

Swiss Confederation

# Seamless nowcasting INCA Open issues Pierre Eckert Matteo Buzzi, Marco Sassi, Guido della Bruna, Marco Gaia



## Nowcasting, various approaches

Nowcasting and very short range forecasting

#### COMMISSION FOR BASIC SYSTEMS

## EXPERT MEETING ON VERY SHORT-RANGE FORECASTING (EM-VSRF)

GENEVA, SWITZERLAND, 21-23 MARCH 2011



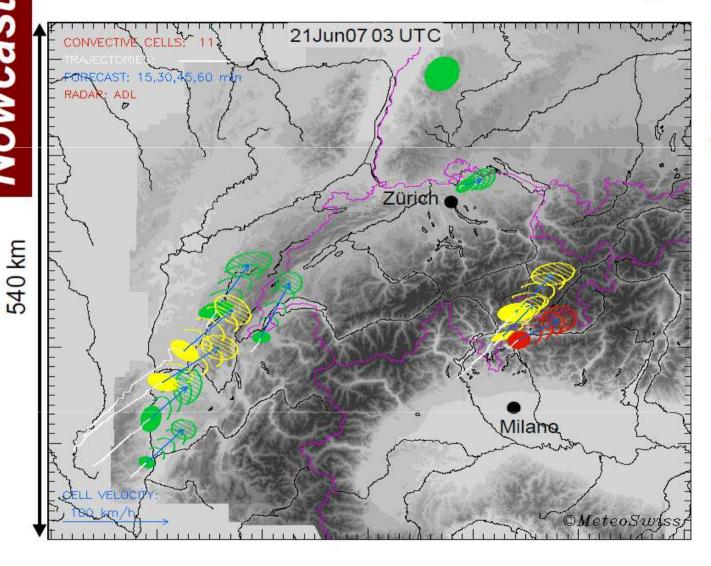
#### Table of possible blending approaches with model and observational data combinations for very short-range forecasting

Туре	Description	Time range, availability	Examples	Documents, web sites	Remarks
Observations only	Object recognition, extrapolation (radar, satellite), data fusion	Nowcasting, immediate	TRT, RDT, gridded observations		Can be centrally produced (satellites)
Observations + model analysis	Indices	Nowcasting, immediate	GII, RII		
Superposition of observations and model Climatological Postrocessing	simple accumulations from rain gauges and radar Comparison of model analysis or forecasts with	SRF, immediate  SRF, available at same time as model output	Sum of rainfall until now + model from now Regressions, discriminance, neural		Simple but far to be available  Non linear methods can be targeted on high
· comessessing	local observations on climatological basis		networks, boosting (choice of relevant predictors),		impact weather
Model diagnostics	Recognition of synoptic features on NWP analysis and forecasts	SRF, available at same time as model output	Troughs, dry zones, jet streams, large scale destabilization, synoptic classification		Synoptic recognition of high impact weather is possible
Adaptive postprocessing	Comparison of model analysis or forecasts with local observations based on recent observations and	SRF, available at same time as model output	UMOS, Kalman filtering		Takes into account model changes. History usually too short to deal with rare events
Observation – model blending	Observations at initial state, model after a few hours	Nowcasting, SRF. Can be immediate if older model is used	INCA, Scribe module		
observations into specific model	provided by NWP model, supplementary local data used for specific model	Nowcasting, SRF	1d models (fog, road state), 2d surface models, hydrological models		
the help of observations	ensemble members with	SRF	Heuristic?		
Assimilation of asynoptic observations	Assimilation of radar, GPS, profiler, satellite data into NWP model	SRF	3dVar, 4dVar, Latent heat nudging		Expensive

#### ♥ TRT

- Convective cells
- Pattern recognition and characterization (cloud top, VIL, lightning activity,...)
- Extrapolation to 60 minutes
- Possibility to diagnose stage of maturity of TS

#### Thunderstorm nowcasting



#### Legend

Solid: present position Hatched: 1 hour forecast Blue vector: cell velocity White line: trajectory

Cell severity ranking:

**WEAK** 

MODERATE

SEVERE

#### **VERY SEVERE**

based on vertically integrated liquid water, 45 dBZ echo top, max dBZ and area > 55dBZ

TRT by A Hering

#### ♥ TRT

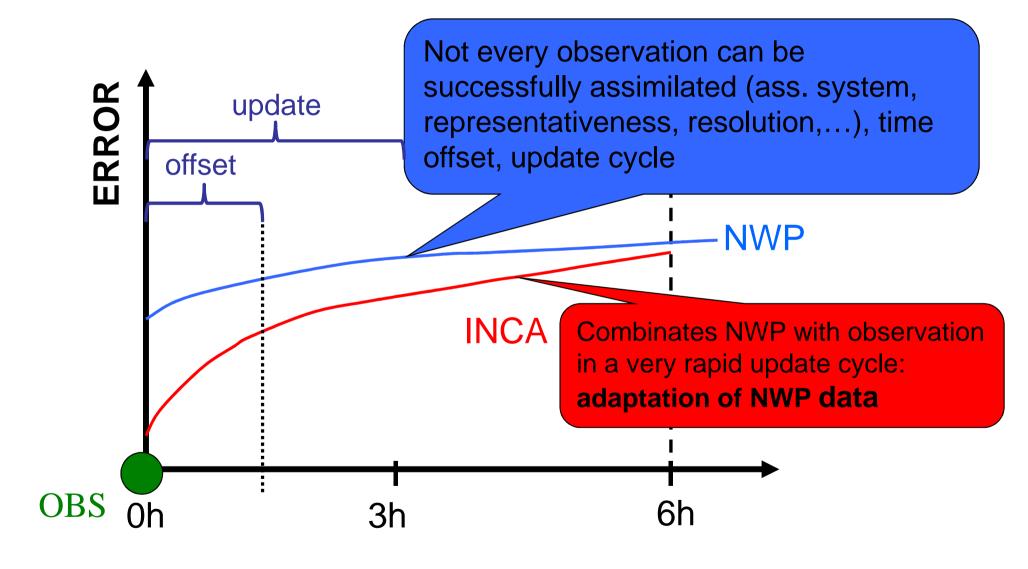
- Is used with some success
- Automated thunderstorm warnings per location
- Not able to diagnose onset of TS
- Extrapolation has limits over complex topography
- Could be better by using NWP winds (...???...)



- Integrated Nowcasting through Comprehensive Analysis
- Analysis, extrapolation and blending system for various parameters
- Different methods for each parameter
- Developed with / adapted from ZAMG
- Recent inclusion of COSMO-1



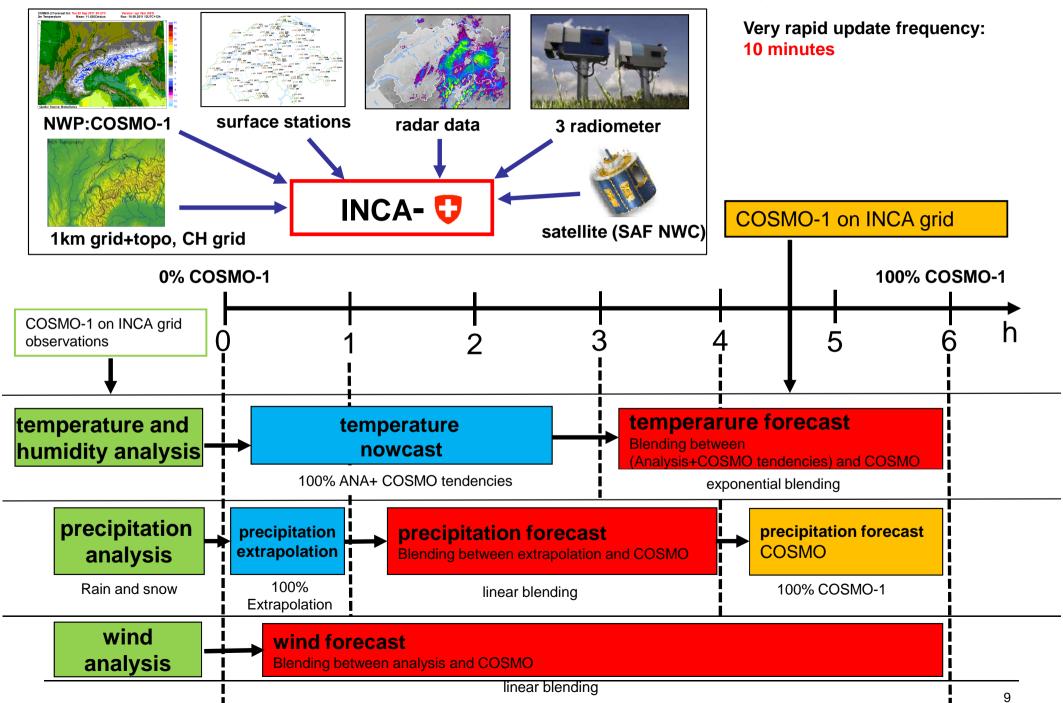
### Motivation: nowcasting window



**NEEDS**: very accurate, high frequency update

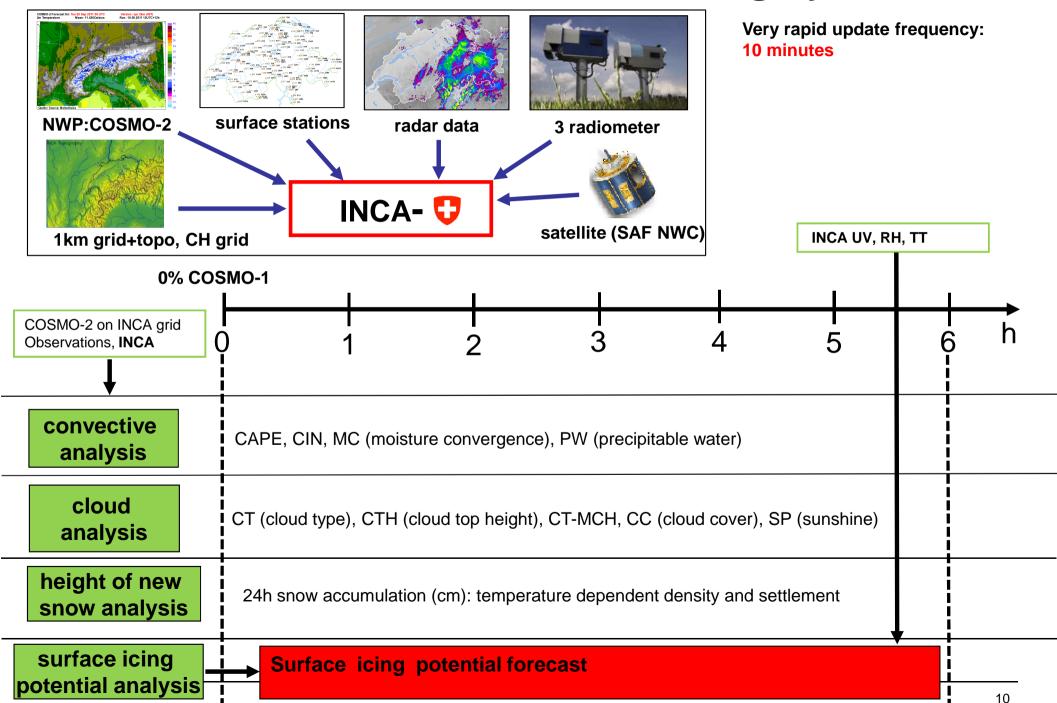
#### U

#### Overview: seamless nowcasting system



#### O

### Overview: seamless nowcasting system 2





## Temperature and humidity analysis

COSMO-1, model levels (80-13)

SYNOP, SMN, NABEL, KANT, MM, Pseudosoundings



First guess @ INCA levels

interpolation

Horizontal resolution: 1.1 km ⇒ 1 km

Vertical resolution: 100 m vertical up to 4500 m 500m from 4500 to 11000m 3D ANALYSIS Surface Analysis

temperature, specific humidity, (snowfall line, zero degree level)

$$T_{i,j,m(z)} = T_{i,j,m(z)}^{COSMO} + \Delta T_{i,j,m(z),k}$$

$$T2M_{i,j} = T2M_{i,j}^{COSMO} + \Delta T_{i,j}^{SL}$$

$$TTTD DU 70.70 (4h.40 min)$$

TT,TD,RH,Z0,ZS (1h,10min)

Temperature, humidity, zero degree level, snowfall line

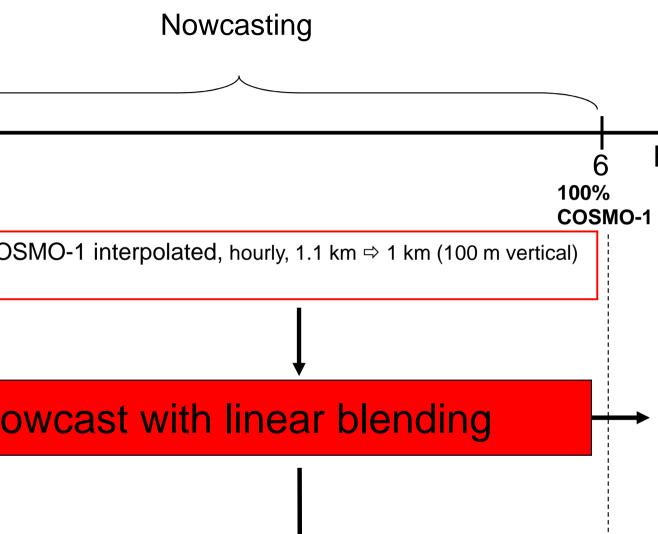


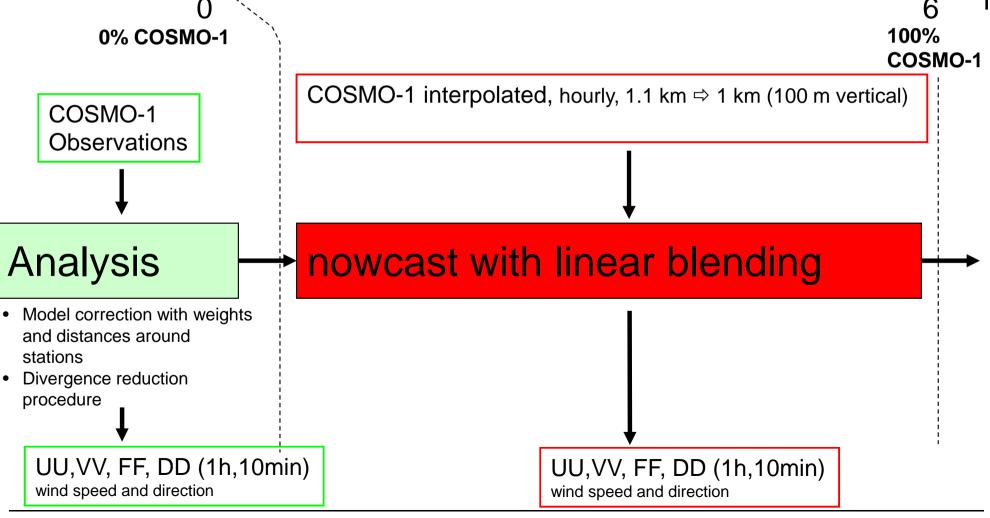
## Temperature and humidity forecast

COSMO-1, model levels (80-13), hourly, 1.1 km ⇒ 1 km (100 m vertical) 100% ANA + tendency 100% COSMO-1 0% COSMO-1 temperature temperarure forecast nowcast Blending between 100% ANA+ COSMO tendencies (Analysis+COSMO tendencies) and COSMO TT,TD,RH,Z0,ZS (1h,10min) TT,TD,RH,Z0,ZS (1h,10min) Temperature, humidity, zero degree level, snowfall line Temperature, humidity, zero degree level, snowfall line



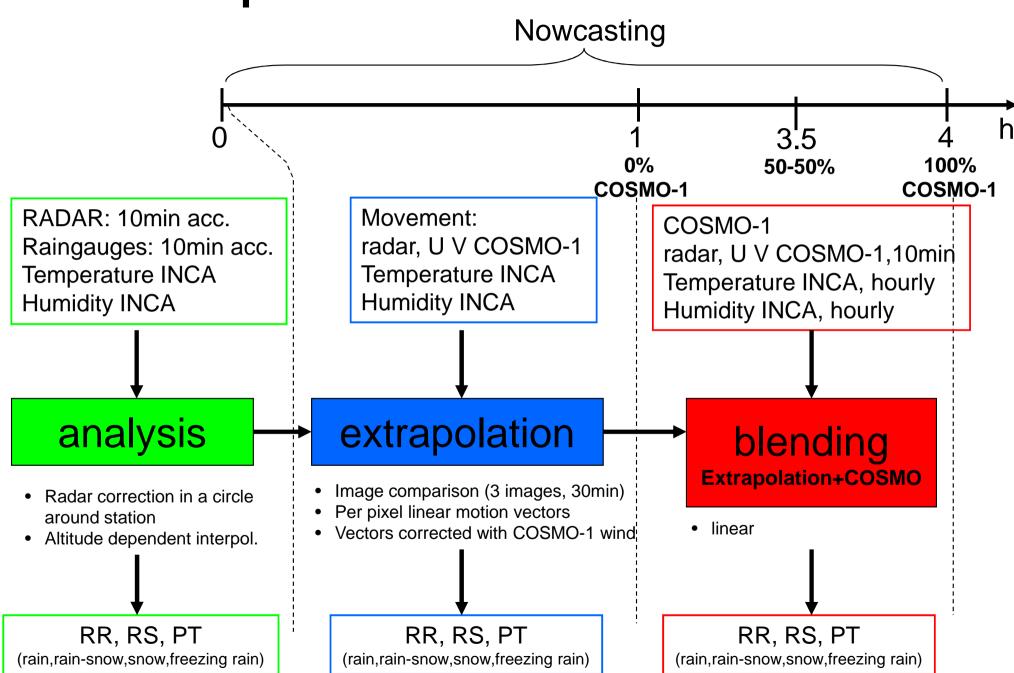
#### 10 m wind nowcast





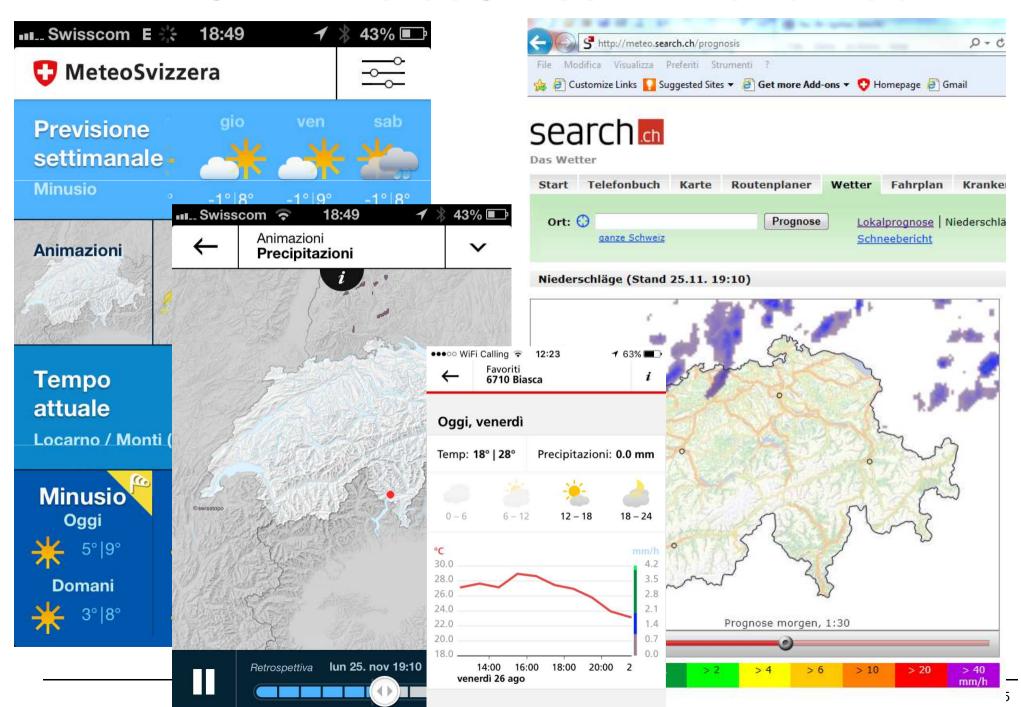


#### **Precipitation nowcast**



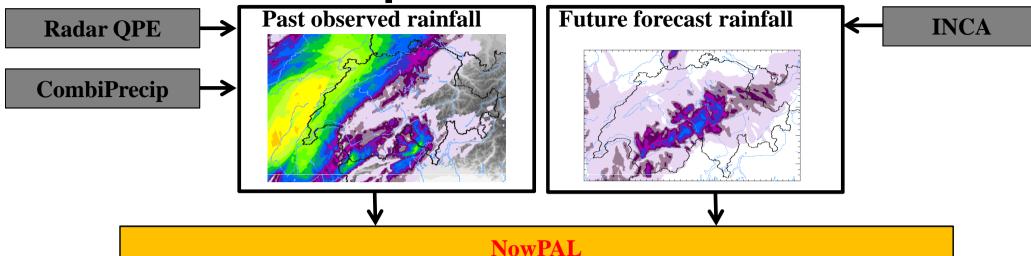


#### INCA in MeteoSwiss APP and web

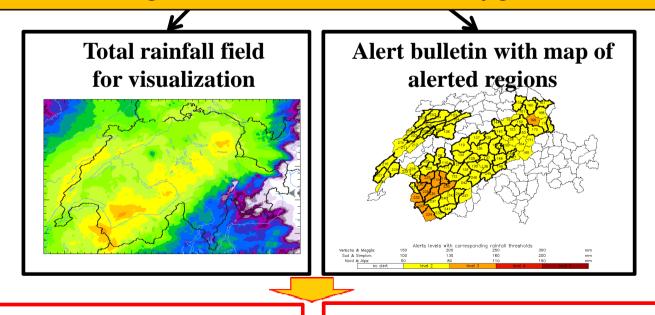




## **INCA** as input for NOWPAL



Input products, temporal accumulations, regions, alert thresholds, latency time and regional evaluation statistics are configurable.

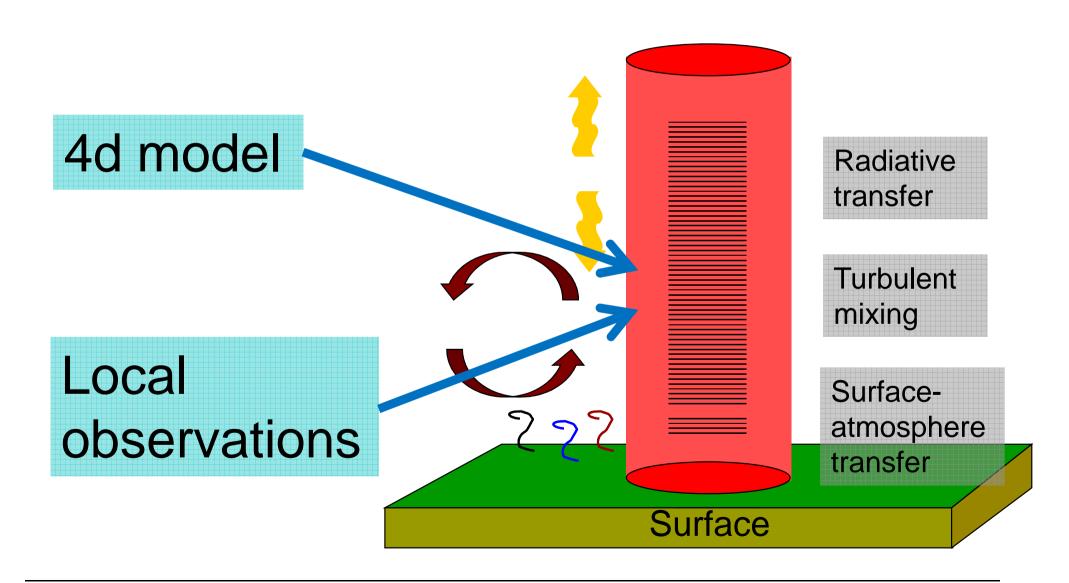


**Forecasters for official warnings** 

Specific customers (SMS, e-mail, xml)

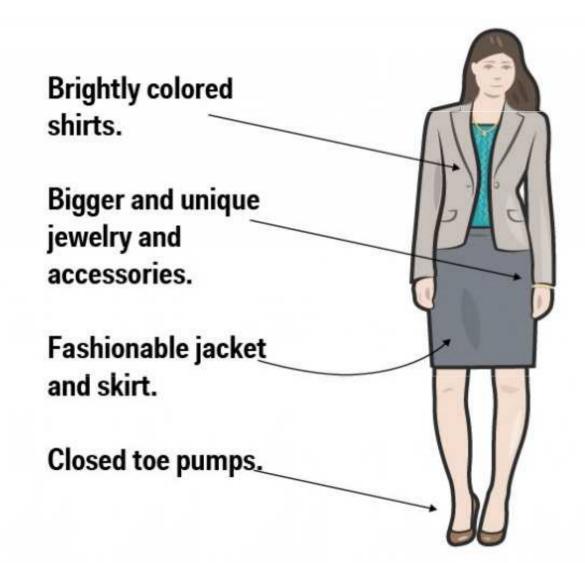
## **Q**

## Dynamical postprocessing 1d model (fog)



#### **O**

## Dynamical postprocessing 1d model (fog)





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Adaptive postprocessing	Comparison of model analysis or forecasts with local observations based on recent observations and	SRF, available at same time as model output	UMOS, Kalman filtering  Calibration	Takes into account model changes. History usually too short to deal with rare events	
Observation – model blending	Observations at initial state, model after a few hours	Nowcasting, SRF. Can be immediate if older model is used	INCA, Scribe module	IVS ?	
observations into specific model	provided by NWP model, supplementary local data used for specific model	Nowcasting, SRF	1d models (fog, road state), 2d surface models, hydrological models	Apart hydrology, no striking success (?)	
Choice of model with the help of observations	ensemble members with	SRF	Heuristic?	Striking success (:)	
Assimilation of asynoptic observations	Assimilation of radar, GPS, profiler, satellite data into NWP model	+EnDA, 2025	3dVar, 4dVar, Latent heat nudging	Expensive	

#### Discussion

- Rapid update analysis seems in view
  - Every hour
  - Available xy minutes after observations (x > 0)
- Integration of more frequent observations: radar, satellites, visibility, ceiling, lightning, wind profiler,...
- Parameter specific methods do not necessarily have coherence

Strong bridge between models and postprocessing

## Grazie per l'attenzione