

New developments in GLAMEPS and HarmonEPS

Inger-Lise Frogner

and the HIRLAM EPS and predictability team, and RMI for GLAMEPS

Belgrade, October 2015

GLAMEPS (version 2, since October 2013)

Operational since 2011

Multi-model, pan-European EPS

48 +4 ensemble members;

4 sub-ensembles:

- Two HIRLAM ensembles with 3D-Var for controls

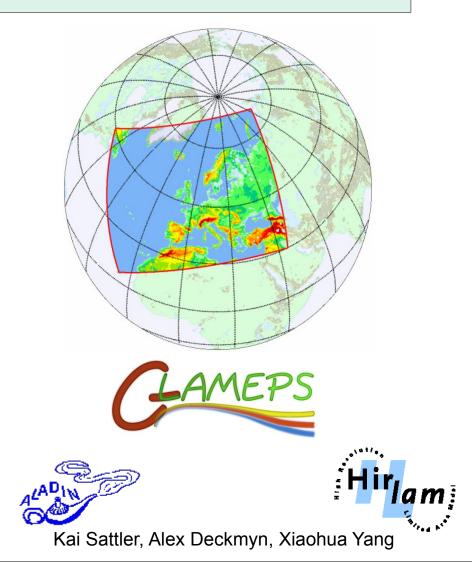
- Two Alaro ensembles (downscaling) with SURFEX or ISBA for surface

- lagged

Nested in IFS ENS

- Forecast range: 54h
- Four times a day (00, 06, 12 and 18 UTC)
- All members have their own surface assimilation cycles
- Stochastic physics in HIRLAM
- Perturbed surface observations in HIRLAM
- ~8 km resolution

Runs as Time-Critical Facility at ECMWF



GLAMEPS (version 3, tests ongoing)

Suggested updates:

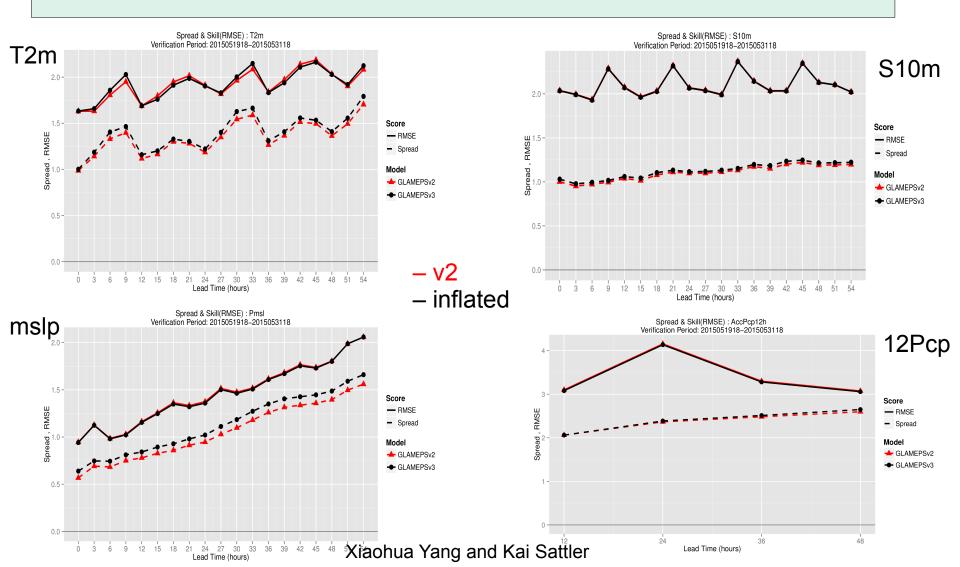
- Inflate the initial perturbations coming from IFS ENS
- Increase resolution to ~5 km
- Include CAPE SVs
- Implementing intended changes for ALARO:
- implement perturbation in horizontal diffusion
- consider adding inflation factor to ALARO boundary



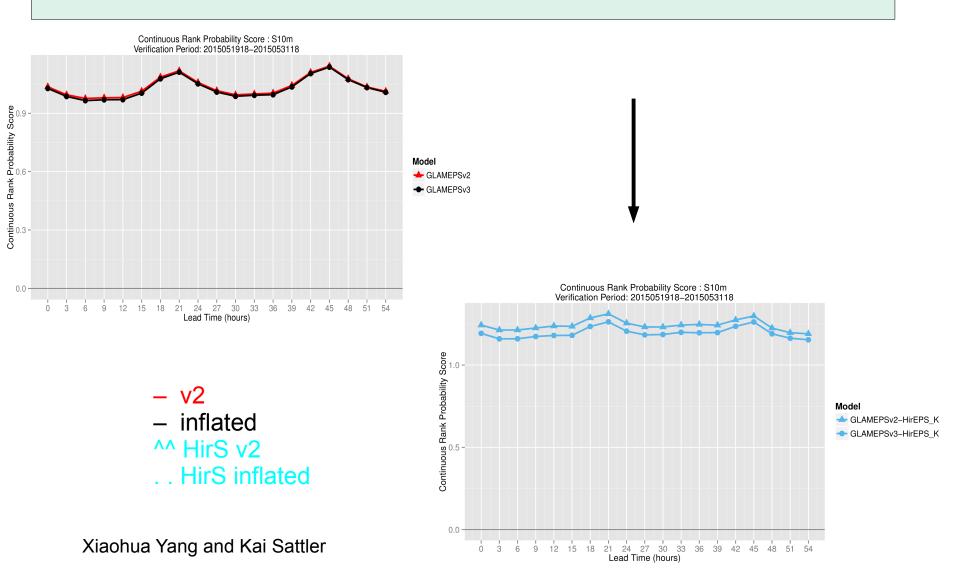


Kai Sattler, Alex Deckmyn, Xiaohua Yang

Inflation of initial perturbations in HIRLAM sub-ensembles – spread/skill



Inflation of initial perturbations in HIRLAM sub-ensembles – CRPS



CAPE-SVs in HIRLAM sub-ensembles

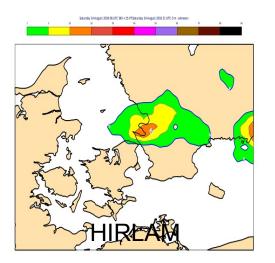
Sibbo van der Veen

Flooding Copenhagen, August 14, 2010 (06+15) - (06+12)

Η

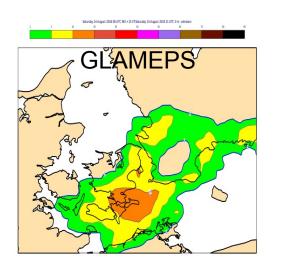
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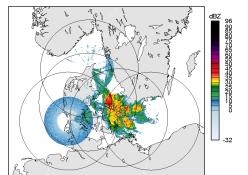
18 – 21 UTC



Probability exceeding 10mm between 18-21 UTC

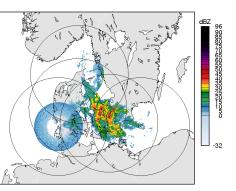
Defaulf





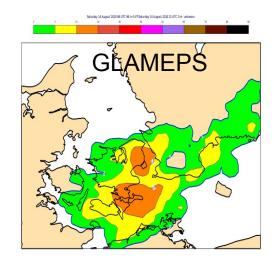
Composite reflectivity 201008141935

Н





With CAPE-SV

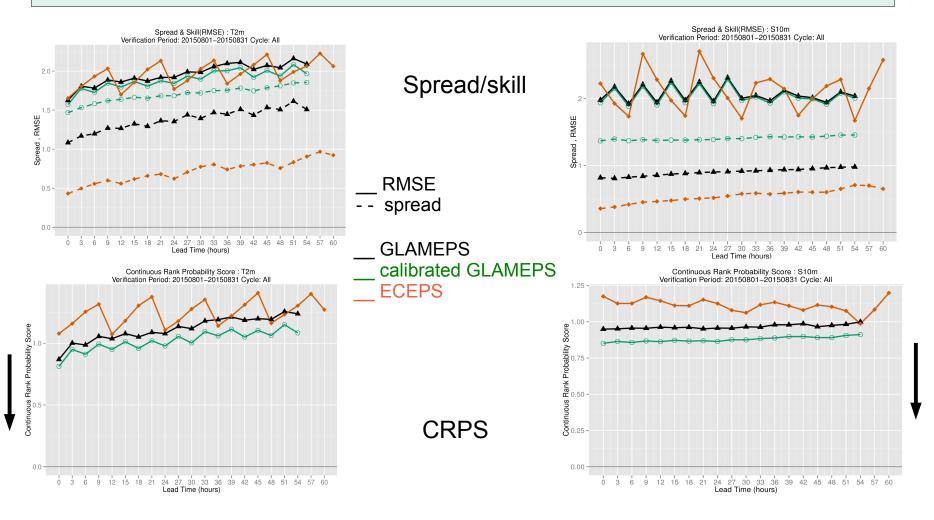


• Goal: Calibration for whole grid, not only station points

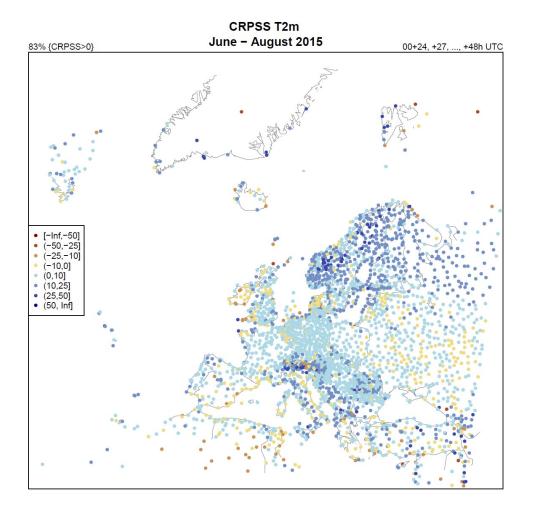
Statistical calibration

Regression with Box-Cox t-distribution

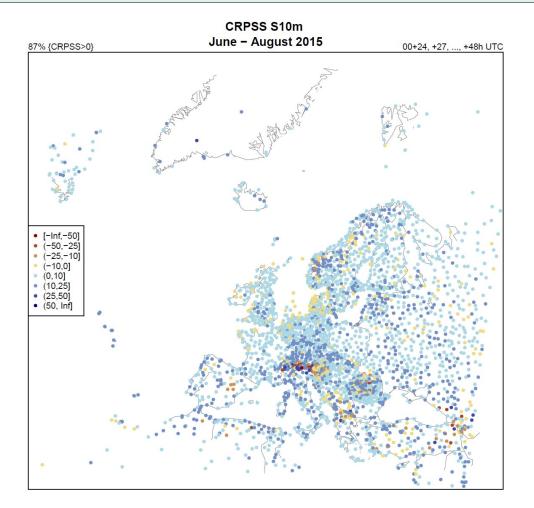
- parameters depending on ensemble statistics and orographical information
- currently applied to temperature 2m and wind speed 10m
- one regression model for the whole domain and each lead time
- training period of 42 days/20.000 cases
- regression models updated once a week



John Bjørnar Bremnes, Thomas Nipen, Maurice Schmeits, Juha Kilpinen, Karoliina Hamalainen



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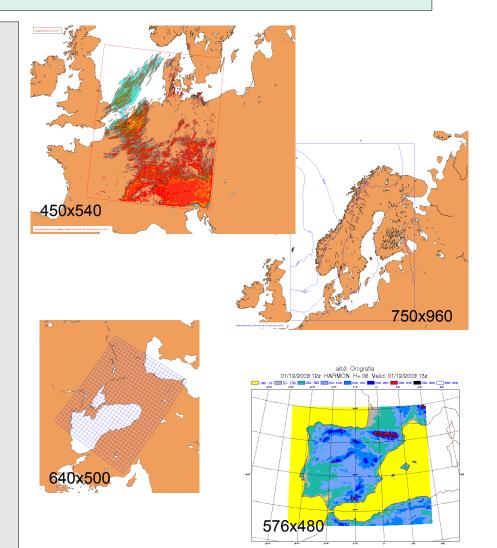
Experimental – first operational versions expected first half 2016

For sub-European areas

- Configurations vary, but typically between 10+1 and 20+2 members
- Arome and Alaro
- 2.5 km
- 3D-Var
- SURFEX
- +36h
- All members have their own surface assimilation cycles

Nested in IFS ENS or IFS high res.

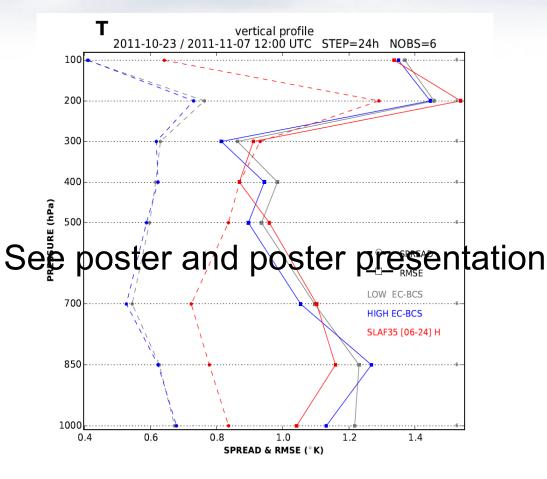
Experiments with perturbations in initial conditions, lateral boundary conditions, model physics and surface ongoing.



LBC

- Default is to use IFS ENS
- Model levels not stored for IFS ENS, makes it harder to do experiments
- Tests with Scaled Lagged Average Forecasts (SLAF)
- Tests with Random Field Perturbations

Results Prob – Spread/Skill Upper Air H+24



GOBIERNO DE ESPAÑA MINISTERIO DE AGRICULTURA, ALIMENTACIÓN

MEDIO AMBIENTE

Random Field Perturbation*

- Initial condition perturbation $z_m(0)=an_{ctl} + \alpha[r_1(0)-r_2(0)], \quad z_{m+1}(0)=an_{ctl} - \alpha[r_1(0)-r_2(0)]$
- Lateral boundary condition perturbation $z_m(t)=x_{ctl}(t) + \alpha[r_1(t)-r_2(t)], \quad z_{m+1}(t)=x_{ctl}(t) - \alpha[r_1(t)-r_2(t)]$

anctl = analysis, control run

x_{ctl}(t) = interpolated hi-res EC-field

 $r_j(t)$ = interpolated hi-res EC-field from random date (similar time of year and same time of day as control); u, v, T, q, p_s

 α = scaling constant that determines perturbation magnitude

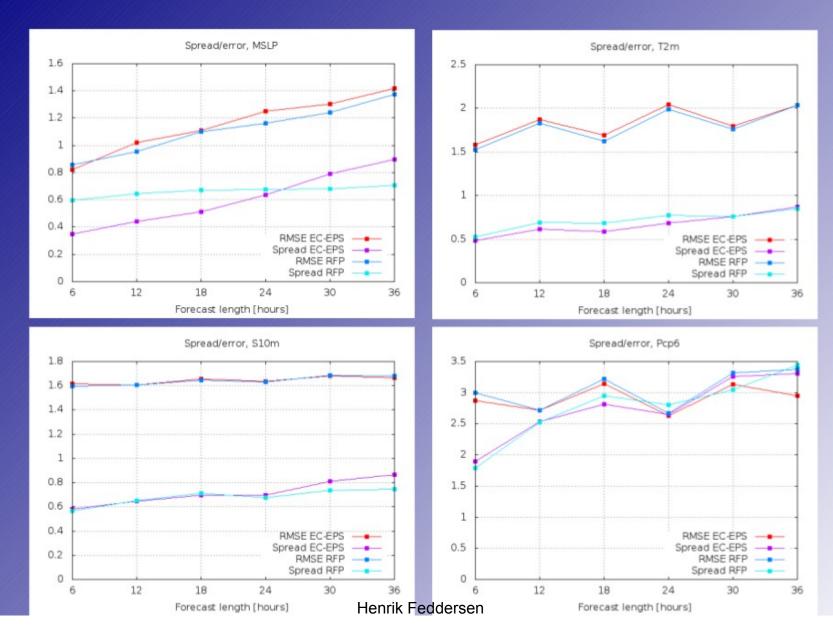
*Magnusson et al., 2009: "Flow-dependent versus flow-independent initial perturbations for ensemble prediction"

Henrik Feddersen

Scaling the perturbations

- Choose α such that the total energy of the random field initial perturbations matches that of the default initial perturbations
- Total energy norm measures distance between two ensemble members
- NB. Lateral EC-EPS boundaries diverge from control run during forecast; random field boundaries are independent of control run and will not contribute (much) to ensemble spread

Standard verification

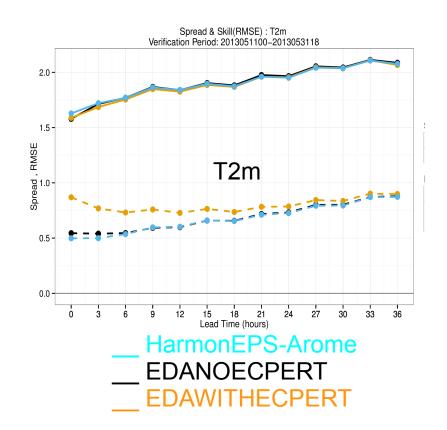


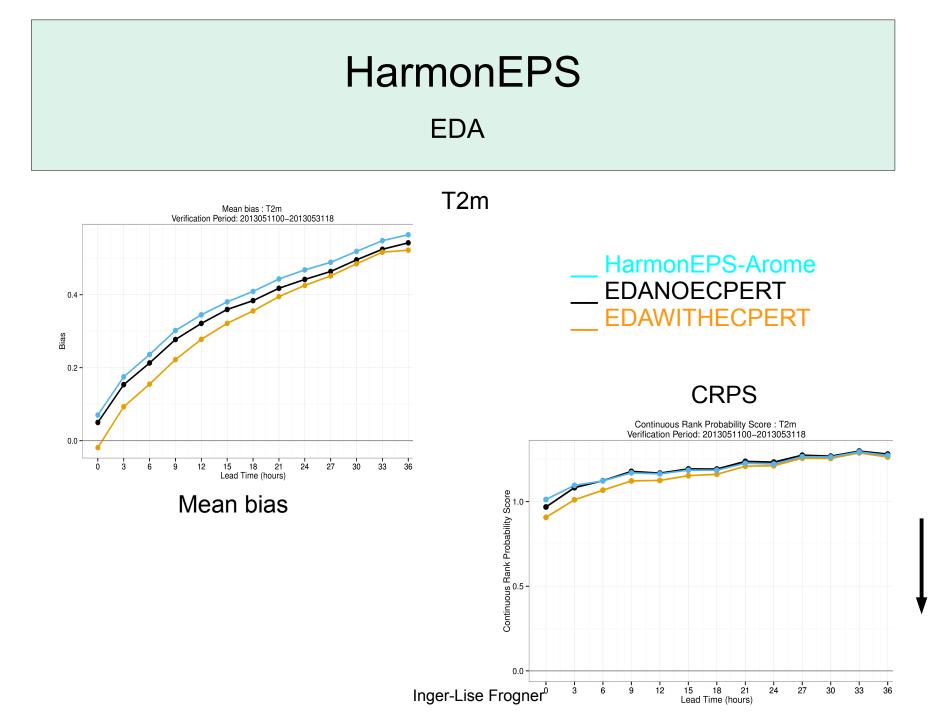
Initial perturbations

- Default is to use IFS ENS
- LETKF under development (Pau Escriba, see Jelena's DA talk)
- EDA with 3D-Var

EDA

- 10 + 1 member Arome EPS
- 21 days in May 2013
- HarmonEPS-Arome: default setup with 3D-Var for control and large scale perturbations from IFS ENS added to this analysis for each member
- EDANOECPERT: Each member running their own analysis, with perturbed observations
- EDAWITHECPERT: same as above, but also added large scale perturbations from IFS ENS

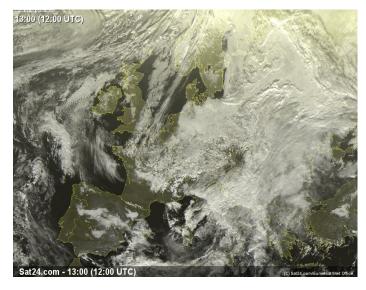




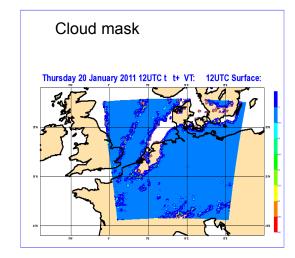
Model error and cloud initialisation

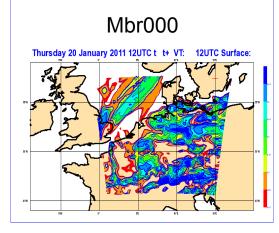
- Default is to use multi-physics with Arome and Alaro
- SPPT (Alfons Callado, implementation ongoing)
- Multi-physics the "LAEF-way" experimentation to start (Bjorn Stensen)
- Cellular Automata (CA) (Lisa Bengtsson, presented last year)
- Stochastic perturbations in parameterizations / processes (Sibbo van der Veen, Lisa Bengtsson)
- Humidity perturbations and MSG cloud mask (Sibbo van der Veen)

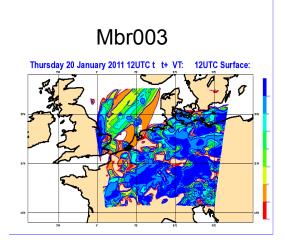
Example of initial clouds in different members (control ensemble)



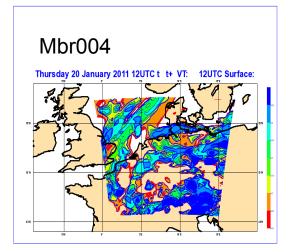
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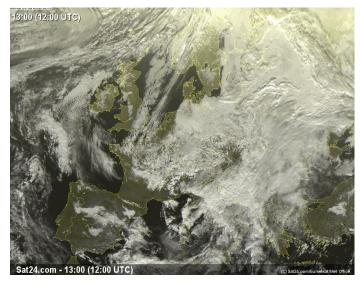




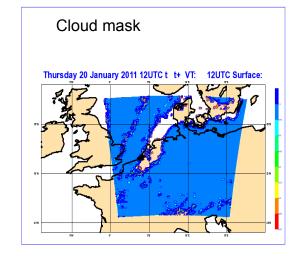
Sibbo van der Veen

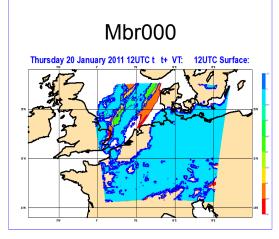


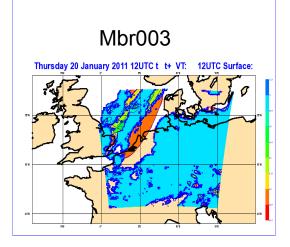
Example of initial clouds in different members (initialization + humidity pert.)



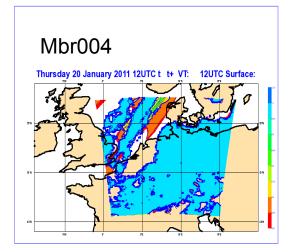
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Sibbo van der Veen



Surface uncertainty

- Perturb surface parameters, like soil moisture, albedo, SST, ...) (Work ongoing, Andrew Singleton)
- Perturb surface physics: study perturbations in momentum, heat and moisture flux parameterizations. (Work ongoing, and presented last year, Andrew Singleton)

Post-processing and HARP EPS developments

- HARP:
 - New scores and parameters to be included
 - Work on new formulation of spread/skill and deeper understanding of the practice of centering the ensemble round control (Åke Johansson)
- Post processing
 - Calibration (Thomas Nipen)
 - Neighborhood (Andrew Singleton)

How to determine neighborhood size?

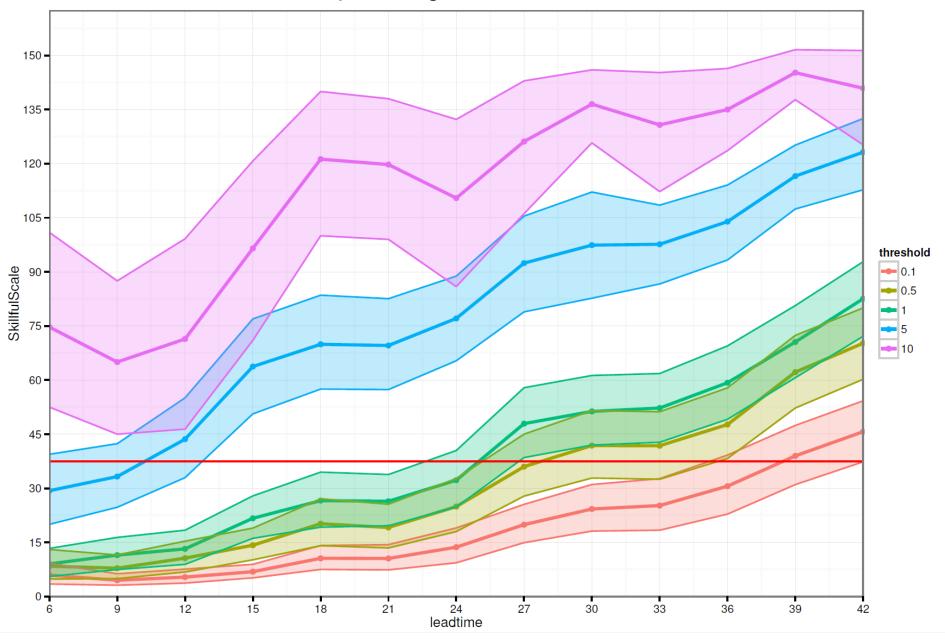
2. Adaptive neighbourhood size

Based on fractions skill score (FSS) between members

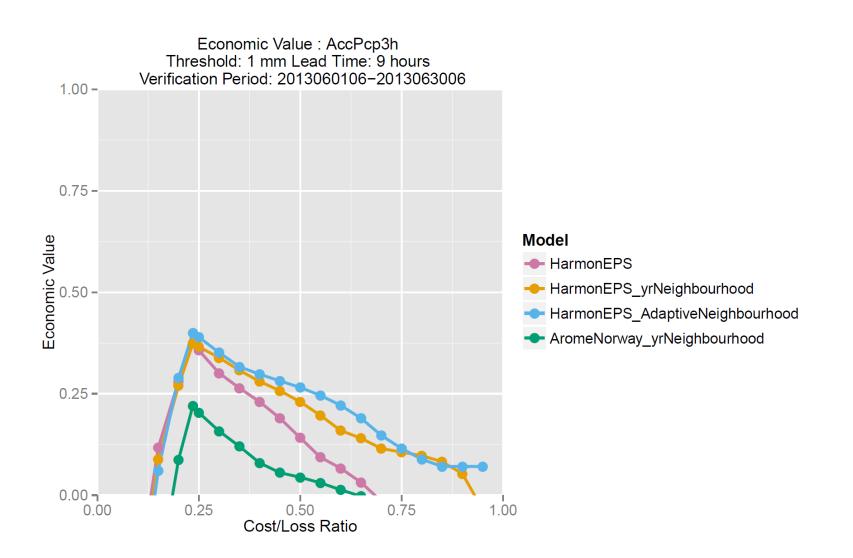
For each lead time and threshold:

- 1. Compute FSS for each member against all other members
- 2. Compute FSS_{uniform} for each member
- 3. Spatial scale at which $FSS > FSS_{uniform}$ is spatial scale for member pair
- 4. Mean of spatial scales for all member pairs is neighbourhood size (don't use maximum as gives too much weight to outliers).

Adaptive neighborhood size



Andrew Singleton



Thank you