IMPROVER: the new probabilistic post processing system at the Met Office.

Nigel Roberts (previous Science Lead for IMPROVER)





## A new probabilistic post processing system called IMPROVER

Provide the Met Office with a single source of blended, probabilistic forecast information for the UK and globe.

## Why?

**Met Office** 

Modern world want here and now forecasts **To exploit frequently updated km-scale NWP models and ensembles** Current post processing needs updating

High resolution NWP needs different corrections Probabilistic framework for km-scale ensembles and multiple models A seamless forecast message from all forecasts Potential data overload





Errors and higher resolution ?



#### 1. The forecasts are not representative of particular locations

E.g. the temperature on a hill is not captured in model grid square

#### 2. The forecasts are biased.

E.g. consistently too much/too little rain or too high/too low temperatures

3. The weather of interest is in the wrong place (or wrong time or coverage) on the day

E.g. the shower is over Ostend not Bruges



### Met Office Need for post-processing high-resolution models





Not good for a forecast for a particular place and time - or verification scores – or automated outputs

### **IMPROVER**



Input forecasts from individual NWP models / ensembles / Inputs nowcast Initial user – Digital, Web pages, App (wider usefulness & interest). New variables Calculate new variables and Adjustments apply physical adjustments Create Convert to binary probabilities and combine members probabilities Apply spatial post processing Process methods and include older probabilities forecasts (time lag) Statistical Apply statistical post processing methods processing Blending Blend probabilities from different models models Spot forecasts Generate spot forecasts Output gridded and spot Outputs

7-day forecasts for now -> 14 days

Principles

- Single modular processing chain for each gridded variable
- Operate on the whole grid
- Probabilistic at the core
- Spot forecasts from gridded probabilities at the end (consistency)
- Objective verification at every stage for real time and trials
- Seamless from nowcast to medium range (multiple models / ensembles)
- Updating seamless blend as new forecasts come in

Roberts & Mittermaier 2016

Outputs

#### Inputs







Calculate new variables and apply physical adjustments

Convert to binary probabilities and combine members

Apply spatial post processing methods and include older

> Generate spot forecasts Output gridded and spot



**Radar extrapolation Nowcast** Out to 6 hours, every 15 minutes Run in IMPROVER MONOW/UKV suite - Caroline Sandford, Stephen Moseley



**MOGREPS-UK 2.2km** Out to 5 days, 3 forecasts every hour



**UKV 1.5km** Out to 12 hours, every hour

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MOGREPS-G~20km Out to 7 days, 18 forecasts every 6 hours

#### New variables, adjustments



- used to determine

whether showers Ben Ayliffe, Kat Hurst





Altitude adjustment then temperature adjustment (from Sheridan et al 2010) Ben Ayliffe

cloud





Continuous

Broken



Snow melting level - used for precipitation type probabilities Stephen Moseley

Methods applied to each forecast

### Create probabilities





#### **Process probabilities**







0.1 1 2 5 10 20 30 40 50 60 70 80 90 95 98 99 99.9 probability (%)

### Statistical processing





EMOS - temperature, wind - based on Gneiting et al 2005, Gavin Evans



Reliability Calibration - precipitation and cloud - Fiona Rust, Gavin Evans



Based on Flowerdew et al 2014 Tellus 72, 1-19

### **Blending models**









Probability of precipitation rate > 0.5 mm/hr (%)

#### Spot forecasts, gridded and spot outputs







LWE Thickness of Precipitation Amount 48 hr 95 Percentile Valid at 2100 UTC on Sun 27/06/2021 IMPROVER Multi-Model Blend Last Updated at 0515 UTC on Thu 24/06/2021





fog rain hail thunder clear cloud sleet snow

50th Percentile Day Time Maximum Temperature - Valid Local Time 2019-01-02 18:00:00



8 -16 -14 -12 -10 -8 -6 -4 -2 0 2 4 6 8 10 12 14 16 18 20 22 24 26 Air temperature (°C)





#### Machine learning at sites for temperature

Current (not IMPROVER) system – calibrate temperature for observed sites using a Kalman Filter and Neural Network (Simon Jackson)



BUT - calibration (KF+ML) at sites gives benefit at only a tiny fraction of locations

IMPROVER is meant to improve forecasts for <u>all</u> locations (where people are)

Can IMPROVER beat previous uncalibrated? Measure of improvement for nearly everyone. Yes.

Can IMPROVER match calibrated sites using its own site calibration / ML? Current project.

Can the site calibration / ML also be applied to the grid? To be seen.

"Not everything that counts can be counted, and not everything that can be counted counts" Probably William Bruce Cameron (not Albert Einstein)

Courtesy of Ben Ayliffe & Gavin Evans

# Site calibration

Comparing two approaches for calibrating temperature forecasts at sites.

#### **Ensemble Model Output Statistics**

• Calibrates full ensemble distribution.





#### **Neural Network**

In this study, focused on optimising the deterministic forecast.



# Site calibration

#### Example plot for daytime max in April 2020 Percentage within +/- 2 degrees



Multi-layer perceptron trained to estimate the error in the temperature forecast, with meteorological and geographical predictors/features) (simple by NN standards)

Rolling 30-day training (long dataset not available)

Use the Neural Net from the previous cycle as a starting point (i.e. a warm start) and a small number of iterations (epochs). Gradually evolves through the seasons.

Predictors: temperature, windspeed, difference in height between grid and spot location, distance to coast (by wind direction), lead-time

EMOS currently better than Neural Net

Potentially apply to grid with appropriate localisation / predictors

### Machine learning?





Phenomena classification Multi-variate relationships Emulation (new members) Calibration (non-probabilistic) Geographical relationships -> localisation Scenarios / clusters Downscaling

Emulation Optimise scaling (neighbourhoods)

Ensemble calibration

**Blending weights** 

Calibration Text, weather "symbols" Multi-variate relationships -> scenarios (clustering)

# Future?



Introduce 14-day global ensemble forecasts ECMWF / MOGREPS-G

Extend for high-impact thresholds (time windows & vicinity neighbourhoods)

More with calibration / ML

Common processing. Common Data Platform.

#### **IMPROVER** team

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Mark Baker, Anna Booton, Clare Bysouth, Rob Coulson, Ric Crocker, Caroline Jones, Jonathan Flowerdew, Roger Harbord, Aaron Hopkinson, Sean Coultas, Dan Brierley, Marion Mittermaier, Nigel Roberts, Tim Pillinger, Mark Worsfold, Victoria Smart