

Neighborhood-based CRPS

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- Presentation of the neighborhood and CRPS
- Inclusion of the neighborhood in the CRPS
- Comparison of probabilistic and deterministic QPF
- Conclusions







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Classical Tables of contingency



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Reward forecasts of events spatially slightly misplaced



Classical Tables of contingency

FSS (Robert and Lean 2008) and BSS (Amodei and Stein 2009)







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- **ARPEGE** : hydrostatic global model ; 5 km over France
- PEARP : 35 hydrostatic global forecasts ; 7,5 km over France ; Singular vectors + EDA and 10 physics
- AROME : non-hydrostatic LAM nested in ARPEGE ; 1.3 km over France
- PEAROME : 16 non-hydrostatic forecasts nested in PEARP ;
 2,5 km over France ; EDA and stochastic physics
- ANTILOPE : data fusion between french radar observations and raingaujes ; 1 km grid over France
- Verification of QPF accumulated during 3 hours on the same grid (2,5 km) : from 01 october to 31 december 2019 over France



C C C C RANCE 2 CRPS for the 3 months period valid at D+1 18 UTC



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- Developpement of a neighborhood-based CRPS using the regional CDF.
- Deterministic limit of CRPS comparable to CRPS for the ensembles of forecasts.
- CRPSso => impact of enlarging the number of members by using neighboring points to improve the CDF at the central point.
- CRPSno => comparison of observed and forecast CDF at the scale of the neighborhood.
- A large part of the double penalty is absorbed by using an ensemble of forecasts versus a deterministic forecast.
- Stein and Stoop (2021) submitted to Monthly Weather Review



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 Unfair estimator (u) of CRPS are obtained by using biased estimator of the dispersion => CRPSuso, CRPSuno

$$E_{X,X'}(|X-X'|) = \frac{1}{Members^2} \sum_{m=1}^{Members} \sum_{n=1}^{Members} |X(m)-X'(n)|$$

 Fair estimator (f) of CRPS are obtained by using unbias estimator of the dispersion => CRPSfso, CRPSfno

$$E_{X,X'}(|X-X'|) = \frac{1}{Members(Members-1)} \sum_{m=1}^{Members} \sum_{n=1}^{Members} |X(m)-X'(n)|$$











