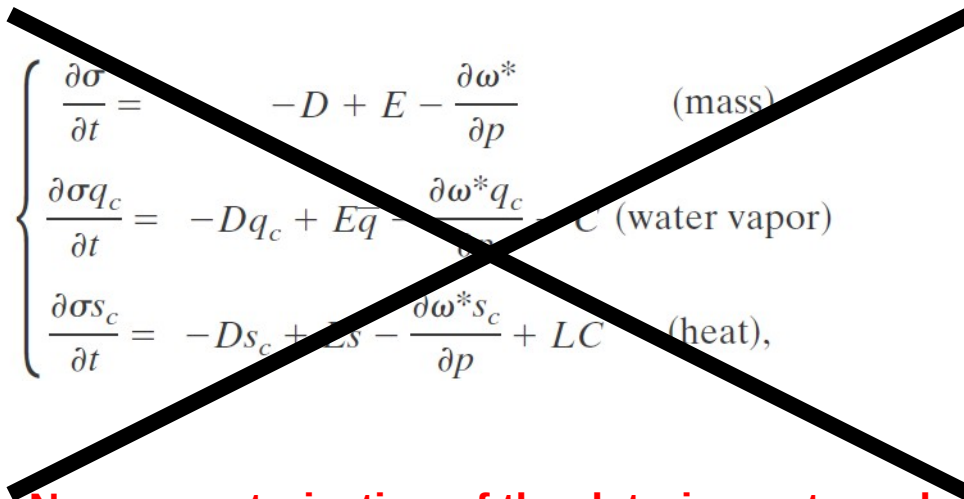
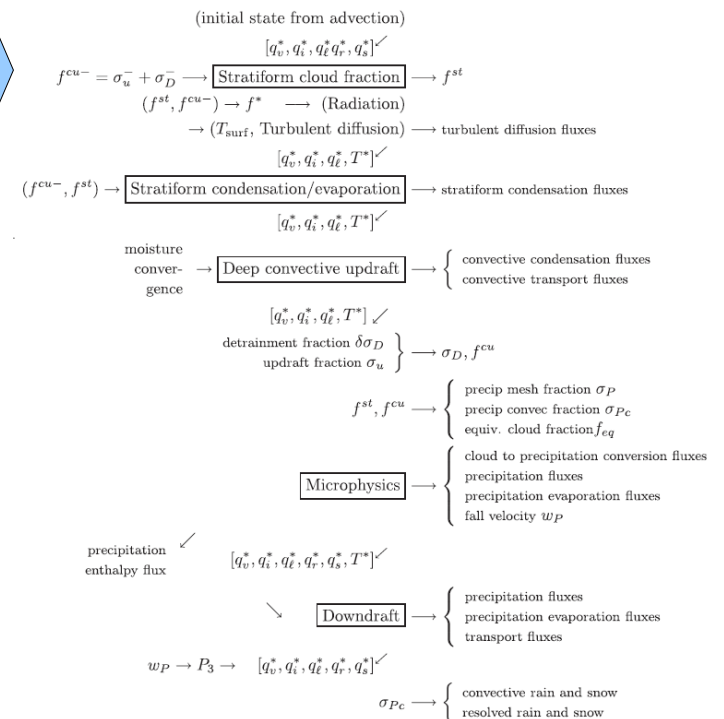


3MT

G07-> Gea09



+ cascade: Modular



No parameterization of the detrainment needed: it is done by the dynamics: Multiscale



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Combining the insights and promoting of the works of his colleagues and understanding the deep implications of it is was a really unique quality of Jean-François.



Thank you for your attention

